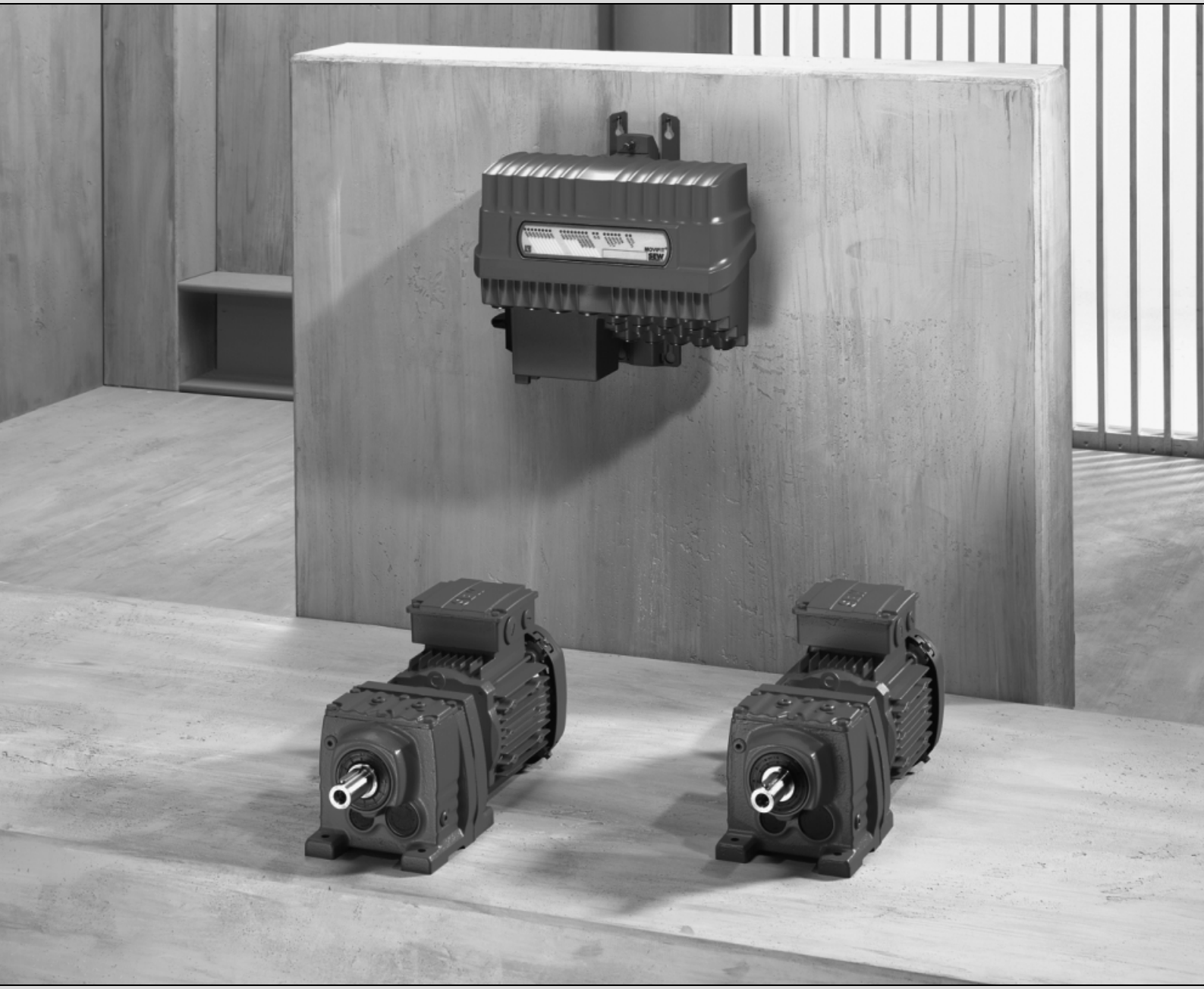
SEW EURODRIVE



MOVIFIT®-SC

Edition 10/2008
11662611 / EN

Operating Instructions

SEW EURODRIVE

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1 General Information

1.1 Use of operating instructions

The operating instructions are an integral part of the product and contain important information for operation and service. The operating instructions are written for all employees who assemble, install, start up, and service this product.

The operating instructions must be kept available in a legible condition. Ensure that persons responsible for the system and its operation, as well as persons who work independently on the unit, have read through the operating instructions completely and understood them. If you are unclear about any of the information in this documentation or require further information, please contact SEW-EURODRIVE.

1.2 Structure of the safety notes

The safety notes in these operating instructions are structured as follows:

Symbol	SIGNAL WORD
	Nature and source of danger. Possible consequence(s) if disregarded. • Measure(s) to avoid the danger.

Symbol	Signal word	Meaning	Consequences if disregarded
Example: General danger Specific danger, e.g. electric shock	**DANGER**	Imminent danger	Severe or fatal injuries
	WARNING	Possible dangerous situation	Severe or fatal injuries
	CAUTION	Possible dangerous situation	Minor injuries
	NOTICE	Possible damage to property	Damage to the drive system or its environment
	TIP	Useful information or tip Simplifies handling of the drive system	

1.3 Rights to claim under warranty

Adhering to the operating instructions is a prerequisite for fault-free operation and the fulfillment of any right to claim under warranty. You should therefore read the operating instructions before you start working with the unit.

Make sure that the operating instructions are available to persons responsible for the plant and its operation as well as to persons who work independently on the unit. You must also ensure that the documentation is legible.

1.4 Exclusion of liability

You must comply with the information contained in these operating instructions to ensure safe operation of MOVIFIT®-SC and to achieve the specified product characteristics and performance features. SEW-EURODRIVE assumes no liability for injury to persons or damage to equipment or property resulting from non-observance of these operating instructions. In such cases, any liability for defects is excluded.

1.5 Copyright

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Copyright law prohibits the unauthorized reproduction, modification, distribution, and use of this instruction manual, in whole or in part.

2 Safety Notes

The following basic safety notes are intended to prevent injury to persons and damage to property. The operator must ensure that the basic safety notes are observed and complied with. Ensure that persons responsible for the system and its operation as well as persons who work independently on the unit have read through the operating instructions carefully and understood them. If you are unclear about any of the information in this documentation or if you require further information, please contact SEW-EURODRIVE.

2.1 General information

Never install or start up damaged products. In the event of damage, submit a complaint to the shipping company immediately.

During operation, MOVIFIT®-SC may have live, uninsulated, and sometimes moving or rotating parts as well as hot surfaces corresponding to its relevant degree of protection.

The unauthorized removal of covers, improper use, incorrect installation or improper operation may result in severe injuries to persons or damage to property.

Consult the documentation for further information.

2.2 Target group

Only **qualified electricians** may perform installation, startup, fault repair and servicing work (observe IEC 60364 and CENELEC HD 384 or DIN VDE 0100 and IEC 60664 or DIN VDE 0110 as well as national accident prevention regulations).

In the context of these basic safety notes, qualified electricians are persons familiar with the installation, assembly, startup, and operation of the product and who possess the qualifications to perform the tasks required of them.

All activity in the other areas of transportation, storage, operation, and disposal must be carried out by persons who are appropriately trained.

2.3 Designated use

MOVIFIT®-SC is a component intended for installation in electrical systems or machines.

When installed in machines, startup of the MOVIFIT®-SC (i.e. start of designated use) is prohibited until it is determined that the machine meets the requirements stipulated in EC directive 98/37/EC (Machine directive).

Startup (i.e. the start of designated use) is only permitted under observance of the EMC directive (2004/108/EC).

MOVIFIT®-SC meets the requirements stipulated in the low-voltage directive 2006/95/EC. The standards contained in the declaration of conformity are used for MOVIFIT®-SC.

Technical data and information on the connection requirements are provided on the nameplate and in the documentation; these must be observed under all circumstances.

2.3.1 Safety functions

MOVIFIT®-SC may not perform any safety functions unless they are described and expressly approved.

Use only components in safety applications that were explicitly designed and supplied for this purpose by SEW-EURODRIVE.

2.4 Other applicable documentation

In addition, note the following publication:

- "DR/DV/DT/DTE/DVE AC Motors, CT/CV Asynchronous Servomotors" operating instructions
- "AC Motors DRS/DRE/DRP" operating instructions

2.5 Transportation and storage

Observe the notes on transportation, storage and proper handling. Observe the climatic conditions as stated in the "Technical Data" sections.

2.6 Installation

The units must be installed and cooled according to the regulations in the relevant documentation.

Protect MOVIFIT®-SC from excessive strain.

The following applications are prohibited unless the unit is explicitly designed for such use:

- Use in potentially explosive areas.
- Use in areas exposed to harmful oils, acids, gases, vapors, dust, radiation, etc.
- Use in non-stationary applications with strong mechanical oscillation and impact loads; see section "Technical Data".

2.7 Electrical connection

Observe applicable national accident prevention guidelines when working on live MOVIFIT®-SC (e.g. BGV A3).

Electrical installation must be carried out according to pertinent regulations (e.g. line cross sections, fusing, and protective earth connection). The documentation contains additional information.

You will find notes on EMC-compliant installation (e.g., shielding, grounding, arrangement of filters and routing of lines) in the MOVIFIT®-SC documentation. The manufacturer of the system or machine is responsible for observing the limits established by EMC legislation.

Protective measures and protection devices must comply with the regulations in force (e.g. EN 60204 or EN 61800-5-1).

2.8 Safe disconnection

MOVIFIT®-SC meets all requirements for safe disconnection of power and electronic connections in accordance with EN 61800-5-1. All connected circuits must also satisfy the requirements for safe disconnection.

2.9 Operation

Systems into which MOVIFIT®-SC is installed must be equipped with additional monitoring and protection devices, if necessary, according to the applicable safety regulations; e.g., the law governing technical equipment, accident prevention regulations, etc. Additional protective measures may be necessary for applications with increased potential risk. Changes to the MOVIFIT®-SC using the software are permitted.

Do not touch live components or power connections immediately after disconnecting the MOVIFIT®-SC from the supply voltage because there may still be some charged capacitors. Wait for at least 1 minute after having switched off the supply voltage.

As soon as supply voltage is present at the MOVIFIT®-SC, the terminal box must be closed (i.e., the MOVIFIT®-EBOX and any hybrid cable connector must be connected and screwed on).

The EBOX of the MOVIFIT®-SC and any power plug connectors must never be disconnected during operation. Doing so can lead to dangerous electric arcs forming, which can cause irreparable damage to the unit (fire risk, irreparable contacts).

Important: The MOVIFIT® maintenance switch only disconnects the integrated motor switch from the mains. The terminals of the MOVIFIT®-SC are still connected to the mains voltage after the maintenance switch is activated.

The unit may still be live and connected to the mains, even if the operation LEDs and other display elements are no longer illuminated.

Mechanical blocking or the unit's internal safety functions can cause a motor standstill. Eliminating the cause of the problem or performing a reset can result in the drive restarting automatically. If, for safety reasons, this is not permitted for the driven machine, disconnect the unit from the mains before correcting the fault.

Caution – Danger of burns: The MOVIFIT®-SC surface temperature can exceed 60°C during operation.

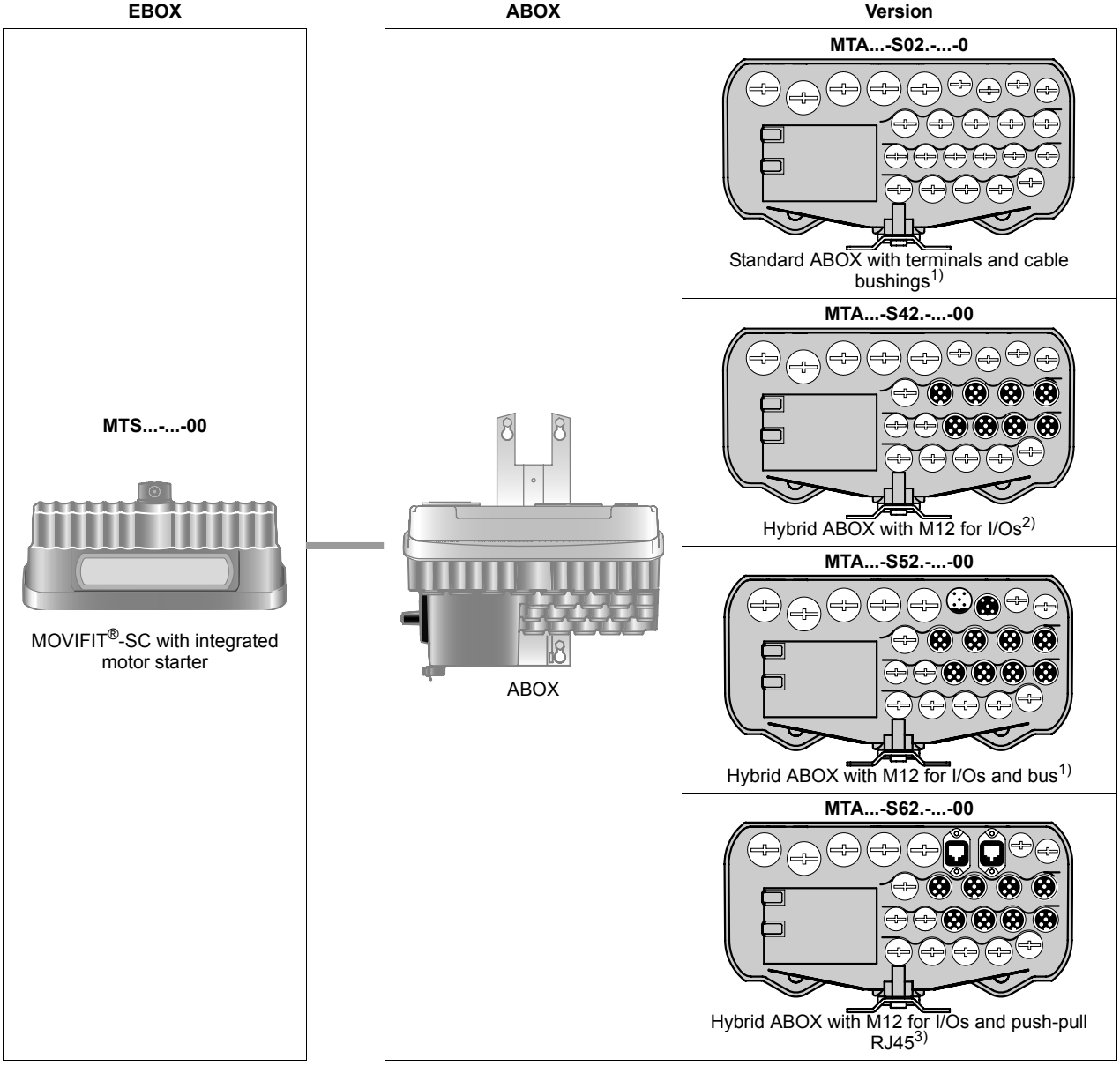
Do not connect terminals X9 and X91 in "single-motor" operating mode.

3 Unit Design

3.1 Overview

3.1.1 Combinations in connection with standard ABOX and hybrid ABOX

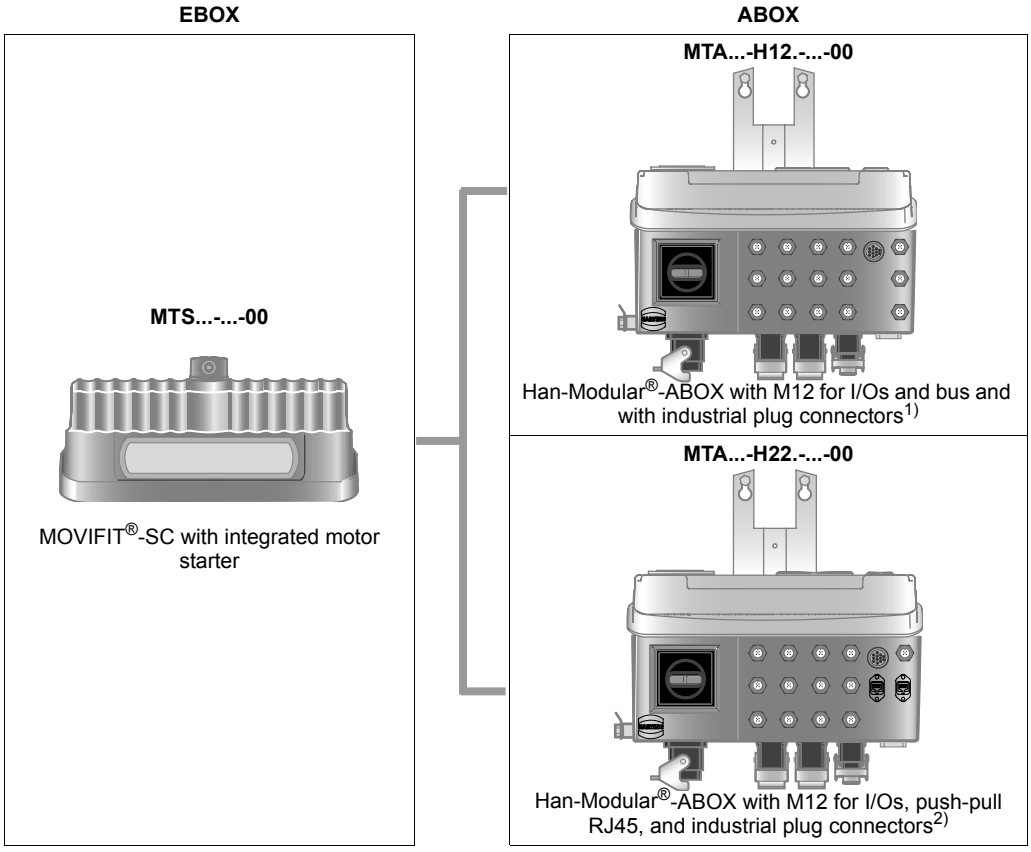
The following figure shows the MOVIFIT® versions described in this instruction manual with the standard ABOX and the hybrid ABOX.



1) With DeviceNet: Micro-style connector for DeviceNet connection
2) Not available with DeviceNet
3) Not available with DeviceNet and PROFIBUS

3.1.2 Combinations in connection with Han-Modular®-ABOX

The figure that follows shows the MOVIFIT® versions described in these operating instructions with the Han-Modular®-ABOX.


EBOX
ABOX
MTS...-...-00
MOVIFIT®-SC with integrated motor starter
MTA...-H12.-...-00
Han-Modular®-ABOX with M12 for I/Os and bus and with industrial plug connectors1)
MTA...-H22.-...-00
Han-Modular®-ABOX with M12 for I/Os, push-pull RJ45, and industrial plug connectors2)

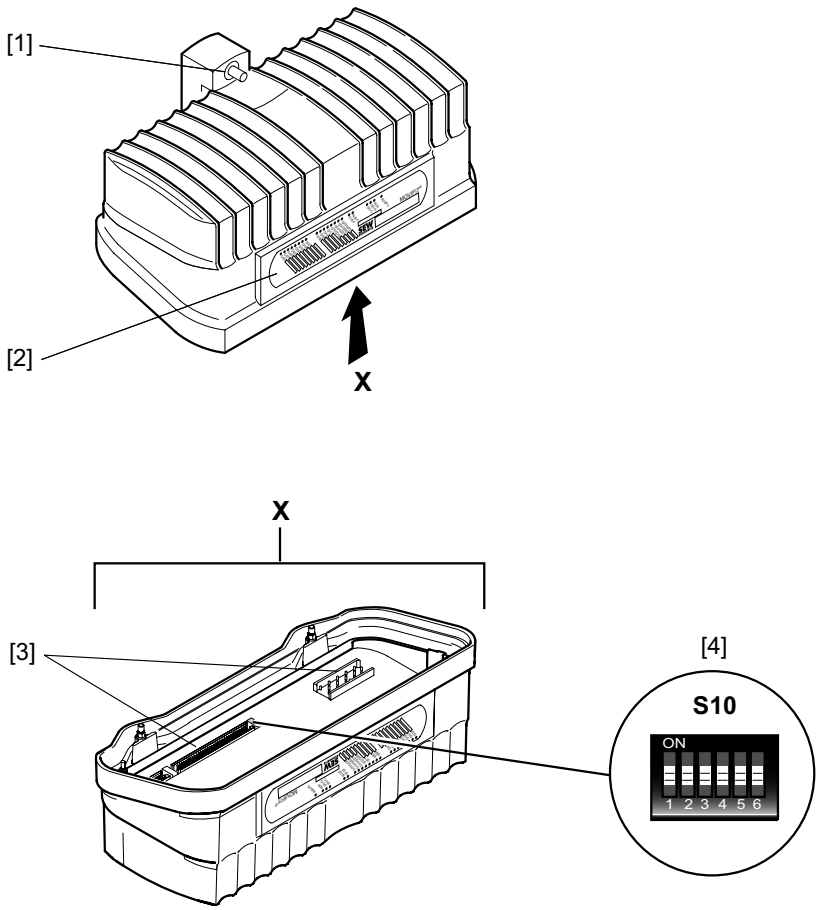
1) With DeviceNet: micro-style connector for DeviceNet connection

2) Not available with DeviceNet and PROFIBUS

3.2 EBOX (active electronics unit)

The MOVIFIT®-SC EBOX is a closed electronics unit with communication interface, I/Os, and motor starter:

EBOX "MTS...-....-00"



848535563

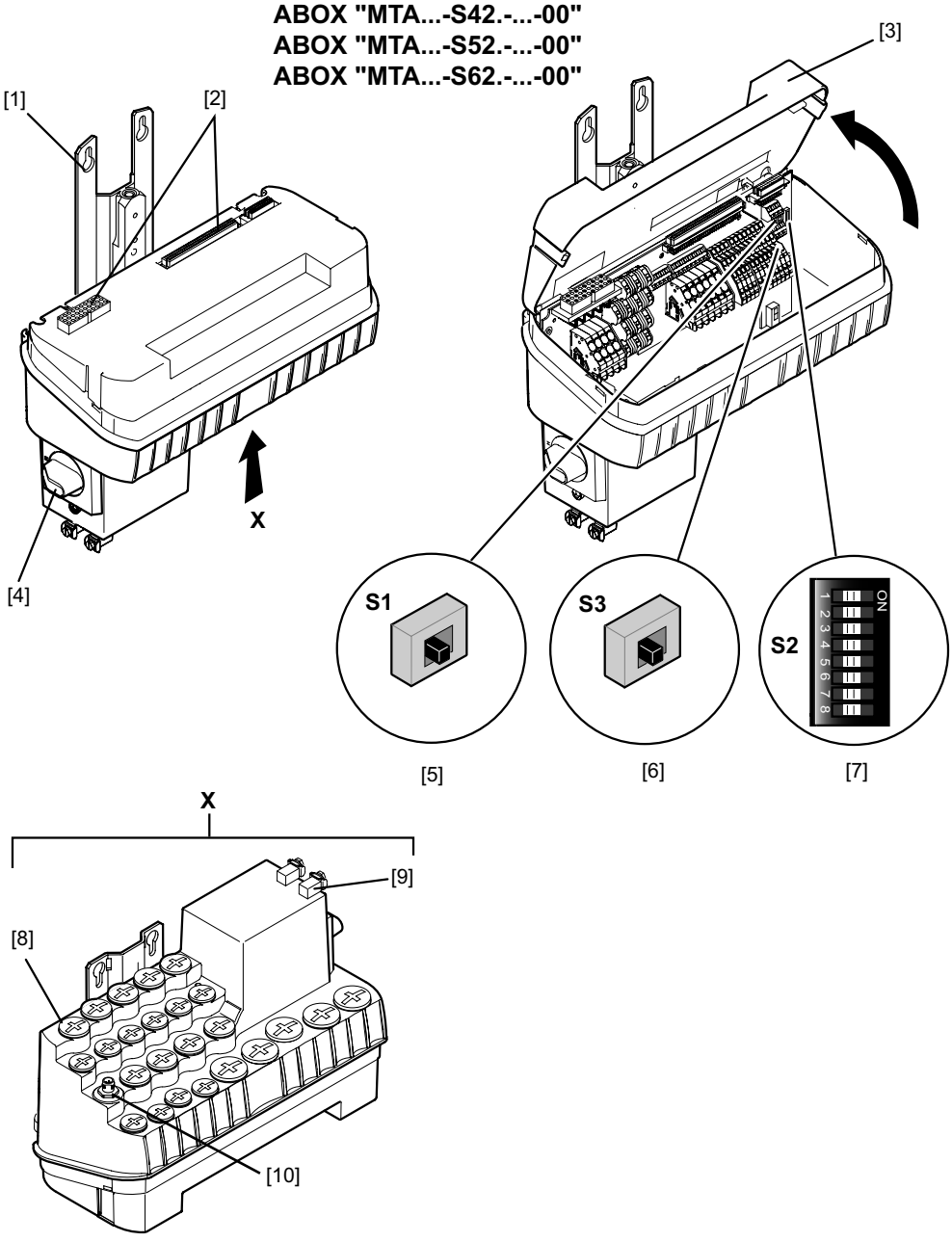
[1] Central opening/closing mechanism
[2] Operation LEDs for I/Os (can be labeled), communication, and unit status
[3] Connection to connection box
[4] DIP switch S10 for unit functions

3.3 ABOX (passive connection unit)

3.3.1 Standard ABOX and hybrid ABOX

The following figure gives an example of the MOVIFIT® standard ABOX/MOVIFIT® hybrid ABOX:

ABOX "MTA...-S02.-...-00"
ABOX "MTA...-S42.-...-00"
ABOX "MTA...-S52.-...-00"
ABOX "MTA...-S62.-...-00"



812524427

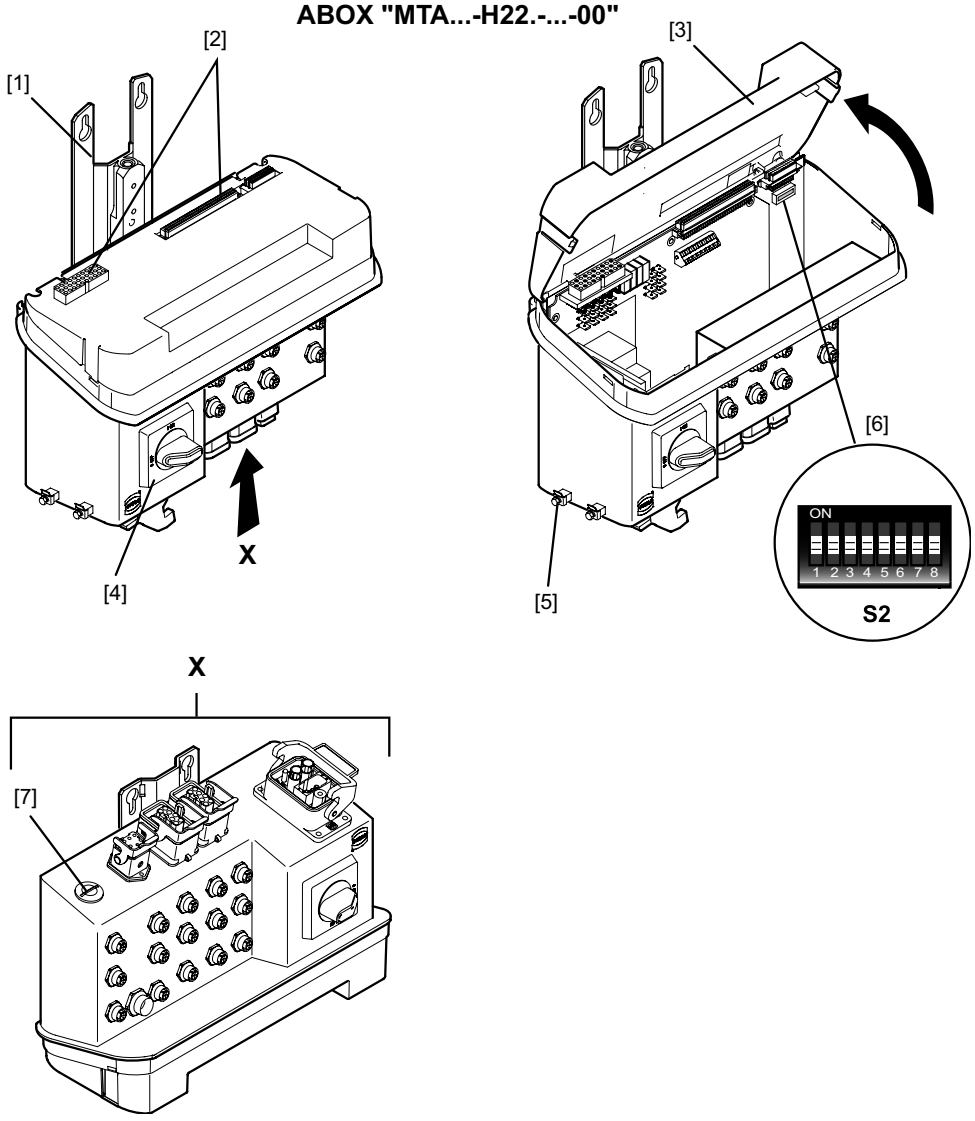
[1] Mounting rail
[2] Connection to EBOX
[3] Protection cover
[4] Maintenance switch
[5] DIP switch S1 for bus termination (PROFIBUS version only)
[6] DIP switches S3 for bus termination SBus
[7] DIP switch S2 for bus address (PROFIBUS and DeviceNet version only)
[8] Diagnostic interface below screw connection
[9] Grounding screws
[10] Micro-style connector (DeviceNet version only)

3.3.2 Han-Modular®-ABOX

The following figure depicts the Han-Modular® connection box with Han-Modular® and M12 plug connector:

	TIP
	The figure below shows an example of the connection technology of the PROFIBUS version. For detailed information on other variants, refer to section "Electrical Installation".

ABOX "MTA...-H12.-...-00"
ABOX "MTA...-H22.-...-00"



812501131

[1] Mounting rail
[2] Connection to EBOX
[3] Protection cover
[4] Maintenance switch
[5] Grounding screws
[6] DIP switch S2 for bus address (PROFIBUS and DeviceNet version only)
[7] Diagnostic interface below screw connection

3.4 Hygienic^{plus} version (optional)

3.4.1 Properties

The Hygienic^{plus} version has the following characteristics:

- IP66 in accordance with EN 60529 and IP69K in accordance with DIN 40050-9 (MOVIFIT® housing closed and all cable bushings sealed according to the relevant degree of protection)
- Easy-to-clean housing (self-draining design)
- Surface with anti-adhering properties
- High impact resistance of the surface against mechanical damage
- Compatibility with cleaning agents having the following properties:
  - Alkaline
  - Acidic
  - Disinfectant

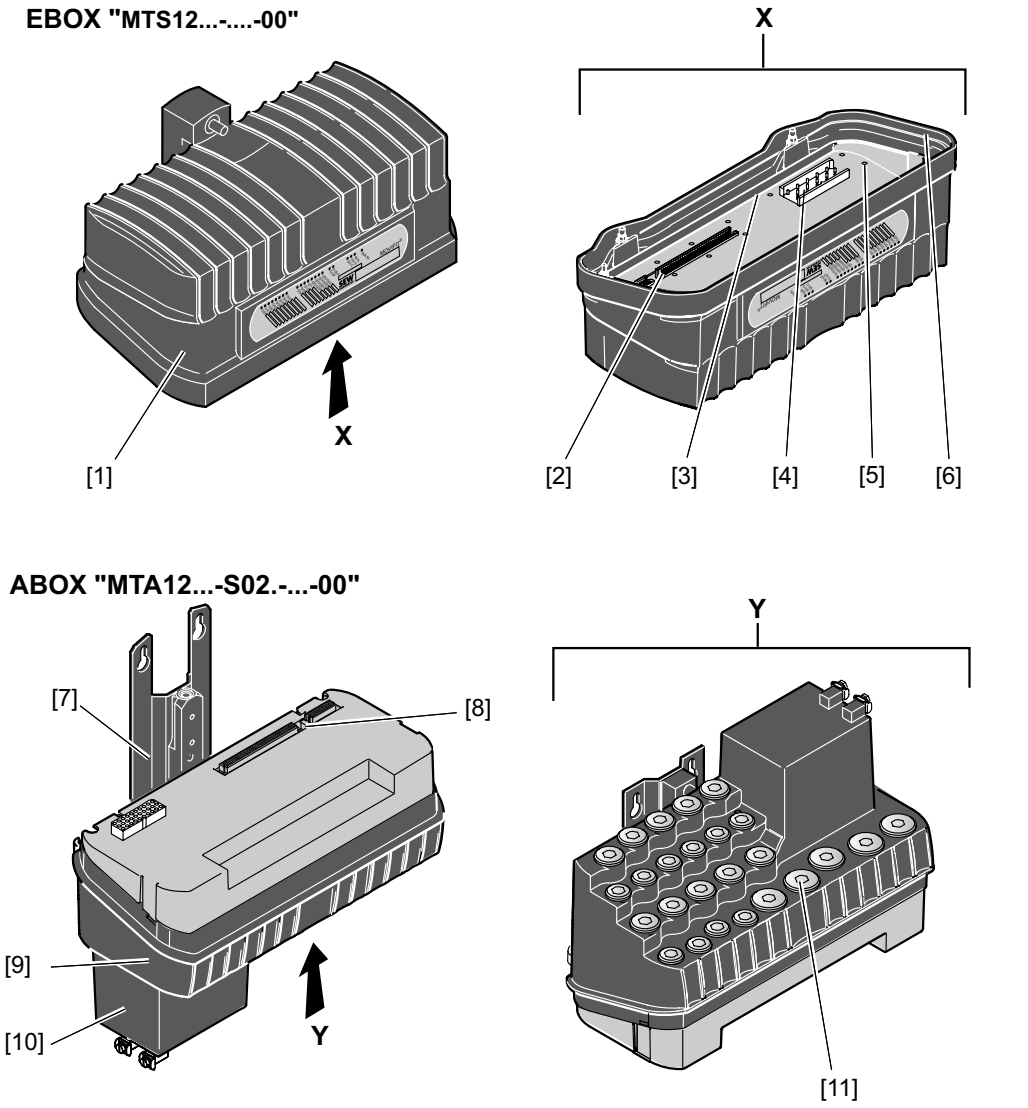
  Never mix cleaning and disinfecting agents.

  Never mix acids and chlorine alkalis, as poisonous chlorine gas will result.

  Strictly observe the safety instructions of the cleaning agent manufacturer.
- Resistant to temperature fluctuations
- Not sensitive to condensation due to connection boards with a special surface treatment

	TIPS
	The Hygienic^{plus} design is only available in connection with the standard ABOX, "MTA12...-S02.-...-00". For additional features of the Hygienic^{plus} version, refer to section "Technical Data".

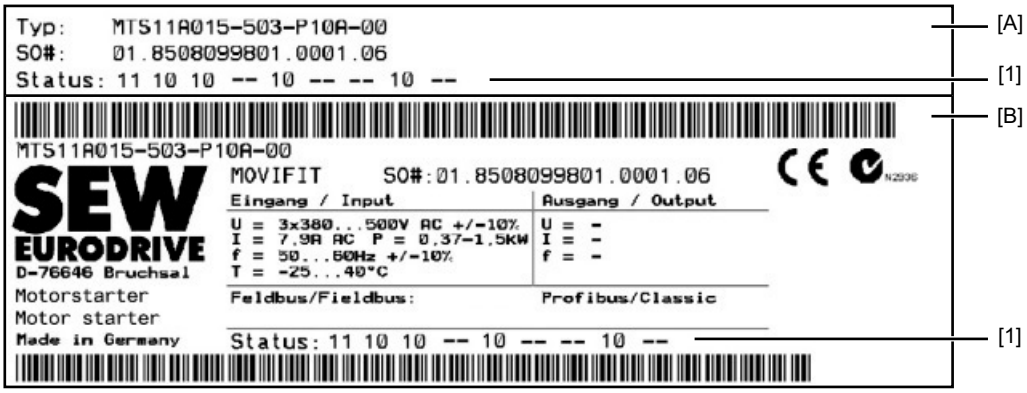
The following figure depicts the additional features of MOVIFIT® units in the optional Hygienic^{plus} version:



[1] EBOX with special surface treatment (only available in one color)
[2] Signal plug connector with gasket
[3] Gasket between ABOX and coverplate
[4] Power plug connector with gasket
[5] Screws with thread sealant
[6] Replaceable profile gasket
[7] Mounting rail with special surface treatment (only available in one color)
[8] Connection board with high resistance to condensation (special surface treatment)
[9] ABOX with special surface treatment (only available in one color)
[10] With the Hygienic^{plus} version: generally without maintenance switch
[11] Stainless steel screw plugs(available as an option)

3.5 Unit designation MOVIFIT®-SC

3.5.1 Sample EBOX nameplate



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[A] External nameplate
[B] Internal nameplate
[1] EBOX status field

MT S 11 A 015- 50 3 - P1 0 A - 00

EBOX version
00 = Series

A = Version

Function level
0 = Classic
1 = Technology
2 = System

Fieldbus
P1 = PROFIBUS
D1 = DeviceNet
E2 = PROFINET
E3 = EtherNet/IP, Modbus/TCP
Z1 = SBus slave

Connection type
3 = 3-phase

Connection voltage
50 = AC 380-500 V

Unit power
015 = 1.5 kW
040 = 4.0 kW

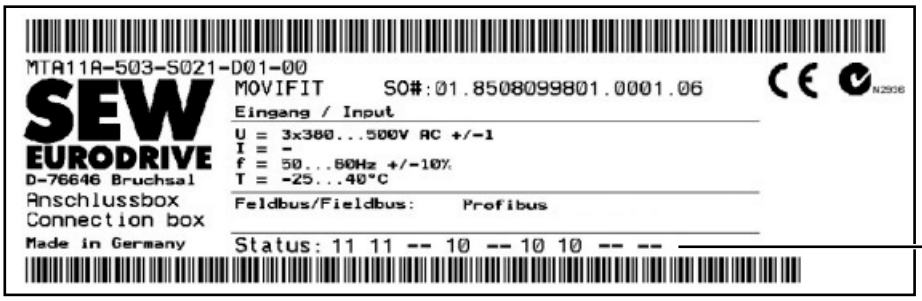
Version A

Series
11 = Standard
12 = Hygienic^{plus} version

Unit type
S = MOVIFIT®-SC (motor starter)

MT = MOVIFIT® unit series

3.5.2 Sample ABOX nameplate



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[1] ABOX status field

MT A 11 A - 50 3 -S02 1 - D 01 - 00 / M11

ABOX option
M11 = Stainless steel mounting rail

ABOX version
00 = Series

Maintenance switch type
01 = With rotary button (ABB)

Maintenance switch version
D = Switch disconnector

Fieldbus
1 = PROFIBUS
2 = DeviceNet
3 = EtherNet/IP, PROFINET, Modbus/TCP

Connection configuration
S02 = Standard ABOX with terminals and cable bushings
S42 = Hybrid ABOX with M12 for I/Os
S52 = Hybrid ABOX with M12 for I/Os + bus
S62 = Hybrid ABOX with M12 for I/Os and push-pull RJ45 for bus
H12 = Han-Modular®-ABOX with M12 for I/Os + bus and industrial plug connectors
H22 = Han-Modular®-ABOX with M12 for I/O, push-pull RJ45, and industrial plug connectors

Connection type
3 = 3-phase (AC)

Connection voltage
50 = 380-500 V

A = Version

Series
11 = Standard
12 = Hygienic^{plus} version

Unit type
A = Connection box

MT = MOVIFIT® unit series

4 Mechanical Installation

4.1 Installation instructions

- Mount MOVIFIT® only on a level, vibration-proof and torsionally rigid support structure, as described in the section "Approved installation position".
- Use suitable cable glands (use reducing adapters if necessary). For versions with plug connectors, make sure to use the matching mating connectors.
- Use screw plugs to seal cable entries not in use.
- Use protective caps to seal plug connectors not in use.

⚠ CAUTION

Risk of injury due to protruding parts, especially the mounting rail.

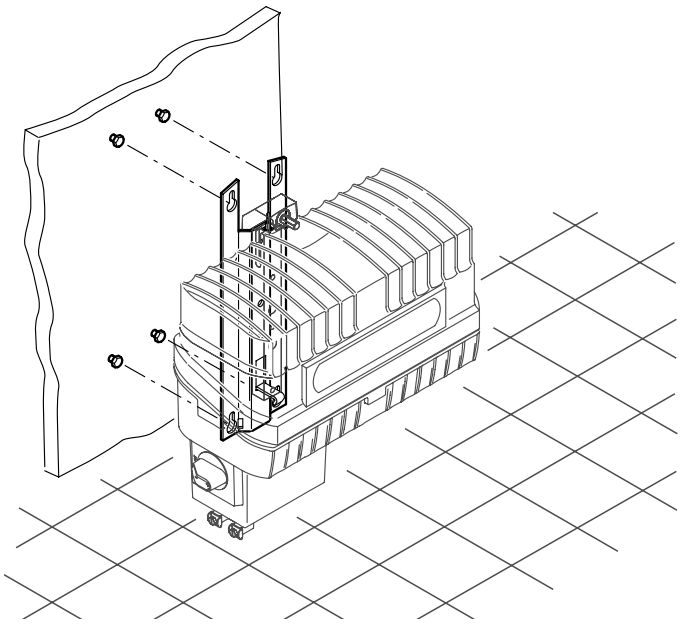
Risk of cutting or crushing.

- Cover sharp and protruding parts, especially the mounting rail, to protect against injury and damage.
- Make sure that only trained specialists carry out the installation.

4.2 Approved installation position

The following figure depicts the approved installation position for MOVIFIT®.

MOVIFIT® is attached by means of a mounting plate using the four screws already installed in the mounting surface. For further information, refer to section "Assembly instructions" (see page 21).



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TIP

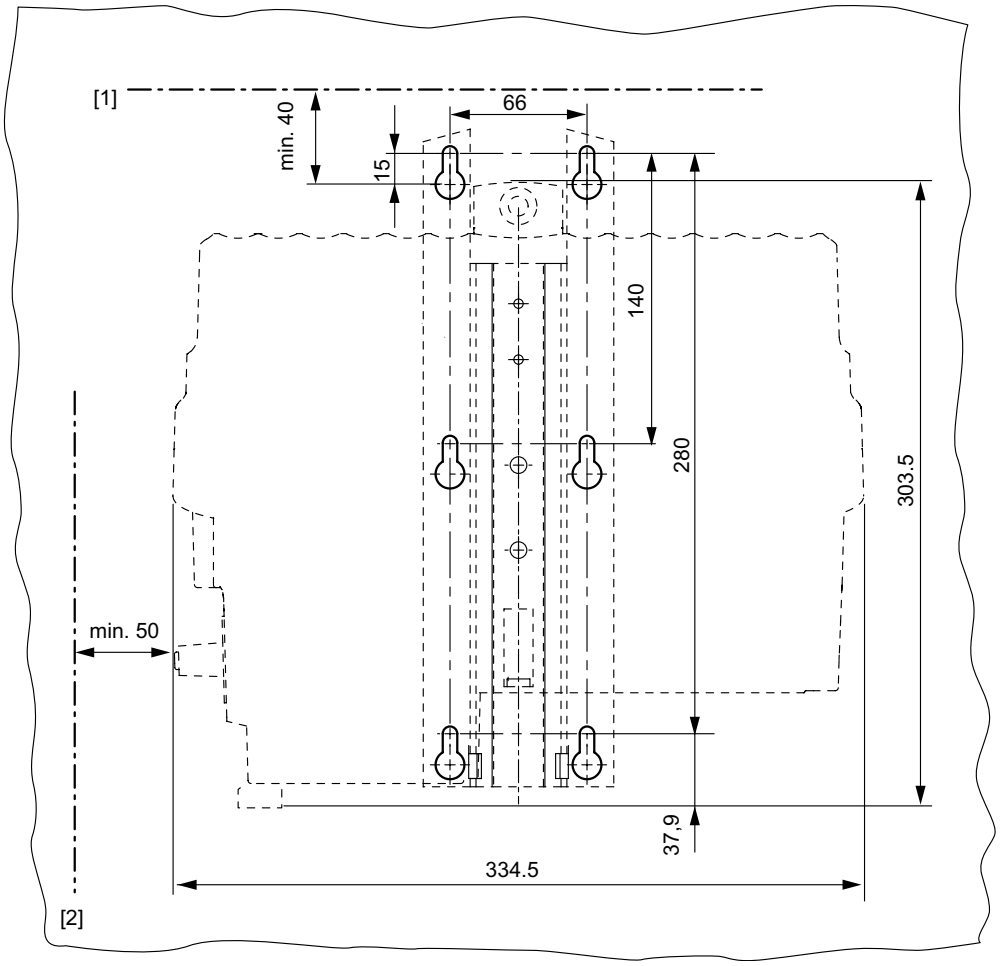
This section uses the version with terminals and cable bushings as an example. However, the assembly instructions are applicable for all versions.

4.3 Assembly instructions

1. Drill the holes necessary to secure at least four screws to the mounting surface as shown in the following figure. SEW-EURODRIVE recommends using screw size M6 and, depending on the base, suitable dowel pins, if necessary.

   Size 1

   In conjunction with a standard mounting rail:

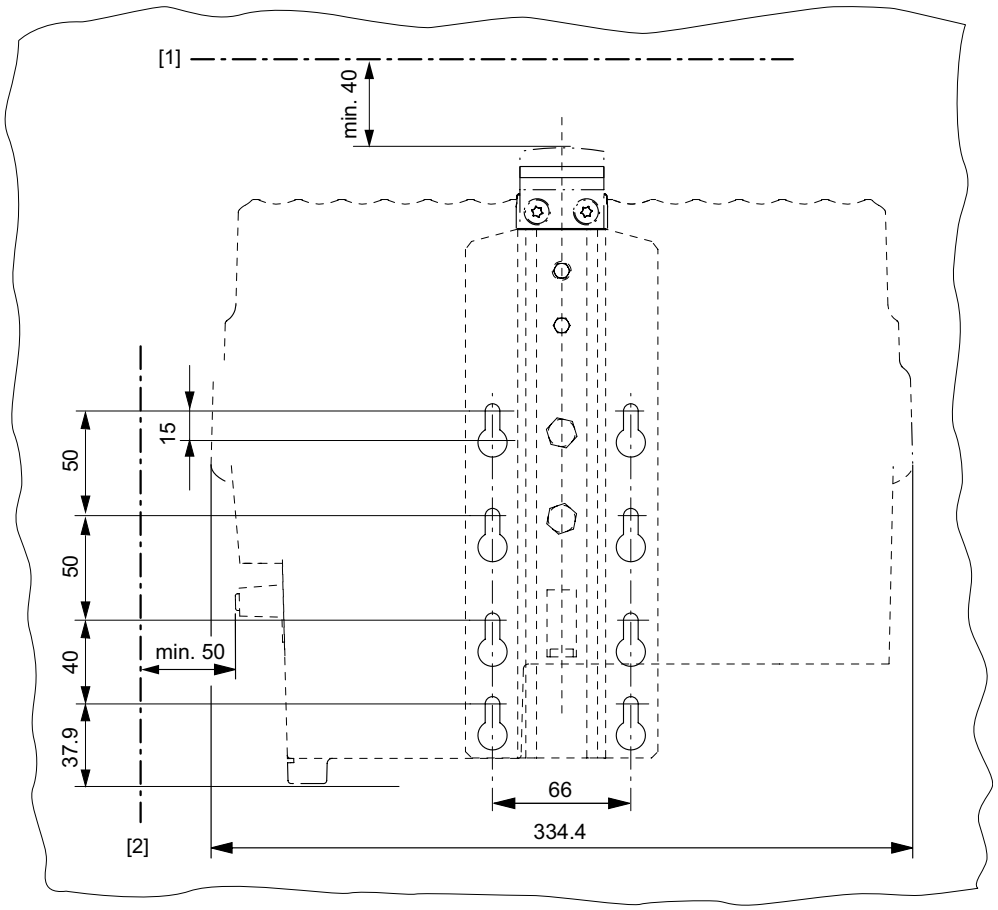


758540299

	TIPS
	• [1] Observe the minimum installation clearance so that the EBOX can be removed from the ABOX. • [2] Observe the minimum installation clearance required to operate the maintenance switch and to ensure heat dissipation for the unit. For detailed dimension drawings, see the section "Dimension drawings" (see page 135).

Size 1

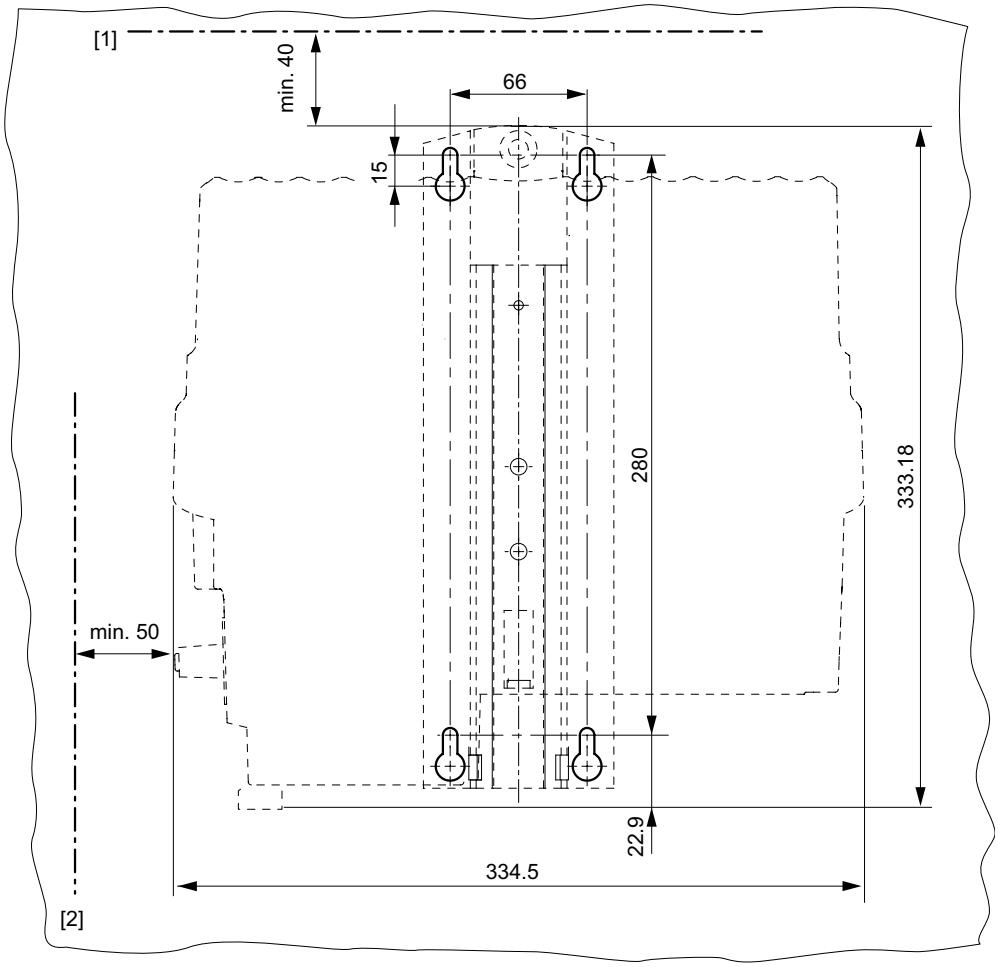
In conjunction with the optional M11 stainless steel mounting rail:



799309835

	TIPS
	• [1] Observe the minimum installation clearance so that the EBOX can be removed from the ABOX. • [2] Observe the minimum installation clearance required to operate the maintenance switch and to ensure heat dissipation for the unit. For detailed dimension drawings, see the section "Dimension drawings" (see page 135).

Size 2:

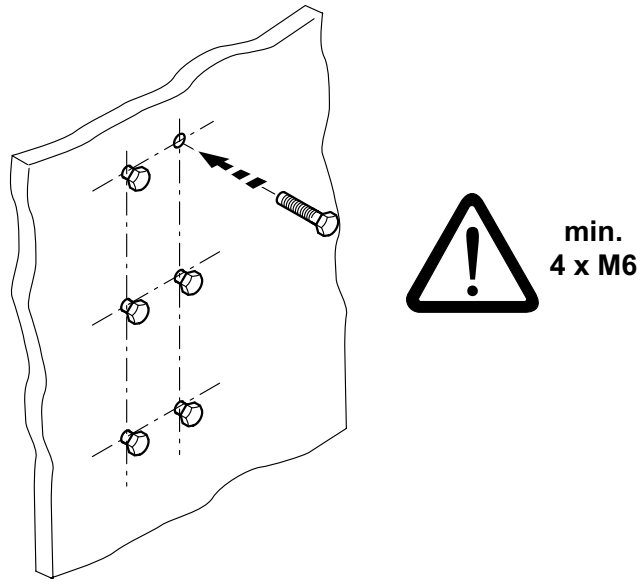


812584331

	TIPS
	• [1] Observe the minimum installation clearance so that the EBOX can be removed from the ABOX. • [2] Observe the minimum installation clearance required to operate the maintenance switch and to ensure heat dissipation for the unit. For detailed dimension drawings, see the section "Dimension drawings" (see page 135).

2. Mount at least 4 screws on the mounting surface. SEW-EURODRIVE recommends using screw size M6 and, depending on the base, dowel pins, if necessary.

   Use appropriate washers or screw and washer assemblies for the mounting plates with special surface treatment on the Hygienic^{plus} version.



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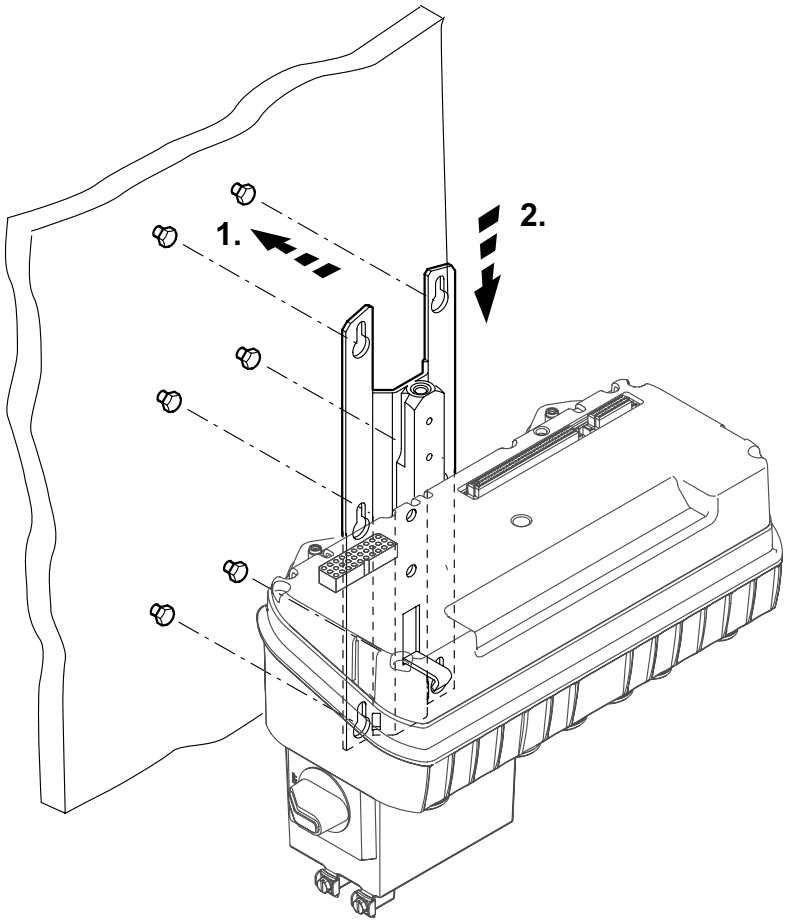
3. Attach the ABOX to the screws using the mounting plate.



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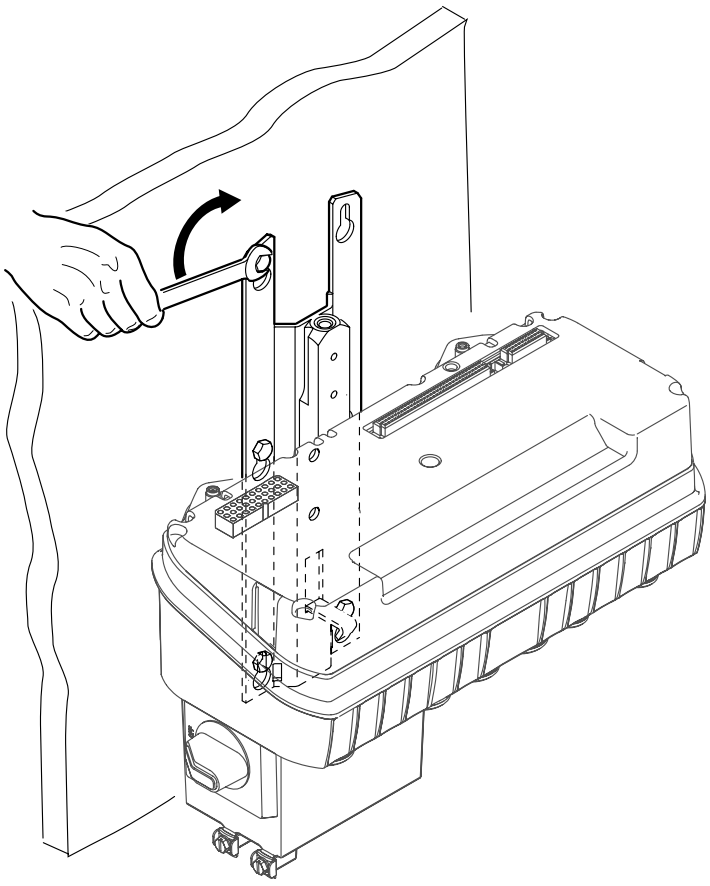
4. Tighten the screws.

	⚠ CAUTION
	Danger due to falling load Minor injuries • You will have to tighten at least 4 wall screws to ensure a secure fit after mounting.



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4.4 Central opening/closing mechanism

⚠ WARNING

The surface temperature of the MOVIFIT®-SC can be very high during operation.

Danger of burns

- Do not touch MOVIFIT®-SC until it has cooled down sufficiently.

NOTICE

If the torque is too high, the central opening/closing mechanism can be destroyed.

- Tighten the retaining screw up to the stop using a tightening torque of 7 Nm (60 lb.in).

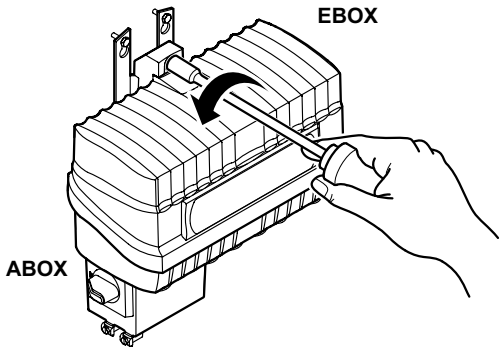
The degree of protection specified in the technical data only applies when a unit is mounted correctly. When the EBOX is removed from the ABOX, moisture, dust, or foreign particles can damage the MOVIFIT®.

- Protect the ABOX and EBOX when the unit is open.

4.4.1 Opening the unit

A socket wrench (SW8) is required for the central retaining screw.

1. Loosen the central retaining screw and continue to turn it counterclockwise until the EBOX stops moving further up.



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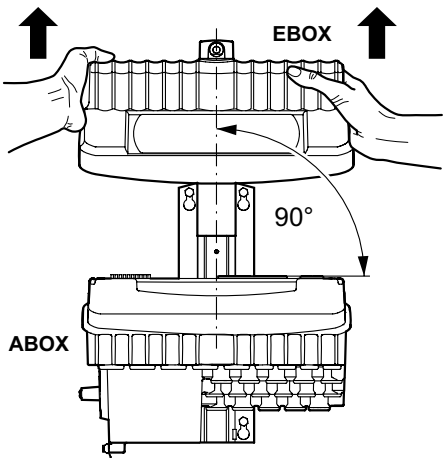
2. Remove the EBOX from the ABOX by lifting it upwards. Do not twist the EBOX.

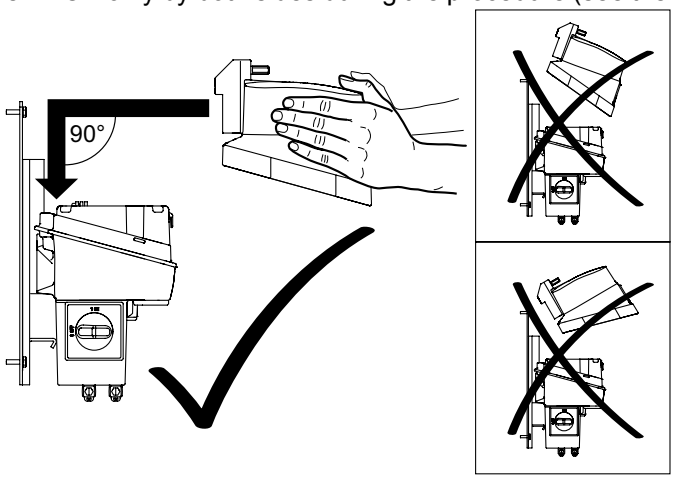


813353099

4.4.2 Closing the unit

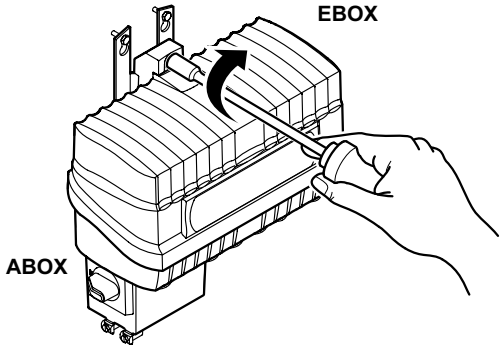
A socket wrench (SW8) is required for the central retaining screw.

1. Position the EBOX on the ABOX.
   - Do not twist the EBOX.
   - Hold the EBOX only by both sides during the procedure (see the following figure).



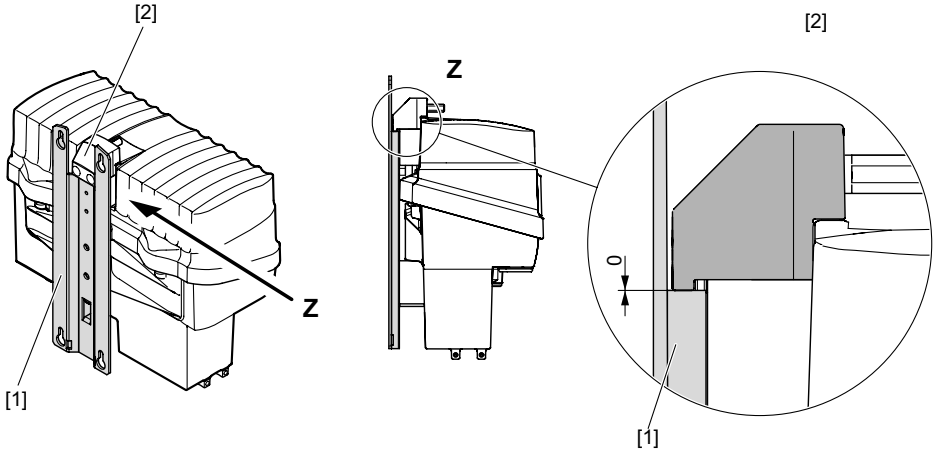
813362059

2. Tighten the retaining screw up to the stop using a tightening torque of 7 Nm (60 lb.in).



813384075

3. MOVIFIT® is closed correctly when the redirector of the closing mechanism [2] is on the mounting plate [1].

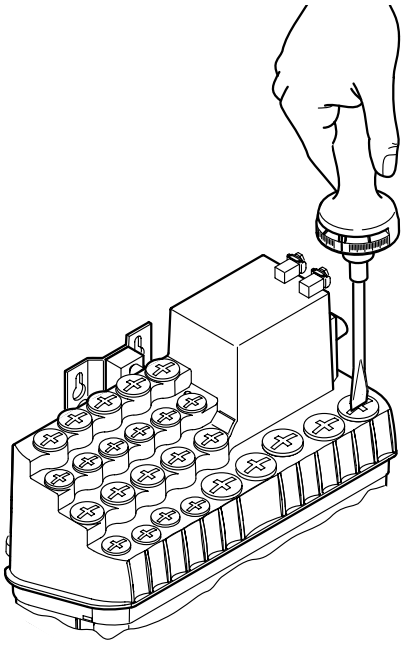


813392395

4.5 Tightening torques

4.5.1 Blanking plugs

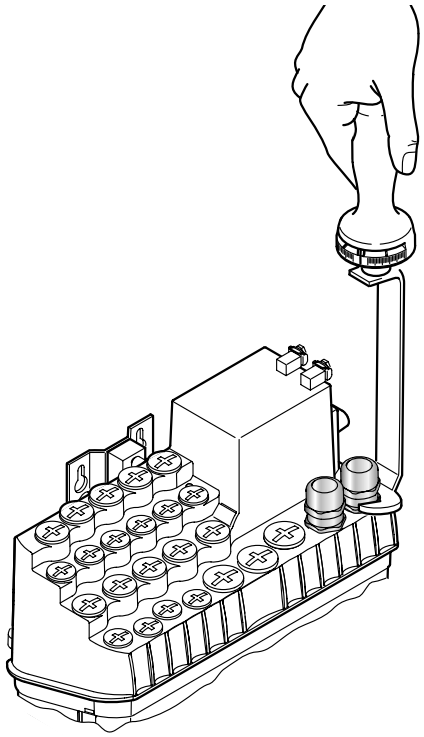
Tighten the blanking plugs optionally supplied by SEW-EURODRIVE using a tightening torque of 2.5 Nm (22 lb.in):



758614667

4.5.2 EMC cable glands

Tighten the EMC cable glands optionally supplied by SEW-EURODRIVE to the following torques:



758624523

Screw connection	Part number	Size	Tightening torque
EMC cable glands (nickel-plated brass)	1820 478 3	M16 x 1.5	3.5 Nm to 4.5 Nm (31-40 lb.in)
	1820 479 1	M20 x 1.5	5.0 Nm to 6.5 Nm (44-57 lb.in)
	1820 480 5	M25 x 1.5	6.0 Nm to 7.5 Nm (53-66 lb.in)
EMC cable glands (stainless steel)	1821 636 6	M16 x 1.5	3.5 Nm to 4.5 Nm (31-40 lb.in)
	1821 637 4	M20 x 1.5	5.0 Nm to 6.5 Nm (44-57 lb.in)
	1821 638 2	M25 x 1.5	6.0 Nm to 7.5 Nm (53-66 lb.in)

The cable retainer in the cable gland must withstand the withdrawal force of the cable from the cable gland as follows:

- Cable with outer diameter > 10 mm: ≥ 160 N
- Cable with outer diameter < 10 mm: = 100 N

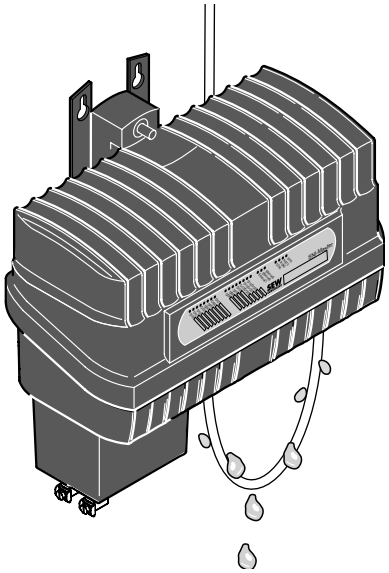
4.6 MOVIFIT® Hygienic^{plus} version

	TIPS
	SEW-EURODRIVE guarantees that the Hygienic^{plus} special surface treatment is free from faults when delivered. Report any damage that has occurred during transport immediately. Although the special surface treatment has a high impact resistance, the housing surfaces are to be handled with care. The corrosion protection can be affected by damage to the special surface treatment resulting from improper handling during transport, installation, operation, cleaning, etc. SEW-EURODRIVE is not liable for such damage.

4.6.1 Installation notes

Observe the following additional notes when installing the MOVIFIT®-SC Hygienic^{plus} version:

- Make sure to prevent moisture and dirt from entering the unit during the installation.
- After electrical installation and during assembly, make sure all gaskets and sealing surfaces are clean and undamaged.
- Check the state of the profile gasket in the EBOX when performing maintenance work. If damaged: Consult SEW-EURODRIVE.
- Degree of protection IP69K is achieved only if the plastic screw plugs delivered as standard are replaced by suitable IP69K screw connections and the approved mounting position is observed (see page 20).
- Make sure to install the cable with a drip loop; see the following figure:



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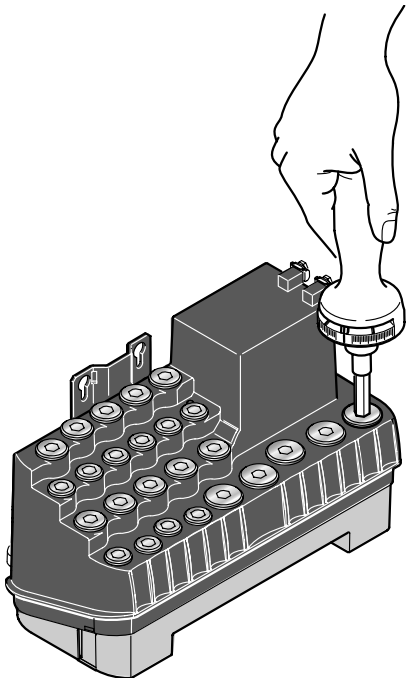
4.6.2 Tightening torques for Hygienic^{plus} version

	NOTICE
	The IP69K degree of protection is achieved only if the plastic screw plugs delivered as standard are replaced by suitable IP69K screw connections. Refer to section "Optional metal screw connections" (see page 134) for screw connections available at SEW-EURODRIVE. Only the listed stainless steel screw connections are suitable for IP69K.

Blanking plugs Tighten the blanking plugs optionally supplied by SEW-EURODRIVE to 2.5 Nm (22 lb.in).



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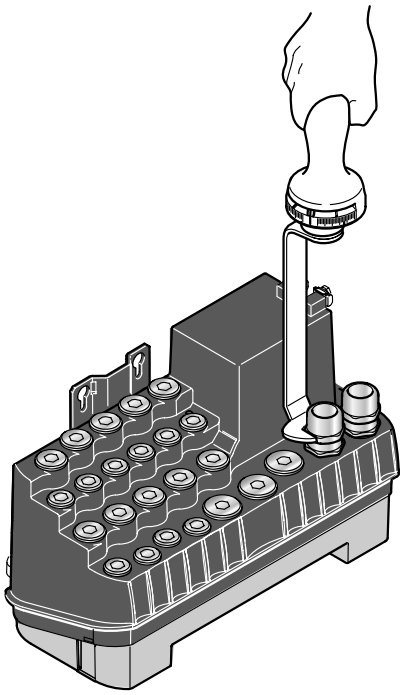
EMC cable glands

Tighten the EMC cable glands optionally supplied by SEW-EURODRIVE to the following torques:



512772875

Screw connection	Part number	Size	Tightening torque
EMC cable glands (nickel-plated brass)	1820 478 3	M16 x 1.5	3.0 Nm to 4.0 Nm (26-35 lb.in)
	1820 479 1	M20 x 1.5	3.5 Nm to 5.0 Nm (31-44 lb.in)
	1820 480 5	M25 x 1.5	4.0 Nm to 5.5 Nm (35-49 lb.in)
EMC cable glands (stainless steel)	1821 636 6	M16 x 1.5	3.5 Nm to 4.5 Nm (31-40 lb.in)
	1821 637 4	M20 x 1.5	5.0 Nm to 6.5 Nm (44-57 lb.in)
	1821 638 2	M25 x 1.5	6.0 Nm to 7.5 Nm (53-66 lb.in)

The cable retainer in the cable gland must withstand the withdrawal force of the cable from the cable gland as follows:

- Cable with outer diameter > 10 mm: ≥ 160 N
- Cable with outer diameter < 10 mm: = 100 N

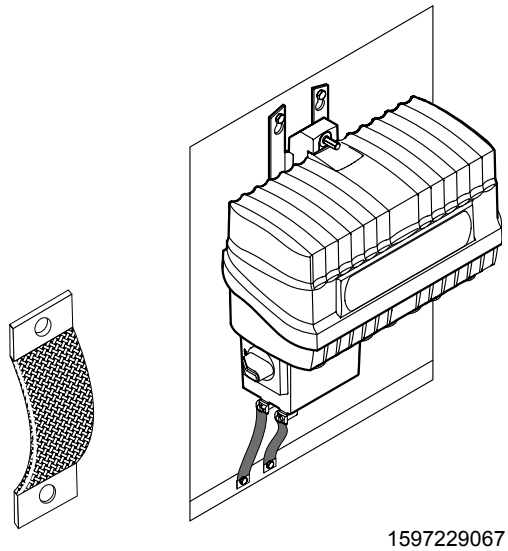
5 Electrical Installation

5.1 Installation planning taking into account EMC aspects

Successful installation of decentralized drives depends on selecting the correct cables, providing correct grounding, and a functioning equipotential bonding.

Always apply the **relevant standards**. Take special consideration of the following:

- **Equipotential bonding**
  - Low-impedance, HF-capable equipotential bonding must be provided independent of the protective earth connection (see also VDE 0113 or VDE 0100 part 540) through:
    - Large surface area for connection of MOVIFIT® mounting rail to the system (untreated, unpainted, uncoated mounting surface)
    - Use of flat grounding strips (HF litz wire) between MOVIFIT® and system grounding point
    - Low-impedance, HF-capable connection between connected motor and system grounding point



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  - Do not use the line shield of data lines for equipotential bonding.
- **Data lines and 24 V supply**
  - Must be routed separately from cables subject to interference (e.g. control cables from solenoid valves, motor cables).
- **Connection between MOVIFIT® and motor**
  - SEW-EURODRIVE recommends using pre-fabricated SEW hybrid cables especially designed for connecting MOVIFIT® units and motors.
- **Line shields**
  - Must have good EMC characteristics (high shield attenuation)
  - Must not serve only as mechanical protection for the cable
  - Must be connected to a wide area of the unit's metal housing at the cable ends; see also section "Connecting the PROFIBUS cable" (see page 43) and section "Connecting the hybrid cable" (see page 44)

	TIP
	Additional information is available in the SEW publication "Drive Engineering – Practical Implementation, EMC in Drive Engineering".

5.2 Installation instructions (all versions)

5.2.1 Connecting supply system cables

- The rated voltage and frequency of the MOVIFIT® motor starter must correspond to the data of the supplying system.
- Line cross section: according to input current I_{mains} for rated power (see section "Technical Data").
- Install the line fuse at the beginning of the supply system cable behind the supply bus junction. Use type D, D0, NH fuses or circuit breakers. Select the fuse size according to the line cross section.
- Do not use a conventional earth-leakage circuit-breaker as a protective device. Universal current-sensitive earth-leakage circuit breakers ("type B") are permitted as a protective device. During normal operation of MOVIFIT® drives, earth-leakage currents > 3.5 mA can occur.
- In accordance with EN 61800-5-1, a second PE connection (at least with the same cross section as the supply system cable) is required parallel to the protective earth via separate points of connection. Leakage currents > 3.5 mA may arise in service.
- Use contactor switch contacts in utilization category AC-3 according to IEC 158 to connect MOVIFIT® drives.

5.2.2 Earth-leakage circuit breakers

- Do not use a conventional earth-leakage circuit breaker as a protective device. Universal current-sensitive earth-leakage circuit breakers (trip current 300 mA) are permitted for use as protective devices. During normal operation of MOVIFIT®, earth-leakage currents of > 3.5 mA can occur.
- SEW-EURODRIVE recommends that you do not use earth-leakage circuit breakers. However, if an earth-leakage circuit breaker (FI) is specified as a direct or indirect touch guard, observe the following note in accordance with EN 61800-5-1:

⚠ WARNING

Wrong type of earth-leakage circuit breaker installed

Severe or fatal injuries

- MOVIFIT® can cause direct current in the protective earth. In cases where an earth-leakage circuit breaker (FI) is used for protection against direct or indirect contact, only an earth-leakage circuit breaker (FI) of type B on the external power supply side of the MOVIFIT® is permitted.

5.2.3 Mains contactor

- Only use a contactor of utilization category AC3 (EN 60947-4-1) as a mains contactor.

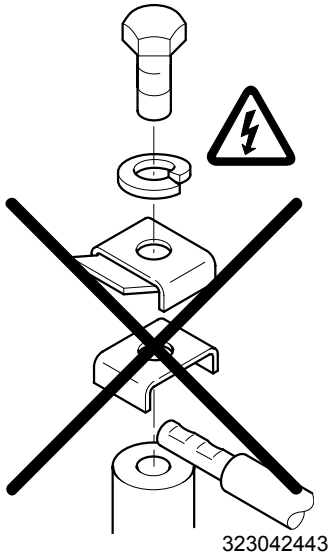
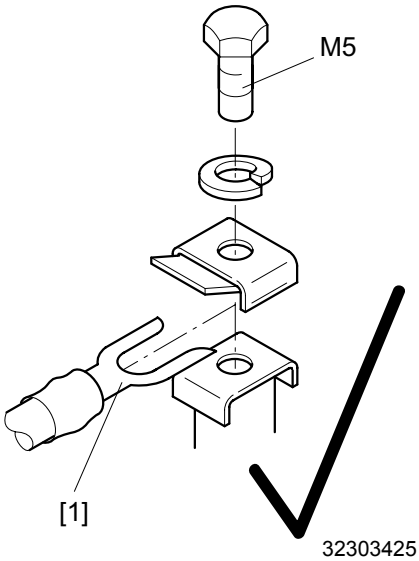
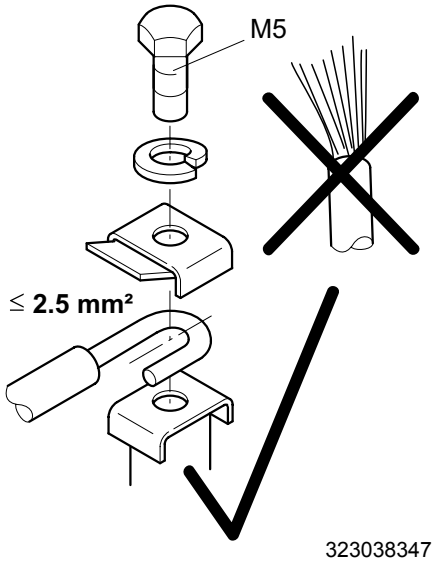
5.2.4 Notes on PE connection and/or equipotential bonding

⚠ DANGER

Incorrect connection of PE

Severe or fatal injuries or damage to property from electric shock

- The permitted tightening torque for the screw connection is 2.0-2.4 Nm (18-21 lb.in).
- Observe the following notes regarding PE connection:

Prohibited assembly procedure	Recommendation: Assembly with forked cable lug Permitted for all cross sections	Assembly with solid connecting wire Permitted for cross sections up to max. 2.5 mm²
		

[1] Forked cable lug suitable for M5 PE screws

Earth-leakage currents ≥ 3.5 mA may occur during normal operation. To meet the requirements of EN 61800-5-1, observe the following note:

- Route a second PE conductor with the cross section of the supply system cable in parallel to the protective earth via separate terminals, or use a copper protective earth conductor with a cross section of 10 mm^2.

5.2.5 Definition PE, FE

- PE refers to the mains-side protective earth connection. The PE conductor in the mains connection cable may only be connected with terminals marked with "PE" (these are designed for the maximum permissible mains connection cross section).
- FE refers to connections for "functional ground". You can connect any existing grounding conductor in the 24 V connection cable. CAUTION: Do not connect the mains-side PE there. These connections are not designed for this purpose and therefore electrical safety is not guaranteed.

5.2.6 Meaning of the 24 V voltage levels

MOVIFIT®-SC has a total of 3 different 24 V potential levels, which are electrically isolated from each other:

- 1) 24V_C: C = Continuous
- 2) 24V_S: S = Switched
- 3) 24V_O: O = Option

Depending on the requirements of the application, these can either be isolated, supplied externally, or connected to each other via a X29 distributor terminal.

1) 24V_C = Electronics and sensor supply

The MOVIFIT® control electronics and the sensors connected to the sensor supply outputs VO24_I, VO24_II, and VO24_III are supplied by 24V_C. Usually, this supply voltage may not be switched off for operation as MOVIFIT® can, in this case, no longer be addressed via the fieldbus or network, and the sensor signals can no longer be processed. The unit also requires a certain amount of time to start up when switched on again.

2) 24V_S = Actuator supply

The digital outputs DO.. and the actuators connected to them are supplied by 24V_S. The sensor supply output VO24_IV is also supplied by 24V_S, while the digital inputs DI12 to DI15 are at the reference potential 0V24_S (as these can be connected to the outputs on the same connections as an alternative). Depending on the application, the supply voltage can be switched off for operation to specifically deactivate the actuators in the system centrally.

3) 24V_O = Option supply

The integrated option card and the sensor/actuator interfaces available on it are supplied by 24V_O.

Depending on the application, the 24V_O can be supplied by either 24V_C or 24V_S (via jumpers at X29), or it can be supplied externally. In this case, note that the entire option card with the connected sensors and actuators is no longer supplied when voltage is disconnected. This generally prompts an error message.

Connection of voltages

Both voltages 24V_C and 24V_S can be connected via terminal X20 with a large line cross section and further looped to the next unit as "24V power bus". The 24V_O voltage is to be connected to terminal X29.

	TIP
	For connection examples, refer to section "Power bus connection examples" (see page 70).

5.2.7 Plug connectors

All MOVIFIT® plug connectors are illustrated in these operating instructions with a contact end view.

5.2.8 Protective devices

MOVIFIT® drives are equipped with integrated overload protection devices, which make external devices obsolete.

5.2.9 UL-compliant installation

- Use only copper conductors with a temperature range of 75°C as connection cables.
- MOVIFIT®-SC is designed for operation on voltage supply systems with a maximum supply current of AC 5,000 A and a maximum rated voltage of AC 500 V.
- As unit fuses for MOVIFIT® SC, use UL-compliant fuses whose power data does not exceed 25 A/600 V.
- For UL-compliant installation, only the EBOX specified on the ABOX nameplate may be mounted to the ABOX. The UL certification refers only to the ABOX/EBOX combination stated on the nameplate.
- For UL-compliant installation, the load capacity of the X1 power terminal is limited to a maximum of 25 A (sum of the device current and the pass-through current to connected devices).
- For UL-compliant installation, the maximum ambient temperature of the MOVIFIT®-SC is limited to 40°C (with P_{Rated} reduction: 3% I_{Rated} per K up to 60°C).
- The motor starters MTS11A015 and MTS11A040 are suitable for group installation.

5.2.10 Installation altitude higher than 1,000 m above sea level

MOVIFIT® with supply voltages of 380 to 500 V can be used at altitudes of more than 1,000 m (3,281 ft) above sea level up to a maximum of 4,000 m (13,123 ft) above sea level under the following peripheral conditions:

- The rated continuous power is reduced based on the reduced cooling above 1,000 m (see section "Technical Data").
- At 1,000 m (3,281 ft) above sea level and higher, the air and creeping distances are only sufficient for overvoltage class 2. If the installation calls for overvoltage class 3, you will have to install additional external overvoltage protection to limit overvoltage peaks to 2.5 kV phase-to-phase and phase-to-ground.
- If safe electrical disconnection is required, it must be implemented outside the unit at altitudes of more than 2,000 m (6,561 ft) above sea level (safe electrical disconnection in accordance with EN 61800-5-1 and EN 60204).
- Up to 2,000 m above sea level, the permitted rated supply voltage is 3 x 500 V. Every 100 m, it is reduced by 6 V to a maximum of 3 x 380 V at 4,000 m above sea level.

5.2.11 Wiring check

Before connecting the system to the power source for the first time, you must perform a wiring check to prevent injuries to persons and/or damage to systems and equipment caused by incorrect wiring. Perform this check as follows:

- Remove all electronic units (EBOX) from the connection units (ABOX).
- Check the insulation of the wiring in accordance with applicable national standards.
- Check the grounding.
- Check the insulation between the supply system cable and the DC 24 V cable.
- Check the insulation between mains cable and communication cable.
- Check the polarity of the DC 24 V cable.
- Check the polarity of the communication cable.
- Ensure equipotential bonding between the MOVIFIT® units.

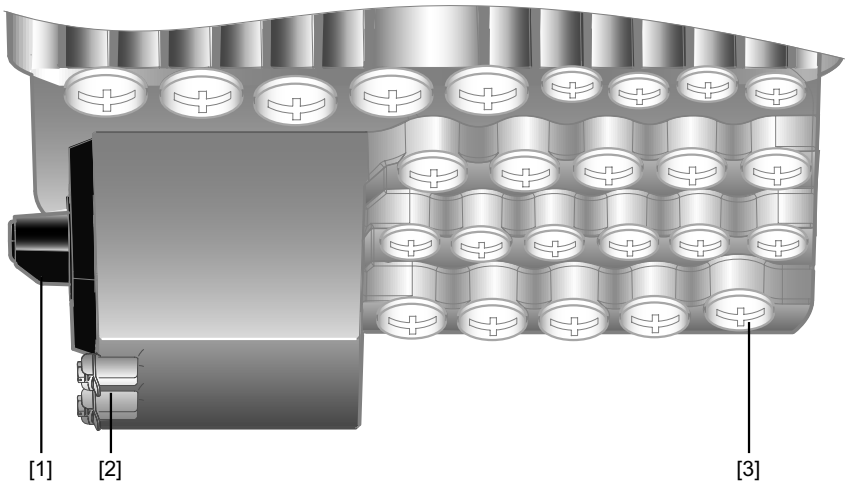
After the wiring check

- Install and fasten all electronics units (EBOX).
- Seal all cable openings and plug connections that are not in use.

5.3 Standard ABOX "MTA...-S02.-...-00"

5.3.1 Description

The following figure depicts the standard ABOX with "MTA...-S02.-...-00" terminals and cable bushings:



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[1] Maintenance switch (option)
[2] PE connection
[3] Diagnostics socket (RJ10) under the screw connection

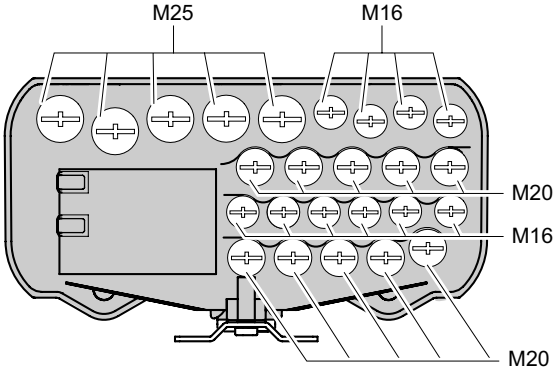
5.3.2 Variants

The following variants of the standard ABOX are available for MOVIFIT®-SC (MTS):

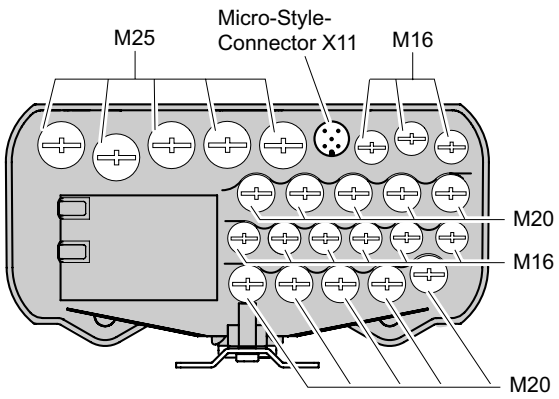
- MTA11A-503-S0**2**.-...-00:
  - Optional switch disconnector

The following figure shows the screw connections and plug connectors of the standard ABOX depending on the fieldbus interface:

PROFIBUS MTA11A-503-S0.**1**-...-00
PROFINET MTA11A-503-S0.**3**-...-00
EtherNet/IP MTA11A-503-S0.**3**-...-00
Modbus/TCP MTA11A-503-S0.**3**-...-00



DeviceNet MTA11A-503-S0.**2**-...-00



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5.3.3 Additional installation instructions for "MTA...-S02.-...-00"

Permitted connection cross section and current-carrying capacity of the terminals

Terminal data	X1 / X20	X8 / X9	X25 / X30 / X31 / X35 / X45 / X81 / X91	X29
Connection cross section (mm^2)	0.2 mm^2 – 6 mm^2	0.08 mm^2 – 4[1] mm^2	0.08 mm^2 – 2.5[1] mm^2	0.2 mm^2 – 1.5[1] mm^2
Connection cross section (AWG)	AWG 24 - AWG 10	AWG 28 – AWG 12[1]	AWG 28 – AWG 14[1]	AWG 24 – AWG 16[1]
Current-carrying capacity (max. continuous current)	X1: 32 A X20: 16 A	20 A	10 A	10 A
Conductor stripping length	13-15 mm	8-9 mm	5-6 mm	5-6 mm

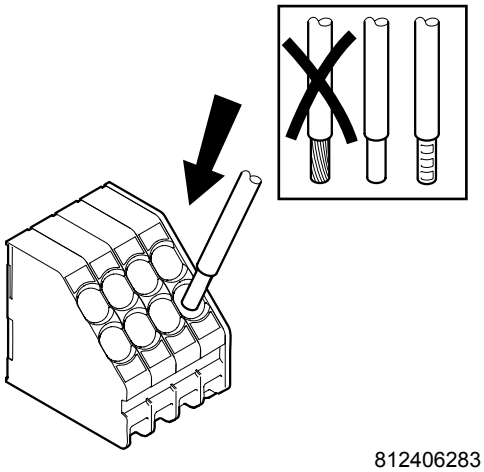
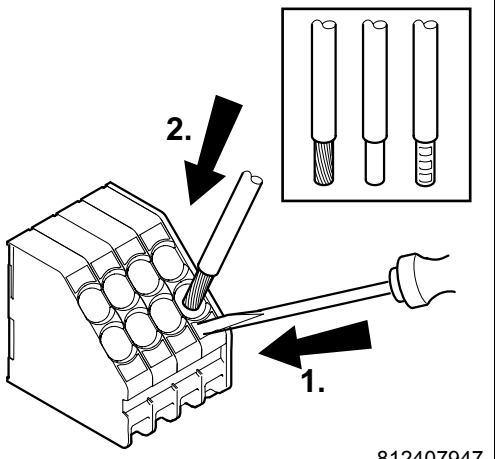
1) The maximum permitted cross section is reduced by one unit when conductor end sleeves are used (e.g. 2.5 mm^2 → 1.5 mm^2).

Conductor end sleeves

Use conductor end sleeves without insulating shrouds for terminals X1, X20, X8, and X9 (DIN 46228 part 1, material E-CU).

Enabling the terminals

Terminals X1, X20

Connecting conductors without a screw driver[1]	Connecting conductors using a screw driver[2]
	
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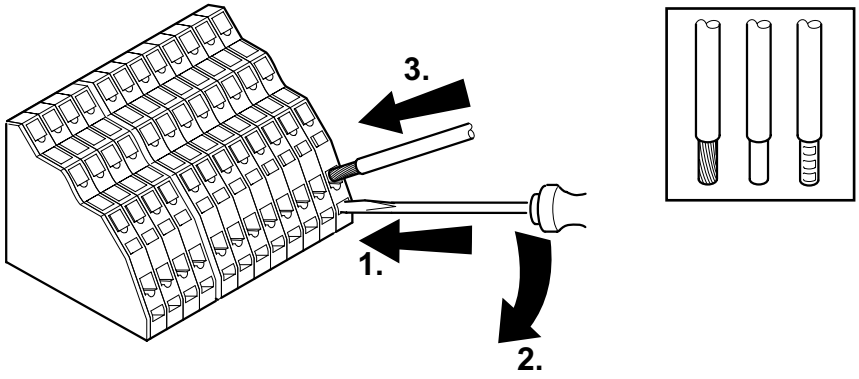
1) Single-wire conductors and flexible conductors with conductor end sleeves can be installed directly (without using a tool) up to two cross section sizes below the rated cross section.
2) When connecting untreated, flexible conductors or conductors with a small cross section that cannot be installed directly, firmly insert a screw driver into the activation opening to open the clamping spring.

Terminals X8 / X81 / X9 / X91 / X29 / X45 / X25 / X30 / X31 / X35[1]



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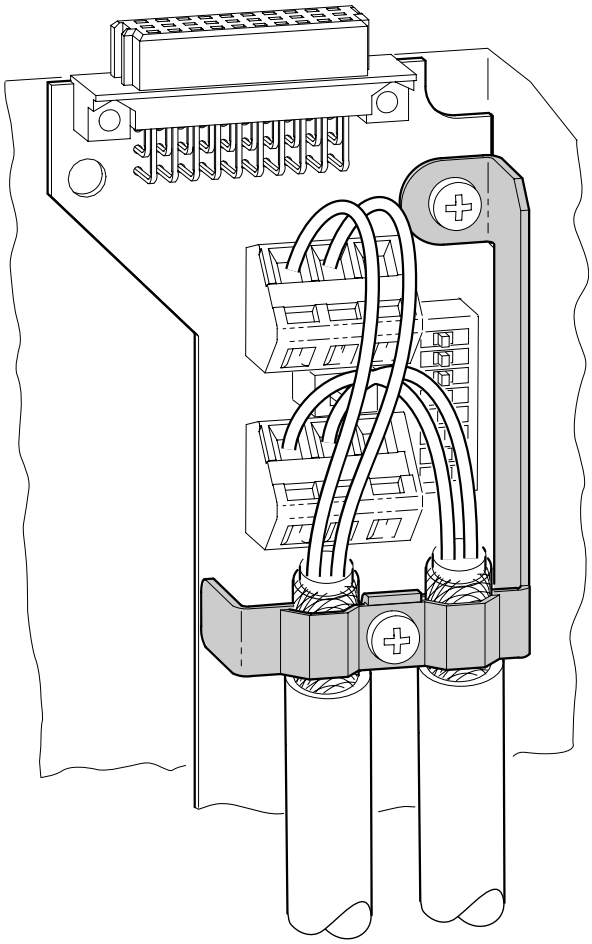
1) Always use a screw driver to connect these terminals, regardless of the conductor type.

Connection of the PROFIBUS cable in MOVIFIT®

Observe the following guidelines compiled by the PROFIBUS Nutzerorganisation e.V. (user organization, Internet: www.profibus.com) when installing the PROFIBUS:

- "Installation guidelines for PROFIBUS DP/FMS", order number 2.111 (German) or 2.112 (English)
- "Installation recommendations for PROFIBUS", order number 8.021 (German) or 8.022 (English)

Apply the cable shield of the PROFIBUS cable as follows:



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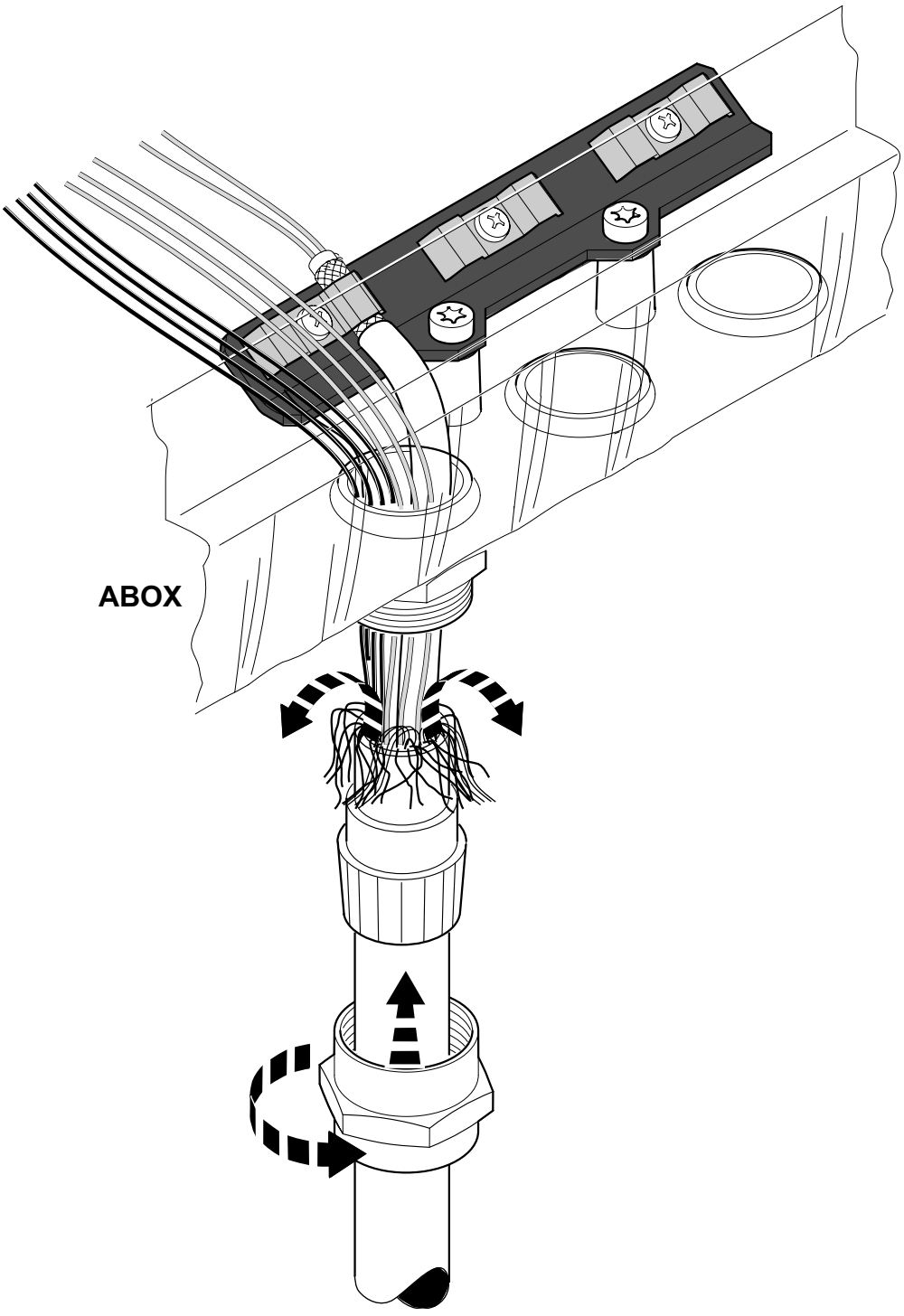
	TIPS
	• Note that the PROFIBUS connector cores inside the MOVIFIT® must be kept as short as possible and are always of equal length for the incoming and outgoing bus. • The PROFIBUS is not interrupted when you remove the EBOX (electronics unit) from the ABOX (connection unit).

Connecting the hybrid cables

- For connecting MOVIFIT® and the motor, SEW-EURODRIVE recommends using the shielded and pre-fabricated SEW hybrid cables specifically designed for this purpose; see section "Hybrid cables" (see page 87).
- The outer shield of the hybrid cable must be attached to the housing of the unit using a suitable EMC cable gland.
- The inner shield of the hybrid cable must be connected via a shield plate in the MOVIFIT®-ABOX as follows:



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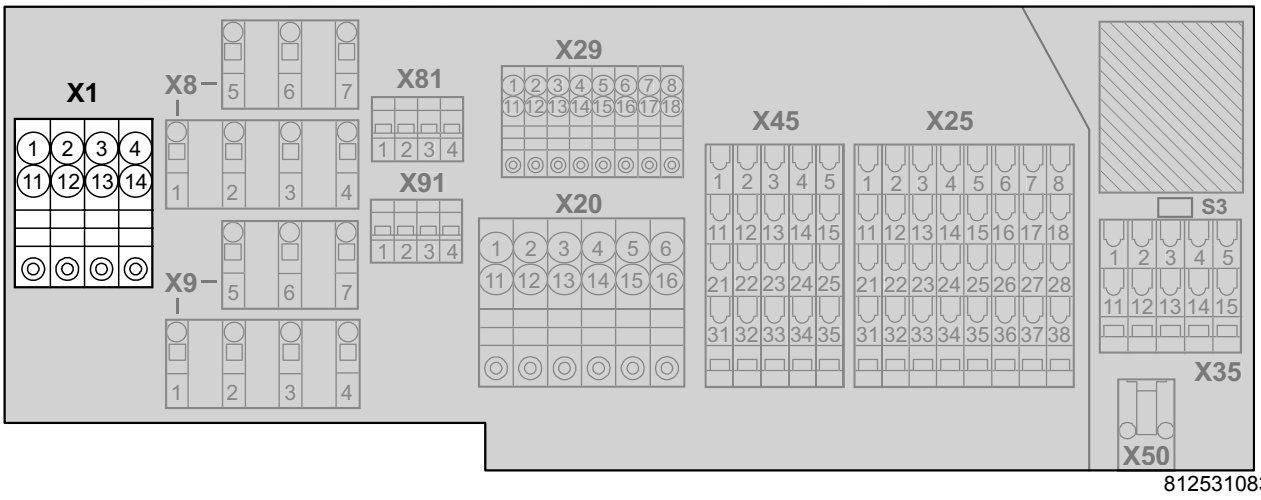
5.3.4 Fieldbus/option-independent terminal assignment

DANGER

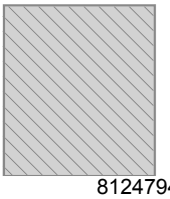
The maintenance switch only disconnects the integrated motor circuit breaker from the mains. Voltage is still present on the terminals of the MOVIFIT® unit.

Severe or fatal injuries from electric shock

- Switch off the power to the MOVIFIT® using a suitable external disconnecting device and wait at least 1 minute before opening the wiring space.



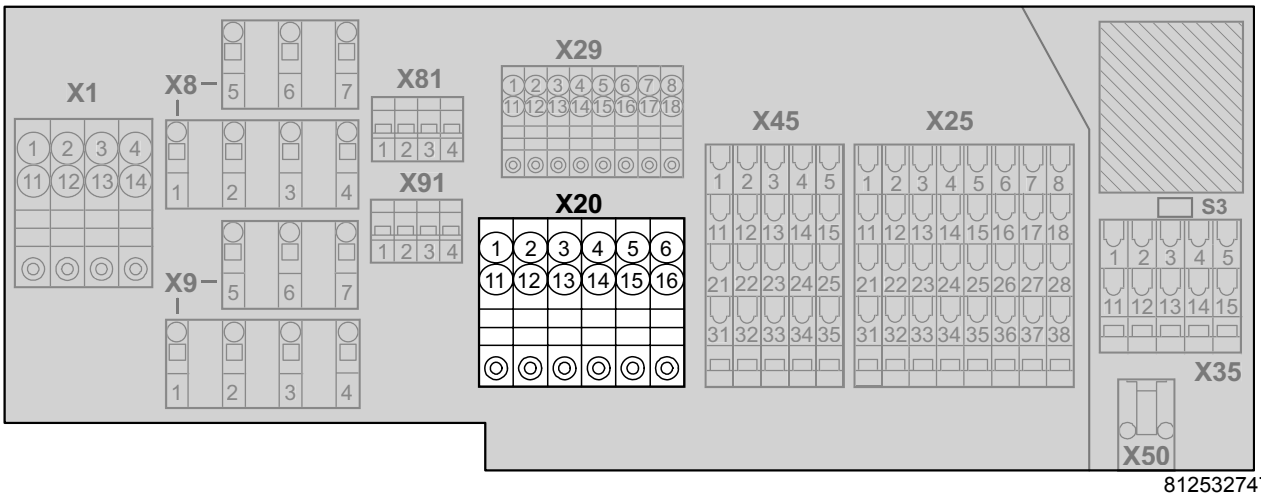
812531083



812479499

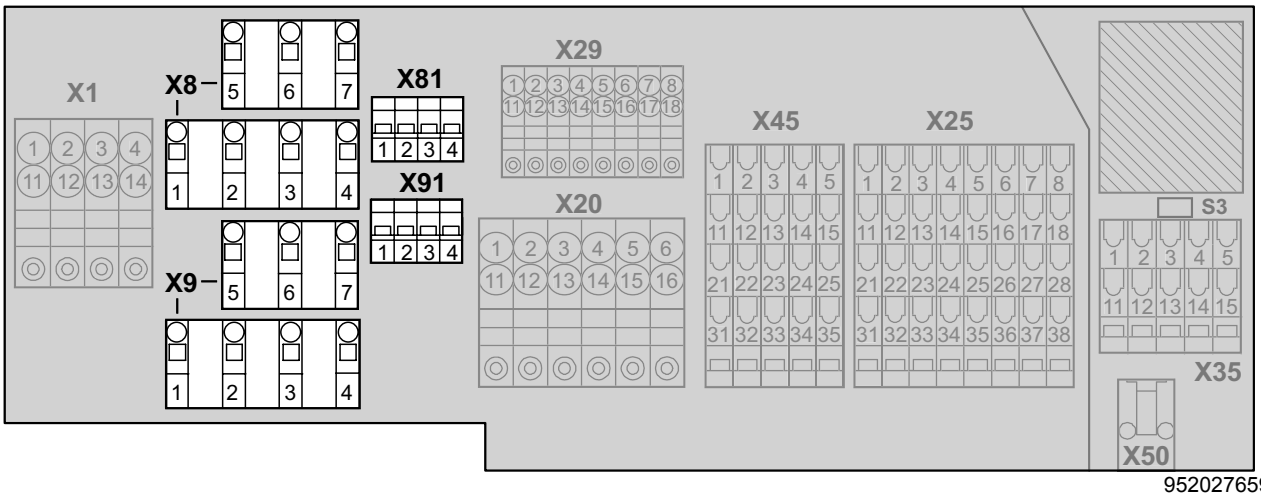
The terminal diagrams depicted in this section differ depending on the fieldbus system used. The area dependent on the fieldbus is therefore depicted as hatched and is described in the following sections.

Mains terminal (power bus)			
No.		**Name**	**Function**
X1	**1**	PE	Mains connection PE (IN)
	2	L1	Mains connection phase L1 (IN)
	3	L2	Mains connection phase L2 (IN)
	4	L3	Mains connection phase L3 (IN)
	11	PE	Mains connection PE (OUT)
	12	L1	Mains connection phase L1 (OUT)
	13	L2	Mains connection phase L2 (OUT)
	14	L3	Mains connection phase L3 (OUT)



812532747

24 V supply terminal (24 V power bus)			
No.		**Name**	**Function**
X20	**1**	FE	Functional ground (IN)
	2	+24V_C	+24 V continuous voltage supply (IN)
	3	0V24_C	0V24 reference potential - continuous voltage (IN)
	4	FE	Functional ground (IN)
	5	+24V_S	+24 V supply – switched (IN)
	6	0V24_S	0V24 reference potential - switched (IN)
	11	FE	Functional ground (OUT)
	12	+24V_C	+24 V continuous voltage supply (OUT)
	13	0V24_C	0V24 reference potential - continuous voltage (OUT)
	14	FE	Functional ground (OUT)
	15	+24V_S	+24 V supply - switched (OUT)
	16	0V24_S	0V24 reference potential - switched (OUT)



952027659

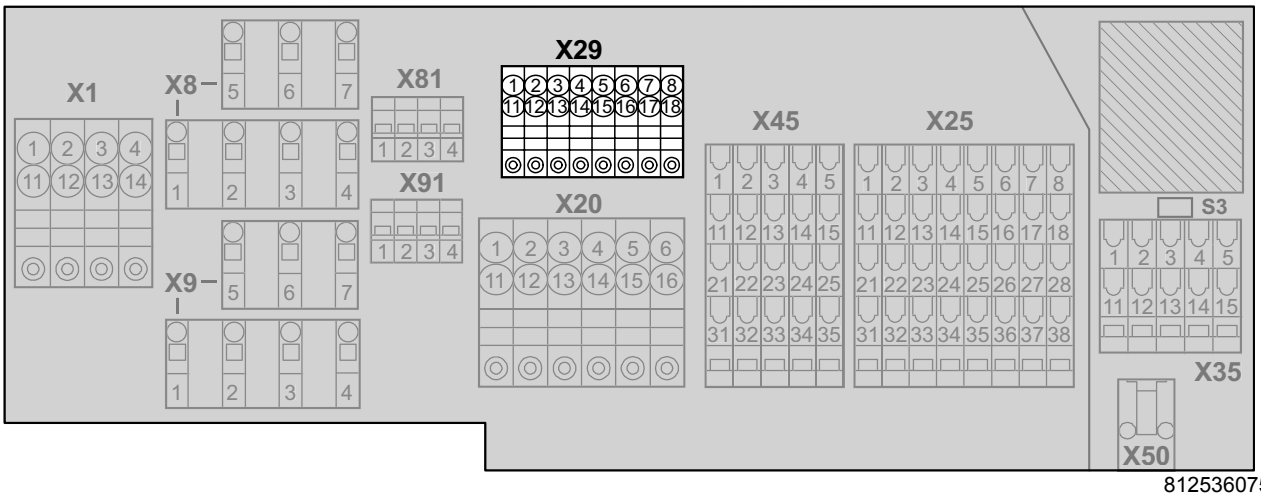
Motor connection terminal (connection via hybrid cable)				
No.		**Name**	**Function**	**Motor**
X8	1	PE	Motor 1 PE connection	
	2	U_M1	Output motor 1 phase U	
	3	V_M1	Output motor 1 phase V	
	4	W_M1	Output motor 1 phase W	
	5	15_M1	Connection for SEW brake, motor 1 terminal 15 (blue)	1
	6	14_M1	Connection for SEW brake, motor 1 terminal 14 (white)	
	7	13_M1	Connection for SEW brake, motor 1 terminal 13 (red)	
X81	**1**	TF+_M1	Connection for temperature sensor TF/TH (+), motor 1	
	2	TF-_M1	Connection for temperature sensor TF/TH (-), motor 1	
	3	DB00	Binary output "Brake released", motor 1 (switching signal 24 V)	
	4	0V24_C	0V24 reference potential for brake output for motor 1	
Important: For operation with only one motor, use terminals X8 and X81. In this case, do not connect terminals X9 and X91.				
X9	**1**	PE	Motor 2 PE connection	
	2	U_M2	Output motor 2 phase U	
	3	V_M2	Output motor 2 phase V	
	4	W_M2	Output motor 2 phase W	
	5	15_M2	Connection for SEW brake, motor 2 terminal 15 (blue)	2
	6	14_M2	Connection for SEW brake, motor 2 terminal 14 (white)	
	7	13_M2	Connection for SEW brake, motor 2 terminal 13 (red)	
X91	**1**	TF+_M2	Connection for temperature sensor TF/TH (+), motor 2	
	2	TF-_M2	Connection for temperature sensor TF/TH (-), motor 2	
	3	DB01	Binary output "Brake released", motor 2 (switching signal 24 V)	
	4	0V24_C	0V24 reference potential for brake output for motor 2	

⚠ DANGER

If binary outputs DB00 or DB01 are used to control the brake, do not change the parameters of the functions of the binary outputs.

Severe or fatal injuries

- Before using the binary output for controlling the brake, check the parameter settings.



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Distributor terminal 24 V (for distributing the supply voltage(s) to the option card)			
No.		**Name**	**Function**
X29	**1**	+24V_C	+24 V supply - continuous voltage (jumpered with X20/2)
	2	0V24_C	0V24 reference potential - continuous voltage (jumpered with X20/3)
	3	+24V_S	+24 V supply - switched (jumpered with X20/5)
	4	0V24_S	0V24 reference potential – switched (jumpered with X20/6)
	5	Res.	Reserved
	6	Res.	Reserved
	7	+24V_O	+24 V supply for option card, supply
	8	0V24_O	0V24 reference potential for option card, supply
	11	+24V_C	+24 V supply - continuous voltage (jumpered with X20/2)
	12	0V24_C	0V24 reference potential - continuous voltage (jumpered with X20/3)
	13	+24V_S	+24 V supply - switched (jumpered with X20/5)
	14	0V24_S	0V24 reference potential – switched (jumpered with X20/6)
	15	Res.	Reserved
	16	Res.	Reserved
	17	+24V_O	+24 V supply for option card, supply
	18	0V24_O	0V24 reference potential for option card, supply

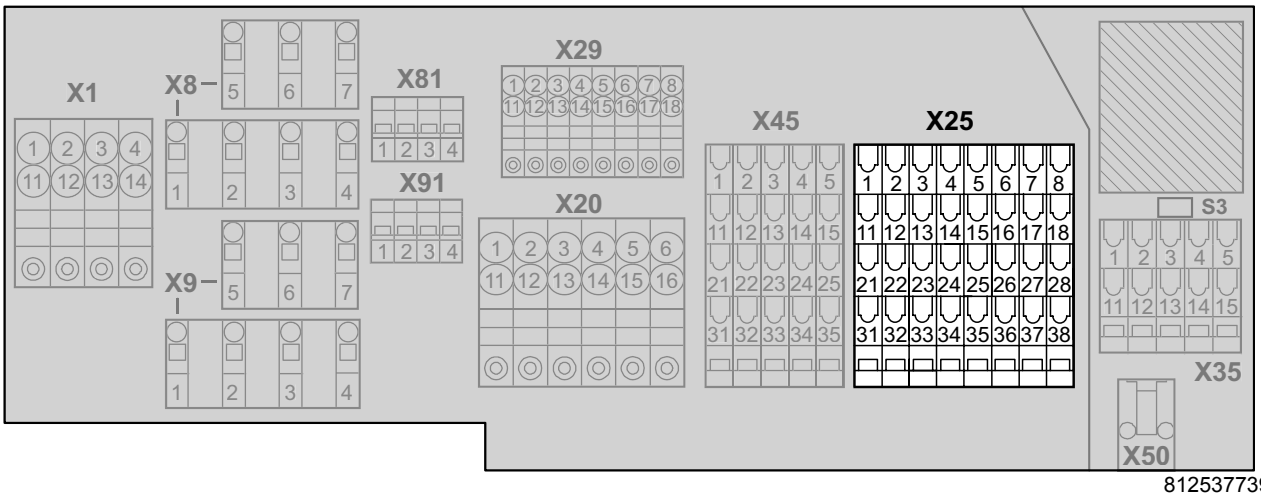
TIPS

- The terminal assignment "X29" illustrated here applies as of status 11 of the wiring board. If you use a wiring board with another status, consult SEW-EURODRIVE.
- The status of the wiring board is indicated in the first status field of the ABOX nameplate:

Status: 11 11 -- 10 -- 10 10 -- --

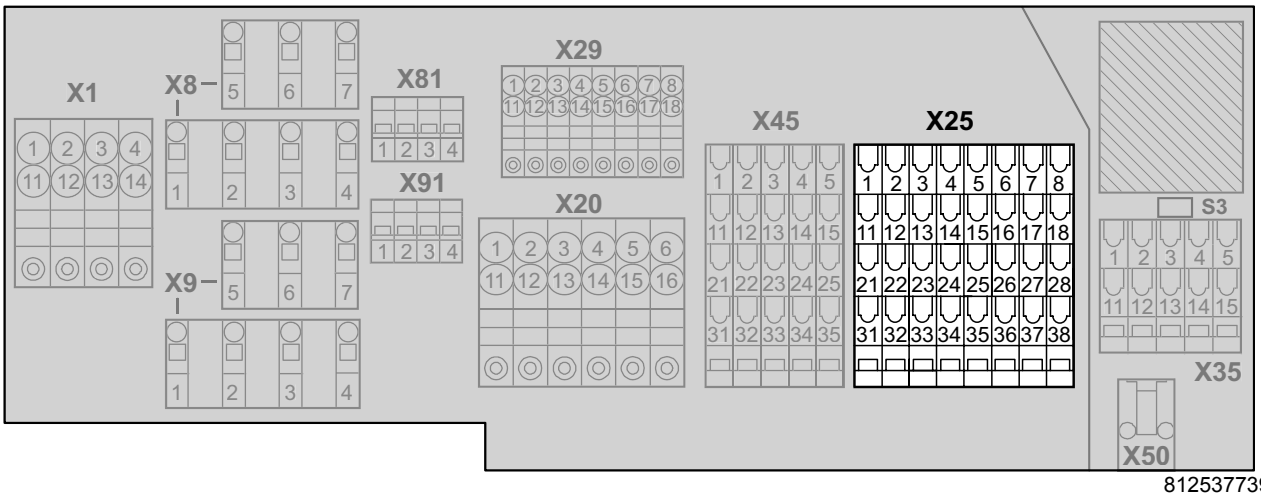
Status of the wiring circuit board

- You can find an example of a nameplate in section "Sample ABOX type code".



812537739

I/O terminal (connection of sensors + actuators)					
No.		**"System" function level with PROFIBUS** **"Technology" function level with PROFIBUS, DeviceNet, PROFINET, EtherNet/IP, or Modbus/TCP** **"Classic" function level with PROFINET**		**Function level "Classic" with PROFIBUS or DeviceNet**	
		Name	**Function**	**Name**	**Function**
X25	**1**	DI00	Binary input DI00 (switching signal)	DI00	Binary input DI00 (switching signal)
	2	DI02	Binary input DI02 (switching signal)	DI01	Binary input DI01 (switching signal)
	3	DI04	Binary input DI04 (switching signal) Encoder 1 connection, track A	DI02	Binary input DI02 (switching signal)
	4	DI06	Binary input DI06 (switching signal) Encoder 2 connection, track A	DI03	Binary input DI03 (switching signal)
	5	DI08	Binary input DI08 (switching signal) Encoder 3 connection, track A	DI04	Binary input DI04 (switching signal)
	6	DI10	Binary input DI10 (switching signal)	DI05	Binary input DI05 (switching signal)
	7	DI12/DO00	Binary input DI12 or binary output DO00 (switching signal)	DI06/DO00	Binary input DI06 or binary output DO00 (switching signal)
	8	DI14/DO02	Binary input DI14 or binary output DO02 (switching signal)	DI07/DO01	Binary input DI07 or binary output DO01 (switching signal)
	11	DI01	Binary input DI01 (switching signal)	**Terminals X25/11 to X25/18 are reserved with the "Classic" function level (PROFIBUS or DeviceNet).**	
	12	DI03	Binary input DI03 (switching signal)		
	13	DI05	Binary input DI05 (switching signal) Encoder 1 connection, track B		
	14	DI07	Binary input DI07 (switching signal) Encoder 2 connection, track B		
	15	DI09	Binary input DI09 (switching signal) Encoder 3 connection, track B		
	16	DI11	Binary input DI11 (switching signal)		
	17	DI13/DO01	Binary input DI13 or binary output DO01 (switching signal)		
	18	DI15/DO03	Binary input DI15 or binary output DO03 (switching signal)		



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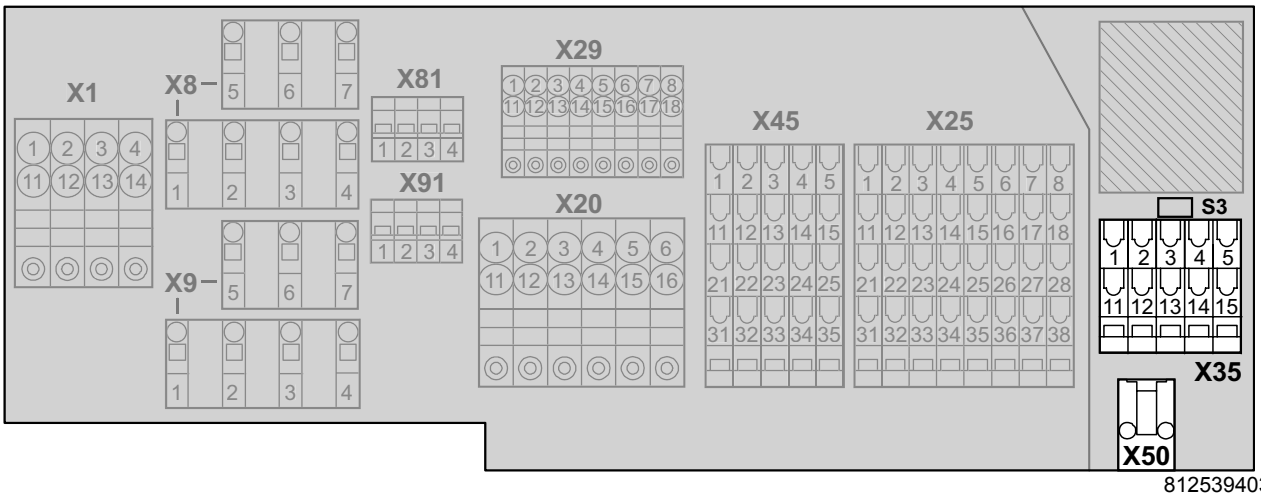
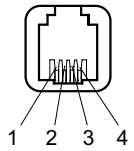
I/O terminal (connection of sensors + actuators)				
No.		**"System" function level with PROFIBUS** **"Technology" function level with PROFIBUS, DeviceNet, PROFINET, EtherNet/IP, or Modbus/TCP** **"Classic" function level with PROFINET**		**Function level "Classic" with PROFIBUS or DeviceNet**
		Name	**Function**	**Function**
X25	**21**	VO24-I	+24 V sensor supply, group I (DI00 - DI03), from +24V_C	+24 V sensor supply, group I (DI00 - DI01), from +24V_C
	22	VO24-I	+24 V sensor supply, group I (DI00 - DI03), from +24V_C	+24 V sensor supply, group I (DI00 - DI01), from +24V_C
	23	VO24-II	+24 V sensor supply, group II (DI04 - DI07), from +24V_C	+24 V sensor supply, group II (DI02 - DI03), from +24V_C
	24	VO24-II	+24 V sensor supply, group II (DI04 - DI07), from +24V_C	+24 V sensor supply, group II (DI02 - DI03), from +24V_C
	25	VO24-III	+24 V sensor supply, group III (DI08 - DI11), from +24V_C	+24 V sensor supply, group III (DI04 - DI05), from +24V_C
	26	VO24-III	+24 V sensor supply, group III (DI08 - DI11), from +24V_C	+24 V sensor supply, group III (DI04 - DI05), from +24V_C
	27	VO24-IV	+24 V sensor supply, group IV (DI12 - DI15), from +24V_S	+24 V sensor supply, group IV (DI06 - DI07), from +24V_S
	28	VO24-IV	+24 V sensor supply, group IV (DI12 - DI15), from +24V_S	+24 V sensor supply, group IV (DI06 - DI07), from +24V_S
	31	0V24_C	0V24 reference potential for sensors	
	32	0V24_C	0V24 reference potential for sensors	
	33	0V24_C	0V24 reference potential for sensors	
	34	0V24_C	0V24 reference potential for sensors	
	35	0V24_C	0V24 reference potential for sensors	
	36	0V24_C	0V24 reference potential for sensors	
	37	0V24_S	0V24 reference potential for actuators or sensors, group IV	
	38	0V24_S	0V24 reference potential for actuators or sensors, group IV	



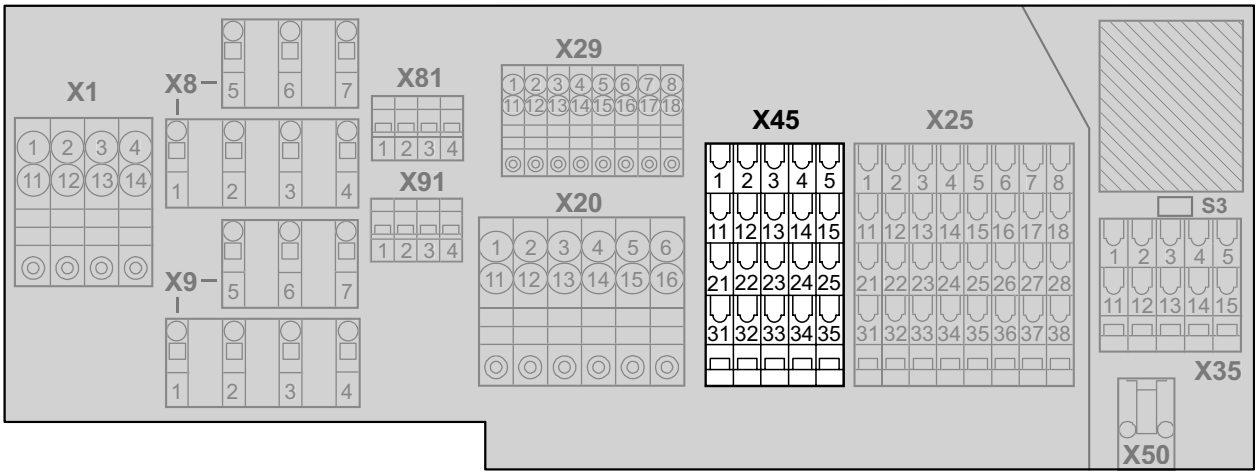
SBus terminal (CAN)			
No.		**Name**	**Function**
X35[1]	**1**	CAN_GND	0 V reference potential for SBus (CAN)
	2	CAN_H	SBus CAN_H - incoming
	3	CAN_L	SBus CAN_L - incoming
	4	+24V_C_PS	+24 V supply - continuous voltage for peripheral devices
	5	0V24_C	0V24 reference potential - continuous voltage for peripheral devices (jumpered with X20/3)
	11	CAN_GND	0 V reference potential for SBus (CAN)
	12	CAN_H	SBus CAN_H – outgoing
	13	CAN_L	SBus CAN_L – outgoing
	14	+24V_C_PS	+24 V supply – continuous voltage for peripheral devices
	15	0V24_C	0V24 reference potential - continuous voltage for peripheral devices (jumpered with X20/3)

1) X35 terminals can only be used with function levels "Technology" or "System".

Diagnostics (RJ10 socket)			
No.		**Name**	**Function**
X50 	**1**	+5 V	5 V supply
	2	RS+	RS485 diagnostics interface
	3	RS-	RS485 diagnostics interface
	4	0V5	0 V reference potential for RS485

5.3.5 Option-dependent terminal assignment

I/O terminals X45

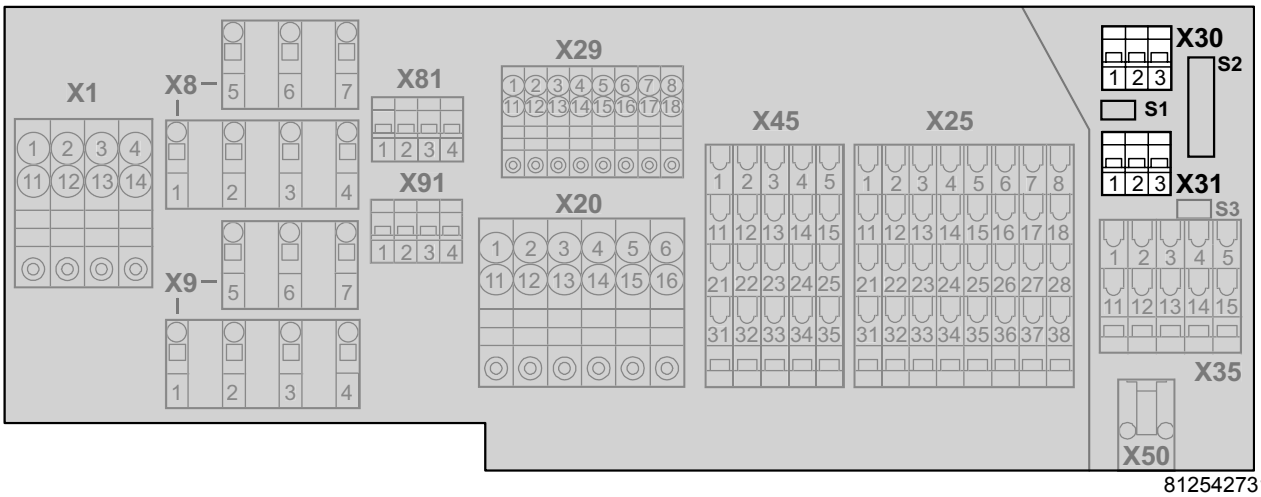


812541067

I/O terminal			
No.		**Name**	**Function**
X45	**1**	Res.	Reserved
	2	Res.	Reserved
	3	Res.	Reserved
	4	Res.	Reserved
	5	Res.	Reserved
	11	Res.	Reserved
	12	Res.	Reserved
	13	Res.	Reserved
	14	Res.	Reserved
	15	Res.	Reserved
	21	Res.	Reserved
	22	Res.	Reserved
	23	Res.	Reserved
	24	Res.	Reserved
	25	Res.	Reserved
	31	Res.	Reserved
	32	Res.	Reserved
	33	Res.	Reserved
	34	Res.	Reserved
	35	Res.	Reserved

5.3.6 Fieldbus-dependent terminal/pin assignment

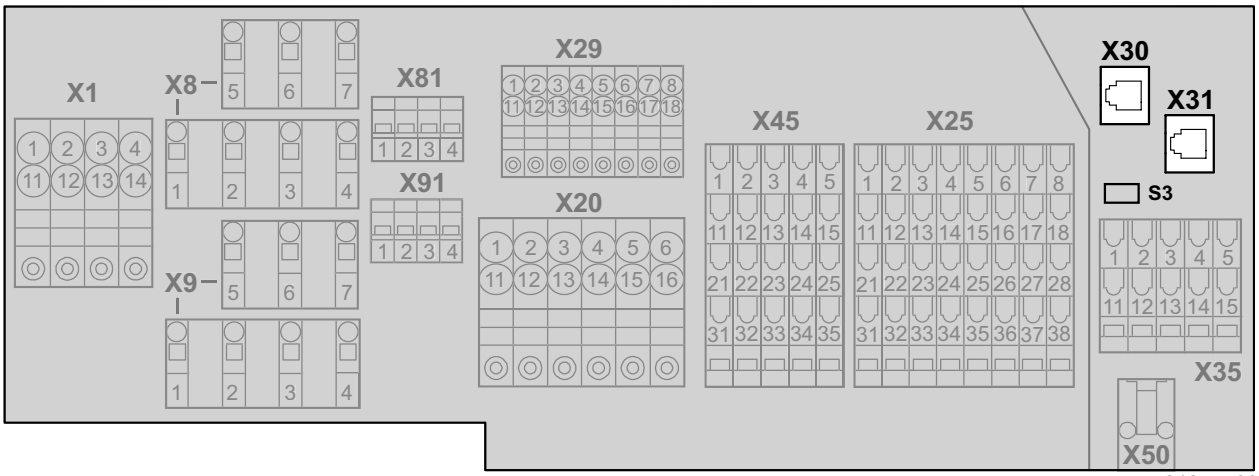
PROFIBUS terminal assignment



812542731

PROFIBUS terminal			
No.		**Name**	**Function**
X30	**1**	A_IN	PROFIBUS line A – incoming
	2	B_IN	PROFIBUS line B – incoming
	3	0V5_PB	0V5 reference potential for PROFIBUS (for measuring purposes only)
X31	**1**	A_OUT	PROFIBUS line A – outgoing
	2	B_OUT	PROFIBUS line B – outgoing
	3	+5V_PB	+5 V output PROFIBUS (for measuring purposes only)

Pin assignment for EtherNet/IP, PROFINET IO, and Modbus/TCP



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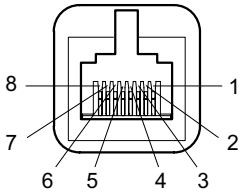
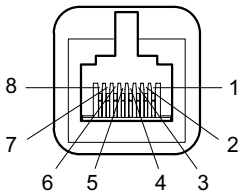
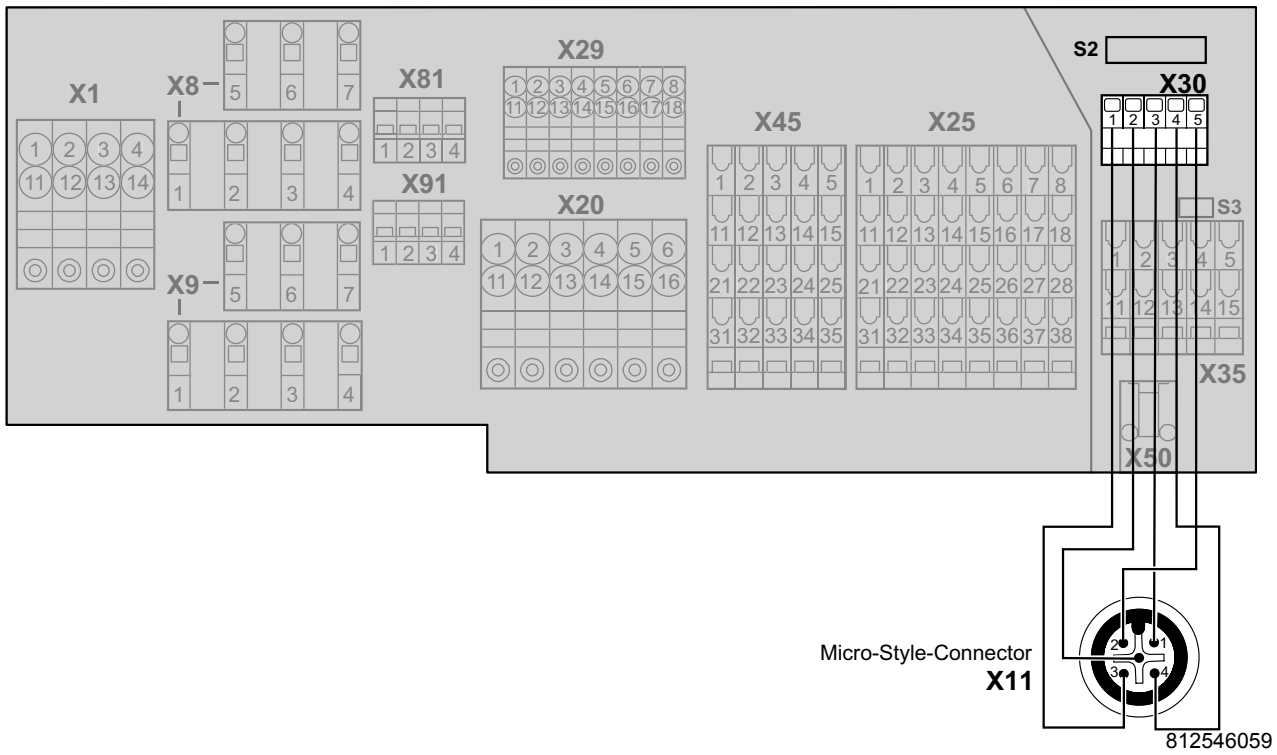
EtherNet/IP, PROFINET and Modbus/TCP connection (RJ45 socket)				
No.		**Name**	**Function**	
X30 	**1**	TX+	Transmit line port 1 positive	Ethernet port 1
	2	TX-	Transmit line port 1 negative	
	3	RX+	Receive line port 1 positive	
	4	Res.	On 75 ohm lead	
	5	Res.	On 75 ohm lead	
	6	RX-	Receive line port 1 negative	
	7	Res.	On 75 ohm lead	
	8	Res.	On 75 ohm lead	
X31 	**1**	TX+	Transmit line port 2 positive	Ethernet port 2
	2	TX-	Transmit line port 2 negative	
	3	RX+	Receive line port 2 positive	
	4	Res.	On 75 ohm lead	
	5	Res.	On 75 ohm lead	
	6	RX-	Receive line port 2 negative	
	7	Res.	On 75 ohm lead	
	8	Res.	On 75 ohm lead	

DeviceNet terminal/pin assignment



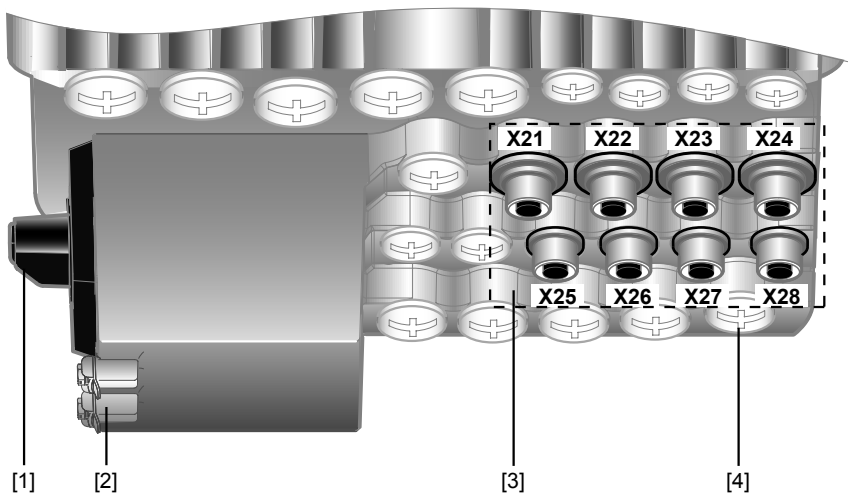
DeviceNet					
Pin no.	**X11**	**X30**	**Name**	**Function**	**Color coding**
Micro-style connector (standard coding)	**1**	**3**	DRAIN	Equipotential bonding	Blue
	2	**5**	V+	DeviceNet voltage supply +24 V	Gray
	3	**1**	V-	DeviceNet reference potential 0V24	Brown
	4	**4**	CAND_H	CAN_H data line	Black
	5	**2**	CAND_L	CAN_L data line	White

5.4 Hybrid ABOX "MTA...-S42.-...-00"

	TIP
	• The hybrid ABOX is based on the standard ABOX "MTA...-S02.-...-00". Therefore, the following describes only the additional plug connectors in comparison with the standard ABOX. • For a description of the terminals, refer to section "Standard ABOX "MTA...-S02.-...00"" (see page 39). • Customers cannot use terminal strip X25 because the described plug connectors are assigned to it.

5.4.1 Description

The following figure depicts the hybrid ABOX with M12 plug connectors for connecting digital I/Os:



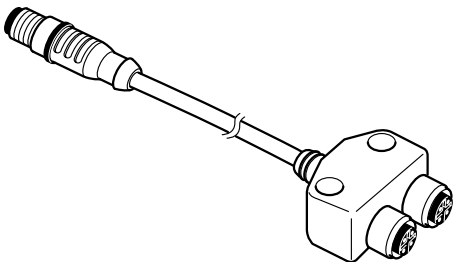
915287947

[1] Maintenance switch (option)
[2] PE connection
[3] M12 plug connector for I/Os
[4] Diagnostics socket (RJ10) under the screw connection

Y adapter

Use a Y adapter with an extension for connecting two sensors/actuators to an M12 plug connector.

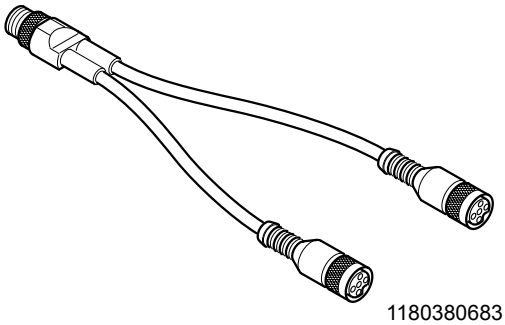
The Y adapter is available from various manufacturers:



915294347

Manufacturer: Escha

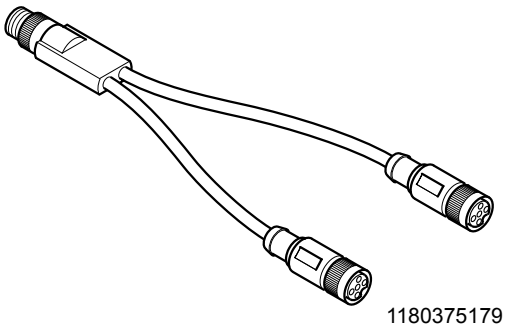
Type: WAS4-0,3-2FKM3/..



1180380683

Manufacturer: Binder

Type: 79 5200 ..

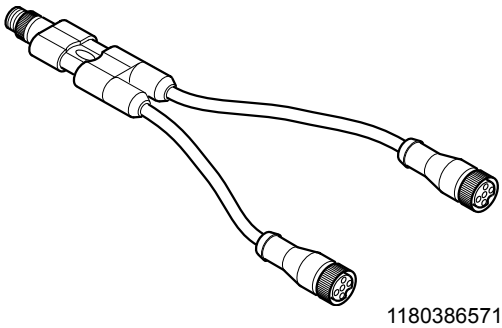


1180375179

Manufacturer: Phoenix Contact

Type: SAC-3P-Y-2XFS SCO/.../...

The cable sheath is made out of PVC. Make sure to use appropriate UV protection.



1180386571

Manufacturer: Murr

Type: 7000-40721-..

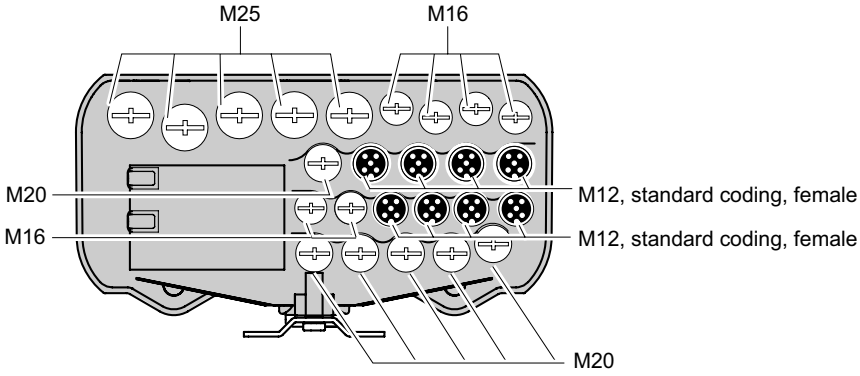
5.4.2 Variants

The following variants of the hybrid ABOX are available for MOVIFIT®-SC (MTS):

- MTA11A-503-S4**2**.-...-00:
  - Optional switch disconnector

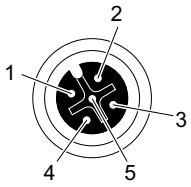
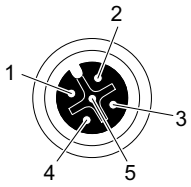
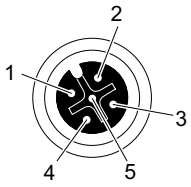
The following figure shows the screw connections and plug connectors of the hybrid ABOX:

PROFIBUS	MTA11A-503-S4.**1**-...-00
PROFINET	MTA11A-503-S4.**3**-...-00
EtherNet/IP	MTA11A-503-S4.**3**-...-00
Modbus/TCP	MTA11A-503-S4.**3**-...-00



915317771

5.4.3 I/O pin assignment (X21-X28)

I/Os					
12 DI + 4 DI/O	**Pin**	**X21**	**X22**	**X23 (Encoder 1 connection)**	**X24 (Encoder 2 connection)**
M12 plug connector, standard coding, female 	**1**	VO24-I	VO24-I	VO24-II	VO24-II
	2	DI01	DI03	DI05 Encoder track B	DI07 Encoder track B
	3	0V24_C	0V24_C	0V24_C	0V24_C
	4	DI00	DI02	DI04 Encoder track A	DI06 Encoder track A
	5	n.c.	n.c.	n.c.	n.c.
	Pin	**X25 (Encoder 3 connection)**	**X26**	**X27**	**X28**
	1	VO24-III	VO24-III	VO24-IV	VO24-IV
	2	DI09 Encoder track B	DI11	DI13/DO01	DI15/DO03
	3	0V24_C	0V24_C	0V24_S	0V24_S
	4	DI08 Encoder track A	DI10	DI12/DO00	DI14/DO02
	5	n.c.	n.c.	n.c.	n.c.
6 DI + 2 DI/O	**Pin**	**X21**	**X22**	**X23**	**X24**
M12 plug connector, standard coding, female 	**1**	VO24-I	VO24-I	VO24-II	VO24-II
	2	Res.	Res.	Res.	Res.
	3	0V24_C	0V24_C	0V24_C	0V24_C
	4	DI00	DI01	DI02	DI03
	5	n.c.	n.c.	n.c.	n.c.
	Pin	**X25**	**X26**	**X27**	**X28**
	1	VO24-III	VO24-III	VO24-IV	VO24-IV
	2	Res.	Res.	Res.	Res.
	3	0V24_C	0V24_C	0V24_S	0V24_S
	4	DI04	DI05	DI06/DO00	DI07/DO01
	5	n.c.	n.c.	n.c.	n.c.
4 DI	**Pin**	**X21**	**X22**	**X23 - X28**	
M12 plug connector, standard coding, female 	**1**	VO24	VO24	Res.	
	2	DI101	DI103	Res.	
	3	0V24_C	0V24_C	Res.	
	4	DI100	DI102	Res.	
	5	n.c.	n.c.	Res.	

12 DI + 4 DI/O	**MOVIFIT® versions with 12 DI + 4 DI/O**	
	Function level	**Fieldbus**
	Technology or System	All
	Classic	PROFINET, EtherNet/IP, Modbus/TCP

6 DI + 2 DI/O	**MOVIFIT® versions with 6 DI + 2 DI/O**	
	Function level	**Fieldbus**
	Classic	PROFIBUS or DeviceNet

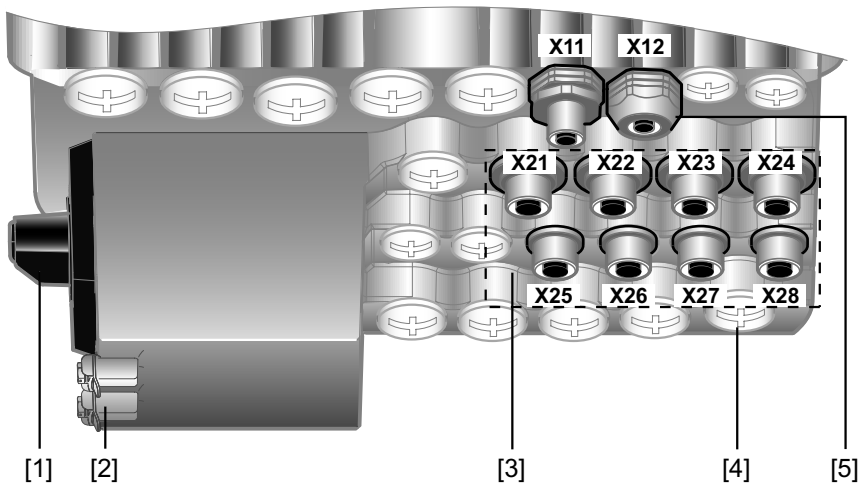
4 DI	**MOVIFIT® versions with 4 DI**	
	Function level	**Fieldbus**
	None	SBus slave

5.5 Hybrid ABOX "MTA...-S52.-...-00"

	TIP
	• The hybrid ABOX is based on the standard ABOX "MTA...-S02.-...-00". Therefore, the following describes only the additional plug connectors in comparison with the standard ABOX. • For a description of the terminals, refer to section "Standard ABOX "MTA...-S02.-...-00"" (see page 39). • Customers cannot use terminal strips X25, X30, or X31 because the described plug connectors are assigned to them.

5.5.1 Description

The following figure depicts the hybrid ABOX with M12 plug connectors for connecting I/Os and bus:



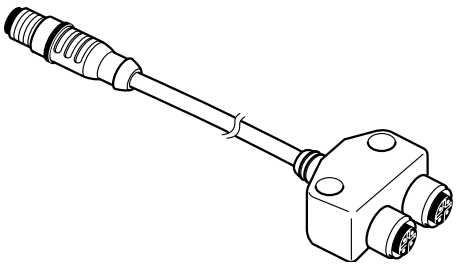
934768139

[1] Maintenance switch (option)
[2] PE connection
[3] M12 plug connector for I/Os
[4] Diagnostics socket (RJ10) under the screw connection
[5] M12 plug connector for the fieldbus connection

Y adapter

Use a Y adapter with an extension for connecting two sensors/actuators to an M12 plug connector.

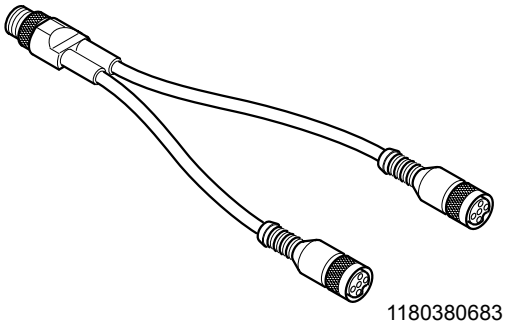
The Y adapter is available from various manufacturers:



915294347

Manufacturer: Escha

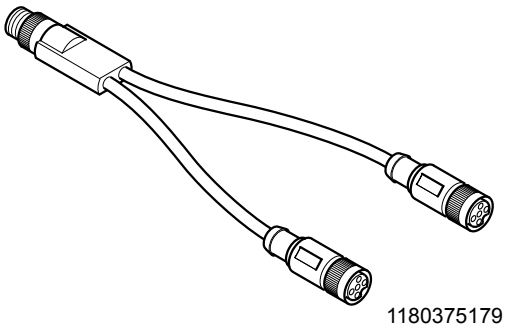
Type: WAS4-0,3-2FKM3/..



1180380683

Manufacturer: Binder

Type: 79 5200 ..

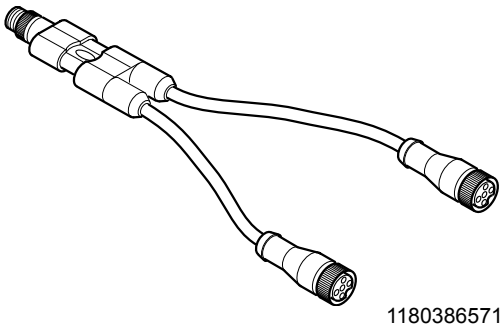


1180375179

Manufacturer: Phoenix Contact

Type: SAC-3P-Y-2XFS SCO/.../...

The cable sheath is made out of PVC. Make sure to use appropriate UV protection.



1180386571

Manufacturer: Murr

Type: 7000-40721-..

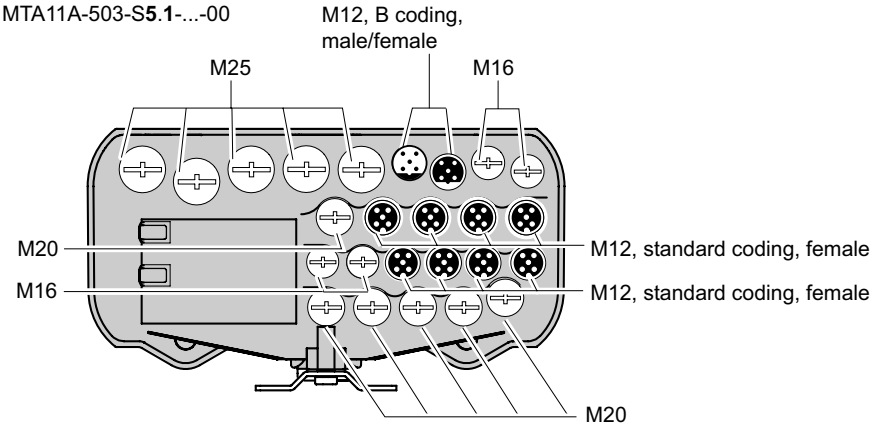
5.5.2 Variants

The following variants of the hybrid ABOX are available for MOVIFIT®-SC (MTS):

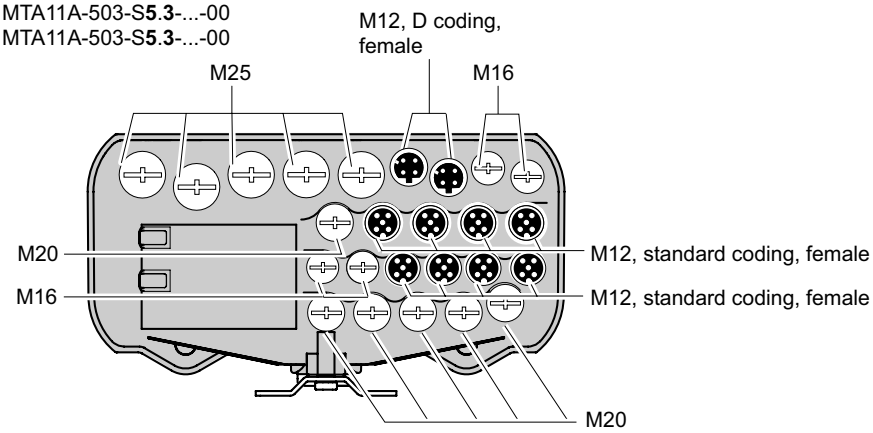
- MTA11A-503-S5**2**.-...-00:
  - Optional switch disconnector

The following figure shows the screw connections and plug connectors of the hybrid ABOX depending on the fieldbus interface:

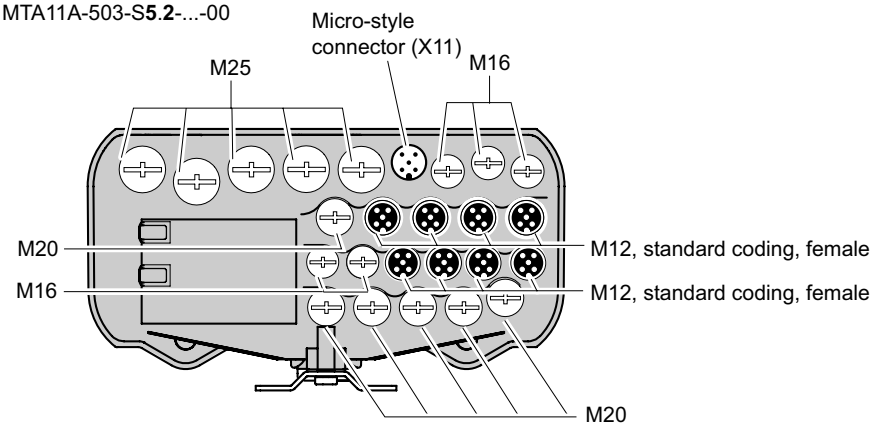
PROFIBUS MTA11A-503-S**5**.**1**-...-00



PROFINET MTA11A-503-S**5**.**3**-...-00
EtherNet/IP MTA11A-503-S**5**.**3**-...-00
Modbus/TCP MTA11A-503-S**5**.**3**-...-00



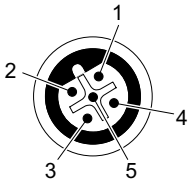
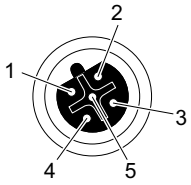
DeviceNet MTA11A-503-S**5**.**2**-...-00



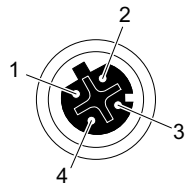
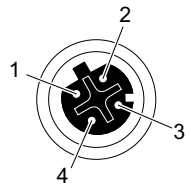
915682827

5.5.3 Pin assignment of fieldbus interface (X11/X12)

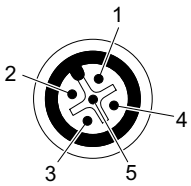
PROFIBUS

X11 (PROFIBUS IN)	Pin	Assignment	X12 (PROFIBUS OUT)	Pin	Assignment
M12 plug connector, B coding, male 	**1**	n.c.	M12 plug connector, B coding, female 	**1**	+5V_PB
	2	A_IN		**2**	A_OUT
	3	n.c.		**3**	0V5_PB
	4	B_IN		**4**	B_OUT
	5	n.c.		**5**	n.c.

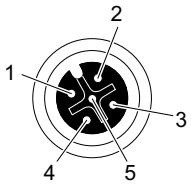
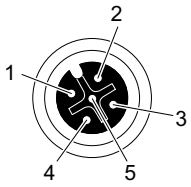
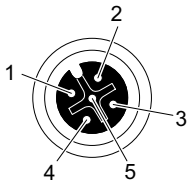
Ethernet (PROFINET, EtherNet/IP, or Modbus/TCP)

X11 (port 1)	Pin	Assignment	X12 (port 2)	Pin	Assignment
M12 plug connector, D coding, female 	**1**	TX+	M12 plug connector, D coding, female 	**1**	TX+
	2	RX+		**2**	RX+
	3	TX-		**3**	TX-
	4	RX-		**4**	RX-

DeviceNet

X11	Pin	Assignment
Micro-style connector, standard coding, male 	**1**	DRAIN
	2	V+
	3	V-
	4	CAND_H
	5	CAND_L

5.5.4 I/O pin assignment (X21-X28)

I/Os					
12 DI + 4 DI/O	**Pin**	**X21**	**X22**	**X23 (Encoder 1 connection)**	**X24 (Encoder 2 connection)**
M12 plug connector, standard coding, female 	**1**	VO24-I	VO24-I	VO24-II	VO24-II
	2	DI01	DI03	DI05 Encoder track B	DI07 Encoder track B
	3	0V24_C	0V24_C	0V24_C	0V24_C
	4	DI00	DI02	DI04 Encoder track A	DI06 Encoder track A
	5	n.c.	n.c.	n.c.	n.c.
	Pin	**X25 (Encoder 3 connection)**	**X26**	**X27**	**X28**
	1	VO24-III	VO24-III	VO24-IV	VO24-IV
	2	DI09 Encoder track B	DI11	DI13/DO01	DI15/DO03
	3	0V24_C	0V24_C	0V24_S	0V24_S
	4	DI08 Encoder track A	DI10	DI12/DO00	DI14/DO02
	5	n.c.	n.c.	n.c.	n.c.
6 DI + 2 DI/O	**Pin**	**X21**	**X22**	**X23**	**X24**
M12 plug connector, standard coding, female 	**1**	VO24-I	VO24-I	VO24-II	VO24-II
	2	Res.	Res.	Res.	Res.
	3	0V24_C	0V24_C	0V24_C	0V24_C
	4	DI00	DI01	DI02	DI03
	5	n.c.	n.c.	n.c.	n.c.
	Pin	**X25**	**X26**	**X27**	**X28**
	1	VO24-III	VO24-III	VO24-IV	VO24-IV
	2	Res.	Res.	Res.	Res.
	3	0V24_C	0V24_C	0V24_S	0V24_S
	4	DI04	DI05	DI06/DO00	DI07/DO01
	5	n.c.	n.c.	n.c.	n.c.
4 DI	**Pin**	**X21**	**X22**	**X23 - X28**	
M12 plug connector, standard coding, female 	**1**	VO24	VO24	Res.	
	2	DI101	DI103	Res.	
	3	0V24_C	0V24_C	Res.	
	4	DI100	DI102	Res.	
	5	n.c.	n.c.	Res.	

12 DI + 4 DI/O	**MOVIFIT® versions with 12 DI + 4 DI/O**	
	Function level	**Fieldbus**
	Technology or System	All
	Classic	PROFINET, EtherNet/IP, Modbus/TCP

6 DI + 2 DI/O	**MOVIFIT® versions with 6 DI + 2 DI/O**	
	Function level	**Fieldbus**
	Classic	PROFIBUS or DeviceNet

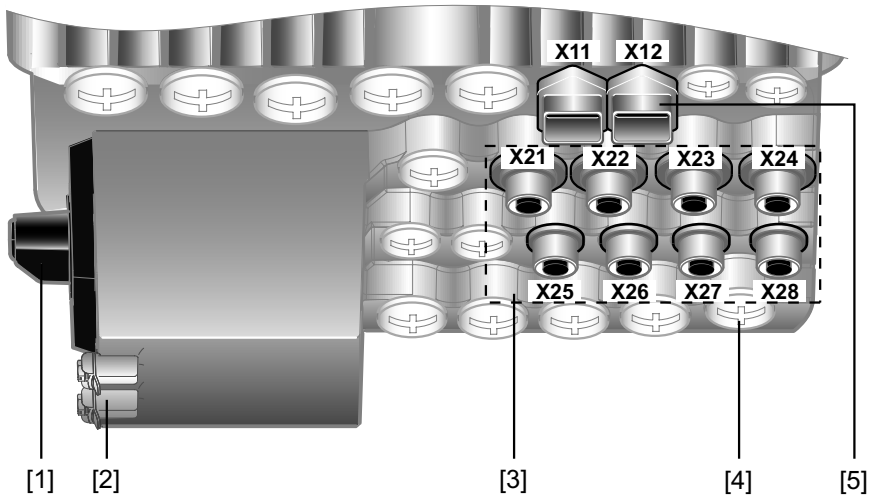
4 DI	**MOVIFIT® versions with 4 DI**	
	Function level	**Fieldbus**
	None	SBus slave

5.6 Hybrid ABOX "MTA...-S62.-...-00"

	TIP
	• The hybrid ABOX is based on the standard ABOX "MTA...-S02.-...-00". Therefore, the following only describes the additional plug connectors in comparison with the ABOX with terminals and cable bushings. • For a description of the terminals, refer to section "Standard ABOX "MTA...-S02.-...00"" (see page 39). • Customers cannot use terminal strips X25, X30, or X31 because the described plug connectors are assigned to them.

5.6.1 Description

The following figure shows the hybrid ABOX with M12 plug connectors for connecting I/Os and the push-pull RJ45 plug connector for Ethernet connection:

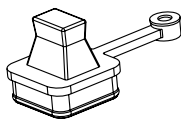


915673995

[1] Maintenance switch (option)
[2] PE connection
[3] M12 plug connector for I/Os
[4] Diagnostics socket (RJ10) under the screw connection
[5] Push-pull RJ45 plug connector for Ethernet connection

	NOTICE
	According to IEC PAS 61076-3-117, push-pull RJ45 sockets may only be used with the appropriate push-pull RJ45 mating connector. Commercially available RJ45 patch cables without push-pull connector housings do not lock into the connectors. Such cables can damage the sockets and are, therefore, not suitable.

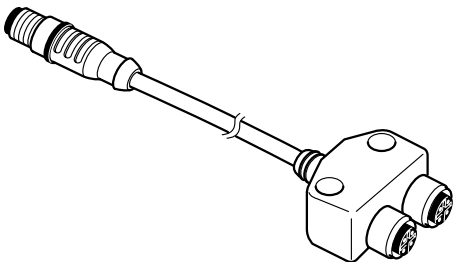
Closing plug, optional

Type	Figure	Contents	Part number
Ethernet closing plug for push-pull RJ45 socket		10 pieces	1822 370 2
		30 pieces	1822 371 0

Y adapter

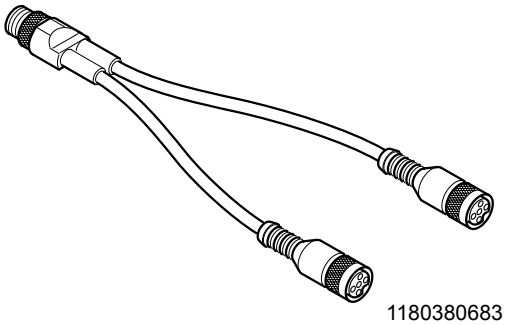
Use a Y adapter with an extension for connecting two sensors/actuators to an M12 plug connector.

The Y adapter is available from various manufacturers:


915294347

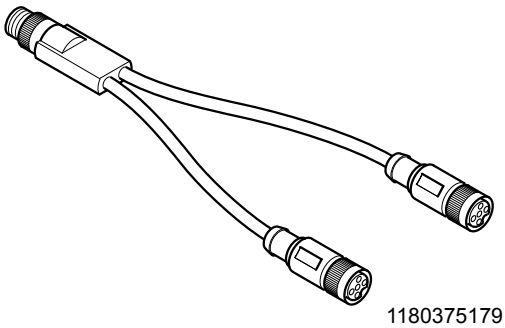
Manufacturer: Escha

Type: WAS4-0,3-2FKM3/..


1180380683

Manufacturer: Binder

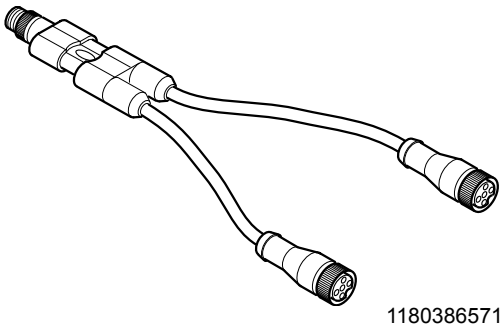
Type: 79 5200 ..


1180375179

Manufacturer: Phoenix Contact

Type: SAC-3P-Y-2XFS SCO/.../...

The cable sheath is made out of PVC. Make sure to use appropriate UV protection.


1180386571

Manufacturer: Murr

Type: 7000-40721-..

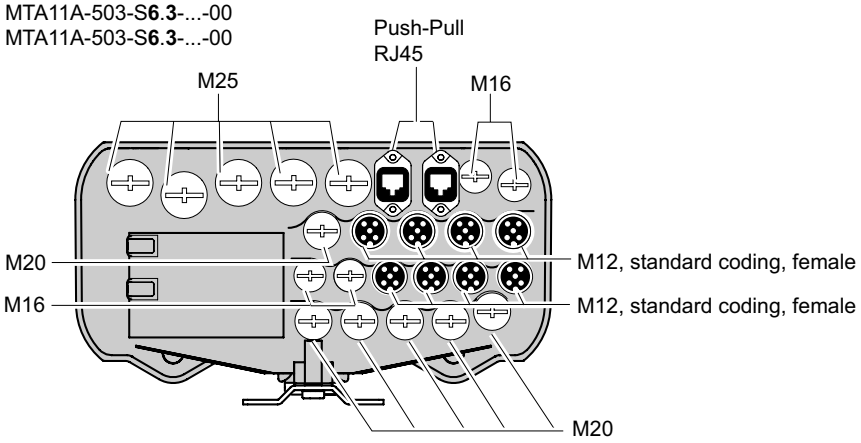
5.6.2 Variants

The following variants of the hybrid ABOX are available for MOVIFIT®-SC (MTS):

- MTA11A-503-S6**2**.-...-00:
  - Optional switch disconnector

The following figure shows the screw connections and plug connectors of the hybrid ABOX:

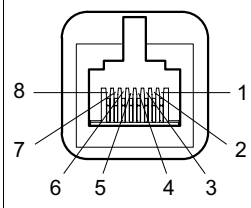
PROFINET MTA11A-503-S**6.3**-...-00
EtherNet/IP MTA11A-503-S**6.3**-...-00
Modbus/TCP MTA11A-503-S**6.3**-...-00

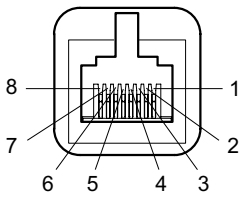


934776075

5.6.3 Pin assignment of fieldbus interface (X11/X12)

Ethernet (PROFINET, EtherNet/IP, or Modbus/TCP)					
X11 (port 1)	**Pin**	**Assignment**	**X12 (port 2)**	**Pin**	**Assignment**
Push-pull RJ45 plug connector	**1**	TX+	Push-pull RJ45 plug connector	**1**	TX+
	2	TX-		**2**	TX-
	3	RX+		**3**	RX+
	4	Res.		**4**	Res.
	5	Res.		**5**	Res.
	6	RX-		**6**	RX-
	7	Res.		**7**	Res.
	8	Res.		**8**	Res.

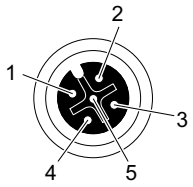
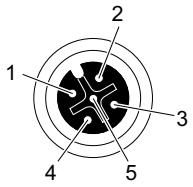
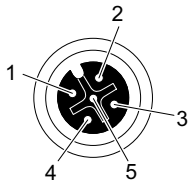




NOTICE

According to IEC PAS 61076-3-117, push-pull RJ45 sockets may only be used with the appropriate push-pull RJ45 mating connector. Commercially available RJ45 patch cables without push-pull connector housings do not lock into the connectors. Such cables can damage the sockets and are, therefore, not suitable.

5.6.4 I/O pin assignment (X21-X28)

I/Os					
12 DI + 4 DI/O	**Pin**	**X21**	**X22**	**X23 (Encoder 1 connection)**	**X24 (Encoder 2 connection)**
M12 plug connector, standard coding, female 	**1**	VO24-I	VO24-I	VO24-II	VO24-II
	2	DI01	DI03	DI05 Encoder track B	DI07 Encoder track B
	3	0V24_C	0V24_C	0V24_C	0V24_C
	4	DI00	DI02	DI04 Encoder track A	DI06 Encoder track A
	5	n.c.	n.c.	n.c.	n.c.
	Pin	**X25 (Encoder 3 connection)**	**X26**	**X27**	**X28**
	1	VO24-III	VO24-III	VO24-IV	VO24-IV
	2	DI09 Encoder track B	DI11	DI13/DO01	DI15/DO03
	3	0V24_C	0V24_C	0V24_S	0V24_S
	4	DI08 Encoder track A	DI10	DI12/DO00	DI14/DO02
	5	n.c.	n.c.	n.c.	n.c.
6 DI + 2 DI/O	**Pin**	**X21**	**X22**	**X23**	**X24**
M12 plug connector, standard coding, female 	**1**	VO24-I	VO24-I	VO24-II	VO24-II
	2	Res.	Res.	Res.	Res.
	3	0V24_C	0V24_C	0V24_C	0V24_C
	4	DI00	DI01	DI02	DI03
	5	n.c.	n.c.	n.c.	n.c.
	Pin	**X25**	**X26**	**X27**	**X28**
	1	VO24-III	VO24-III	VO24-IV	VO24-IV
	2	Res.	Res.	Res.	Res.
	3	0V24_C	0V24_C	0V24_S	0V24_S
	4	DI04	DI05	DI06/DO00	DI07/DO01
	5	n.c.	n.c.	n.c.	n.c.
4 DI	**Pin**	**X21**	**X22**	**X23 - X28**	
M12 plug connector, standard coding, female 	**1**	VO24	VO24	Res.	
	2	DI101	DI103	Res.	
	3	0V24_C	0V24_C	Res.	
	4	DI100	DI102	Res.	
	5	n.c.	n.c.	Res.	

12 DI + 4 DI/O	**MOVIFIT® versions with 12 DI + 4 DI/O**	
	Function level	**Fieldbus**
	Technology or System	All
	Classic	PROFINET, EtherNet/IP, Modbus/TCP

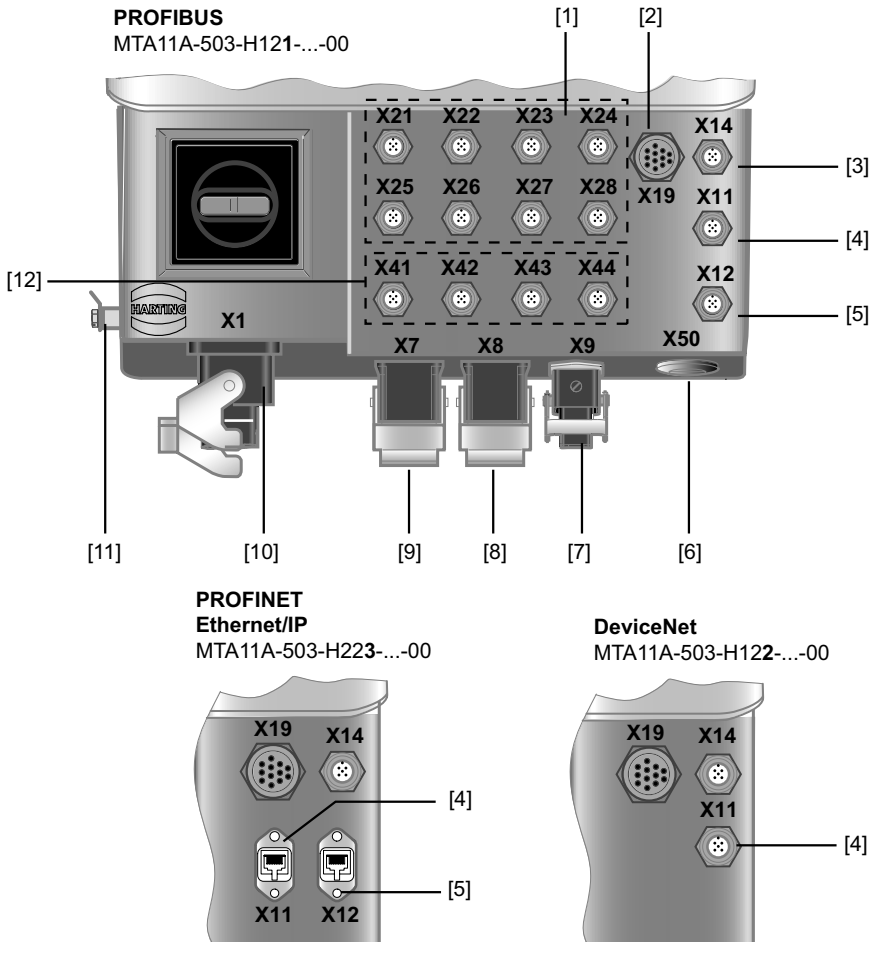
6 DI + 2 DI/O	**MOVIFIT® versions with 6 DI + 2 DI/O**	
	Function level	**Fieldbus**
	Classic	PROFIBUS or DeviceNet

4 DI	**MOVIFIT® versions with 4 DI**	
	Function level	**Fieldbus**
	None	SBus slave

5.7 Han-Modular®-ABOX "MTA...-H12.-...-00", "MTA...-H22.-...-00"

5.7.1 Description

The following figure shows the Han-Modular®-ABOX for MOVIFIT®-SC depending on the fieldbus interface:



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[1] M12 plug connector for I/Os
[2] M23 plug connector (12-pin) for I/O extension box
[3] SBus (CAN)
[4] In conjunction with PROFIBUS: PROFIBUS IN
With PROFINET + EtherNet/IP + Modbus/TCP: Ethernet port 1
With DeviceNet: wired to X11 plug connector (micro-style connector)
[5] With PROFIBUS: PROFIBUS OUT or terminating resistor
With PROFINET + EtherNet/IP + Modbus/TCP: Ethernet port 2
[6] Diagnostics socket (RJ10) under the screw connection
[7] Han-Modular® plug connector for connecting an external braking resistor
[8] Han-Modular® plug connector for connecting motor 2
[9] Han-Modular® plug connector for connecting motor 1
[10] Han-Modular® plug connector for power connection (power distribution with T adapter)
[11] PE connection
[12] M12 plug connector for optional I/Os

NOTICE

According to IEC PAS 61076-3-117, push-pull RJ45 sockets may only be used with the appropriate push-pull RJ45 mating connector. Commercially available RJ45 patch cables without push-pull connector housings do not lock into the connectors. Such cables can damage the sockets and are, therefore, not suitable.

5.7.2 Variants

The following variants of the Han-Modular®-ABOX are available for MOVIFIT®-SC (MTS):

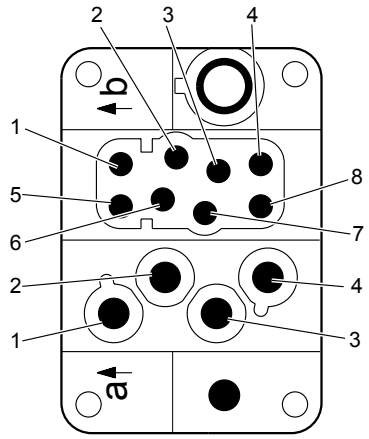
- MTA11A-503-H2**2.**-...-00, MTA11A-503-H1**2.**-...-00:
  - Switch disconnector integrated as standard

5.7.3 Power bus pin assignment (X1)

Power bus

X1

Han-Modular® with
2 module pin inserts, male



Pin	Assignment
Module a (HAN® CC Protected)	
a.1	Mains phase L1
a.2	Mains phase L2
a.3	Mains phase L3
a.4	n.c.
Module b (HAN® EE)	
b.1	+24V_C
b.2	n.c.
b.3	n.c.
b.4	+24V_S
b.5	0V24_C
b.6	n.c.
b.7	n.c.
b.8	0V24_S
Grounding pins	
PE	PE/housing

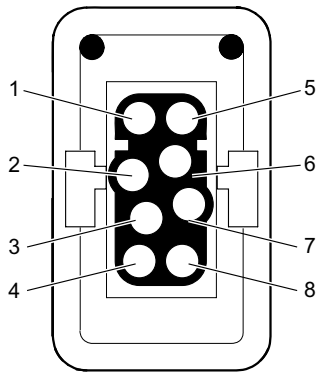
⚠ DANGER

The maintenance switch disconnects only the integrated frequency inverter from the mains. Voltage is still present on the X1 plug connector of the MOVIFIT®.

Severe or fatal injuries from electric shock

- Switch off the power to the MOVIFIT® using a suitable external disconnecting device before touching the plug connector contacts.

5.7.4 Motor pin assignment (X8/X9)

Motor	Pin	X8	X9
Han-Modular® Compact with HAN® EE module, socket insert, female 	**1**	TF+_M1	TF+_M2
	2	13_M1	13_M2
	3	U_M1	U_M2
	4	W_M1	W_M2
	5	TF-_M1	TF-_M2
	6	14_M1	14_M2
	7	15_M1	15_M2
	8	V_M1	V_M2
	PE	PE_M1	PE_M2

⚠ CAUTION

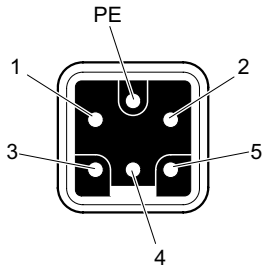
Important: For operation with one motor, use plug connector X8.

- **Do not** insert any plugs in the X9 plug connector.

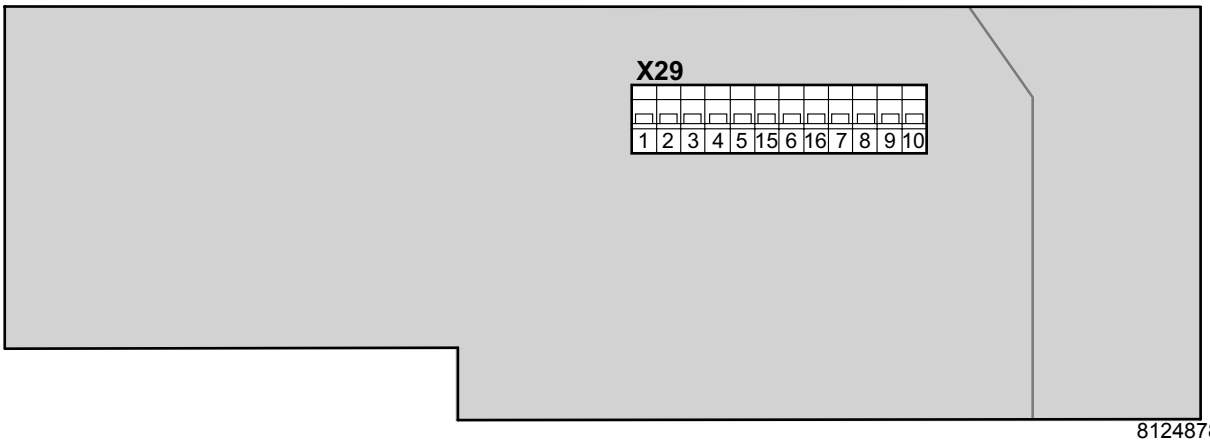
TIP

To connect MOVIFIT® and the motor, SEW-EURODRIVE recommends using the shielded and pre-fabricated SEW hybrid cables with Harting plug connectors specifically designed for this purpose, see section "Hybrid cables" (see page 87).

5.7.5 Pin assignment of braking resistor (X6)

External braking resistor	Pin	X6
HAN® Q5/0, socket insert, female 	**1**	n.c.
	2	n.c.
	3	+R
	4	n.c.
	5	-R
	PE	PE/housing

5.7.6 Terminal assignment for distributor terminal 24 V to option card (X29)



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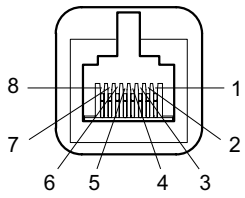
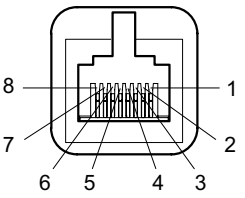
Distributor terminal 24 V (for distributing the supply voltage(s) to the option card)			
No.		**Name**	**Function**
X29	**1**	+24V_C	+24 V supply – continuous voltage (jumpered with X20/2)
	2	0V24_C	0V24 reference potential – continuous voltage (jumpered with X20/3)
	3	+24V_S	+24 V supply – switched (jumpered with X20/5)
	4	0V24_S	0V24 reference potential – switched (jumpered with X20/6)
	5	Res.	Reserved
	15	Res.	
	6	Res.	Reserved
	16	Res.	
	7	+24V_O	+24 V supply for option card, supply
	8	0V24_O	0V24 reference potential for option card, supply
	9	Res.	Reserved
	10	Res.	Reserved

5.7.7 Pin assignment of fieldbus interface

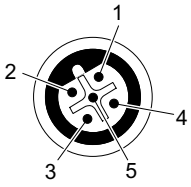
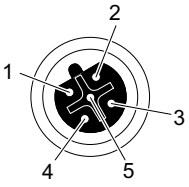
Ethernet (PROFINET, EtherNet/IP, or Modbus/TCP)

X11 (port 1)	Pin	Assignment	X12 (port 2)	Pin	Assignment
Push-pull RJ45 plug connector 	**1**	TX+	Push-pull RJ45 plug connector 	**1**	TX+
	2	TX-		**2**	TX-
	3	RX+		**3**	RX+
	4	Res.		**4**	Res.
	5	Res.		**5**	Res.
	6	RX-		**6**	RX-
	7	Res.		**7**	Res.
	8	Res.		**8**	Res.

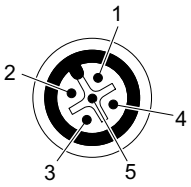
NOTICE

According to IEC PAS 61076-3-117, push-pull RJ45 sockets may only be used with the appropriate push-pull RJ45 mating connector. Commercially available RJ45 patch cables without push-pull connector housings do not lock into the connectors. Such cables can damage the sockets and are, therefore, not suitable.

PROFIBUS

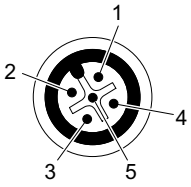
X11 (PROFIBUS IN)	Pin	Assignment	X12 (PROFIBUS OUT)	Pin	Assignment
M12 plug connector, B coding, male 	**1**	n.c.	M12 plug connector, B coding, female 	**1**	+5V_PB
	2	A_IN		**2**	A_OUT
	3	n.c.		**3**	0V5_PB
	4	B_IN		**4**	B_OUT
	5	FE		**5**	FE

DeviceNet

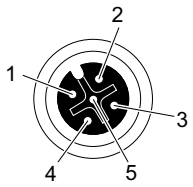
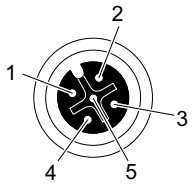
X11	Pin	Assignment
Micro-style connector, standard coding, male 	**1**	DRAIN
	2	V+
	3	V-
	4	CAND_H
	5	CAND_L

SBus (CAN)

Can only be used with function levels "Technology" or "System"

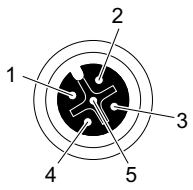
X14	Pin	Assignment
M12 plug connector, standard coding, male 	**1**	FE
	2	n.c.
	3	0V5-II
	4	CAN1_H
	5	CAN1_L

5.7.8 I/O pin assignment (X21-X28/X19/X41-X44)

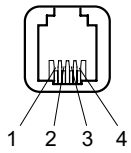
I/Os					
12 DI + 4 DI/O	**Pin**	**X21**	**X22**	**X23 (Encoder 1 connection)**	**X24 (Encoder 2 connection)**
M12 plug connector, standard coding, female 	**1**	VO24-I	VO24-I	VO24-II	VO24-II
	2	DI01	DI03	DI05 Encoder track B	DI07 Encoder track B
	3	0V24_C	0V24_C	0V24_C	0V24_C
	4	DI00	DI02	DI04 Encoder track A	DI06 Encoder track A
	5	FE	FE	FE	FE
	Pin	**X25 (Encoder 3 connection)**	**X26**	**X27**	**X28**
	1	VO24-III	VO24-II	VO24-IV	VO24-IV
	2	DI09 Encoder track B	DI11	DI13/DO01	DI15/DO03
	3	0V24_C	0V24_C	0V24_S	0V24_S
	4	DI08 Encoder track A	DI10	DI12/DO00	DI14/DO02
	5	FE	FE	FE	FE
6 DI + 2 DI/O	**Pin**	**X21**	**X22**	**X23**	**X24**
M12 plug connector, standard coding, female 	**1**	VO24-I	VO24-I	VO24-I	VO24-II
	2	Res.	Res.	Res.	Res.
	3	0V24_C	0V24_C	0V24_C	0V24_C
	4	DI00	DI01	DI02	DI03
	5	FE	FE	FE	FE
	Pin	**X25**	**X26**	**X27**	**X28**
	1	VO24-II	VO24-II	VO24-IV	VO24-IV
	2	Res.	Res.	Res.	Res.
	3	0V24_C	0V24_C	0V24_S	0V24_S
	4	DI04	DI05	DI06/DO00	DI07/DO01
	5	FE	FE	FE	FE

12 DI + 4 DI/O	**MOVIFIT® versions with 12 DI + 4 DI/O**	
	Function level	**Fieldbus**
	Technology or System	All
	Classic	PROFINET, EtherNet/IP, Modbus/TCP

6 DI + 2 DI/O	**MOVIFIT® versions with 6 DI + 2 DI/O**	
	Function level	**Fieldbus**
	Classic	PROFIBUS or DeviceNet

Option I/Os with PROFIsafe option S11					
	Pin	**X41**	**X42**	**X43**	**X44**
M12 plug connector, standard coding, female 	**1**	Reserved	Reserved	Reserved	Reserved
	2	Reserved	Reserved	Reserved	Reserved
	3	Reserved	Reserved	Reserved	Reserved
	4	Reserved	Reserved	Reserved	Reserved
	5	Reserved	Reserved	Reserved	Reserved

5.7.9 Pin assignment of diagnostic interface

Diagnostic interface		
X50	**Pin**	**Assignment**
Diagnostic interface X50 (RJ10 socket) 	**1**	+5 V
	2	RS+
	3	RS-
	4	0V5

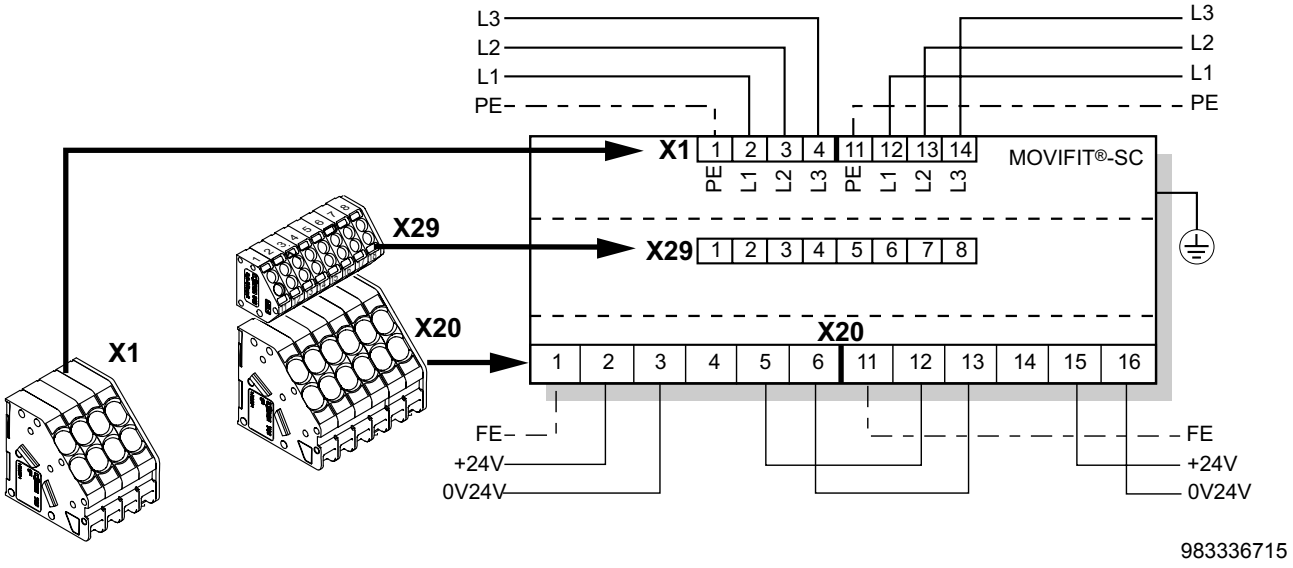
5.8 Power bus connection examples

5.8.1 Power bus in conjunction with terminal connection

	TIP
	The examples are valid for the following connection boxes: • Standard ABOX "MTA...-S02.-...-00" • Hybrid ABOX "MTA...-S42.-...-00" • Hybrid ABOX "MTA...-S52.-...-00" • Hybrid ABOX "MTA...-S62.-...-00"

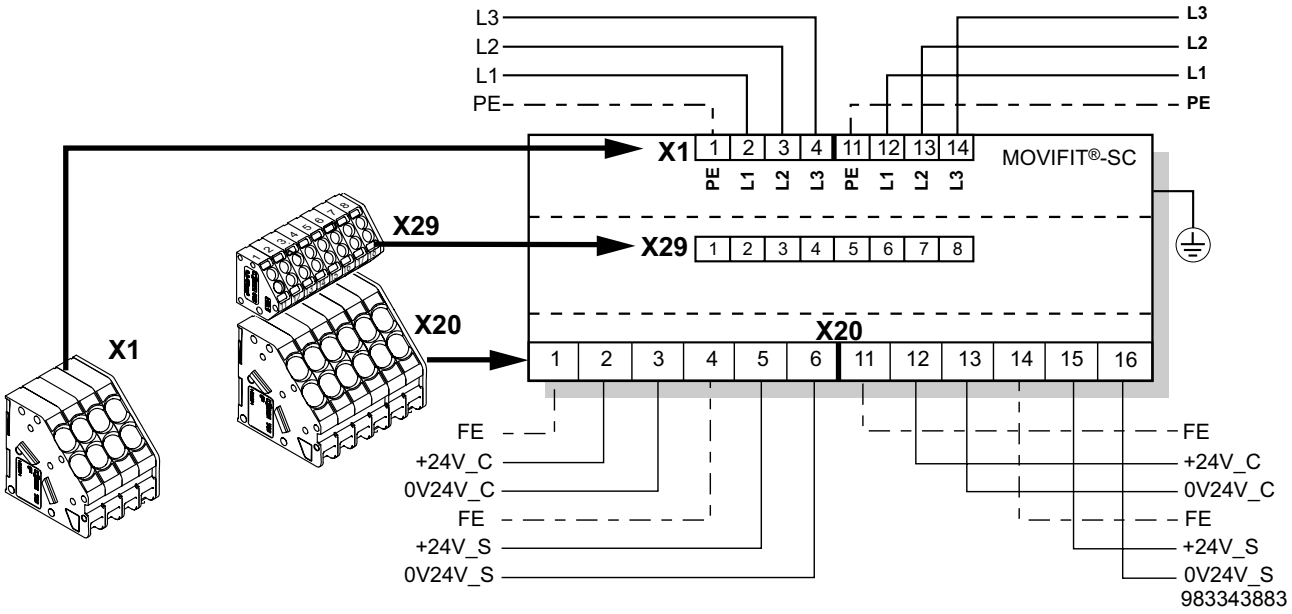
Connection example with a common 24 V voltage circuit

The following figure shows a connection example for the power bus with a common 24 V voltage circuit for the sensor/actuator supply.



Connection example with two separate 24 V voltage circuits

The following figure depicts a basic connection example for the power bus with two separate 24 V voltage circuits for sensor/actuator supply:

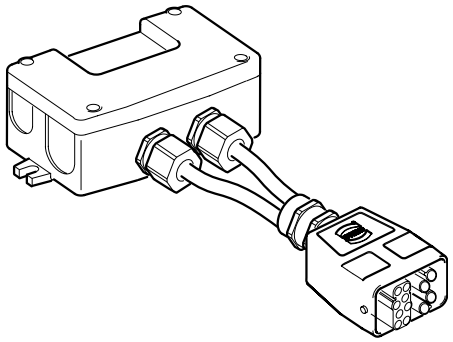


5.8.2 Power bus with Han-Modular® plug connector

	TIP
	This example applies for the following connection boxes: • Han-Modular®-ABOX "MTA...-H12.-...-00" • Han-Modular®-ABOX "MTA...-H22.-...-00"

Power distribution and line protection

- SEW-EURODRIVE recommends using HARTING Power S products for power bus project planning.
- Two lines of max. 6 mm^2 can be routed in the AC 400 V 50/60 Hz and DC 24 V supply cable.
- The spur lines leading to MOVIFIT® have a cross section of 4 mm^2 and are a maximum of 1.5 m long.
- The Han Power S distributor is available from Harting (part number 6104 202 1069).



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- Supply sensor, group IV (24V_S)

  In the connector of the Han Power S distributor mentioned above (part number 6104 202 1069), the 24V_S supply voltage of sensor supply group IV is jumpered with 24V_C continuous voltage.

Accessories:

Harting provides the following accessories for the Han Power S distributor.

Type	Cable diameter	Part number at Harting
Bushing seal for small entry	7-10 mm	0912 000 9965
	10-13 mm	0912 000 9966
	13-16 mm	0912 000 9967
Filler plug for small entry		0912 000 9968
Bushing seal for large entry	7-10 mm	0912 000 9969
	10-13 mm	0912 000 9970
	13-16 mm	0912 000 9971
	16-19 mm	0912 000 9972
	19-22 mm	0912 000 9973
Filler plug for large entry		0912 000 9974

5.9 Connection examples for fieldbus systems

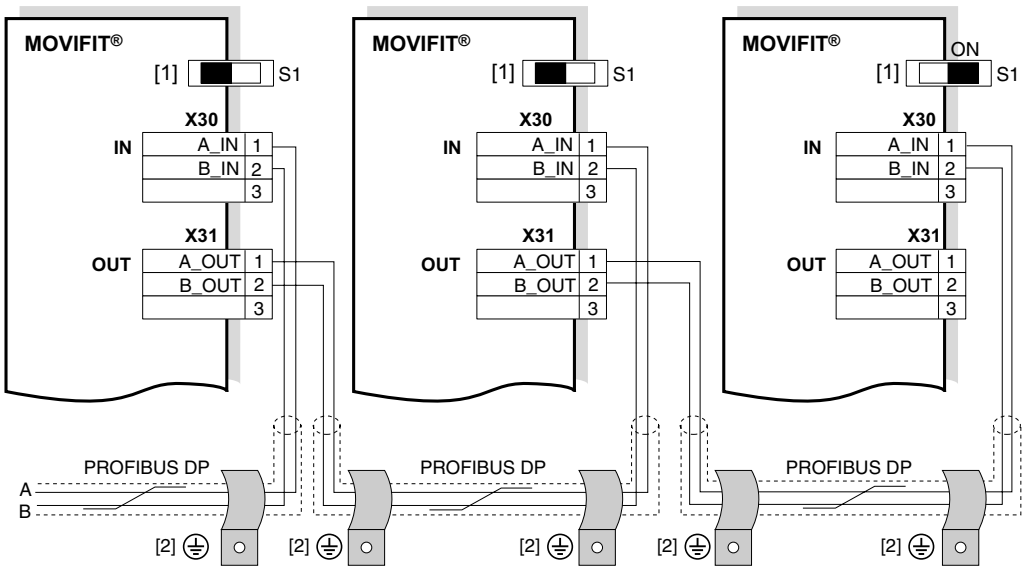
5.9.1 PROFIBUS

Via terminals

	TIP
	The example applies for the following connection box: • Standard ABOX "MTA...-S02.-...-00" • Hybrid ABOX "MTA...-S42.-...-00"

The following figure shows the PROFIBUS connection via terminals:

- If MOVIFIT® is located at the end of a PROFIBUS segment, it can only be connected to the PROFIBUS mains using the incoming PROFIBUS line.
- To prevent malfunctions in the bus system due to reflections, etc., the PROFIBUS segment must be terminated at the first and last physical stations with bus terminating resistors.
- The bus terminating resistors are already installed in the MOVIFIT®-ABOX and they can be activated using the S1 switch.



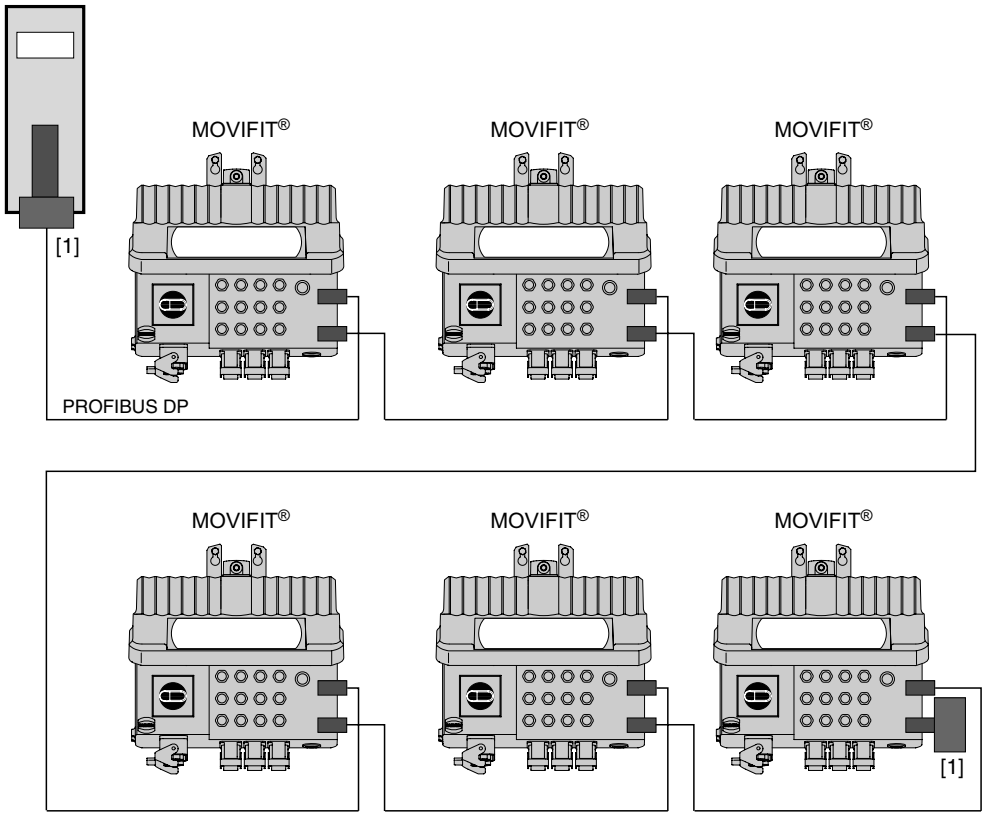
[1] DIP switch S1 for bus termination
[2] Shield plate, see section "Connecting the PROFIBUS line" (see page 43)

Via M12 plug connectors

	TIP
	The example applies for the following connection boxes: • Hybrid ABOX "MTA...-S52.-...-00" • Han-Modular®-ABOX "MTA...-H12.-...-00"

The following figure depicts the basic connection topology for PROFIBUS using M12 plug connectors (the example shows a Han-Modular®-ABOX):

- The connection boxes have M12 plug connectors for connection to the PROFIBUS. They comply with the recommendations of PROFIBUS directive no. 2.141 "Connection technology for PROFIBUS".
- To prevent malfunctions in the bus system due to reflections, etc., the PROFIBUS segment must be terminated at the first and last physical stations with bus terminating resistors.
- A plug-in bus terminator (M12) must be used for the last station in place of the outgoing bus connection.



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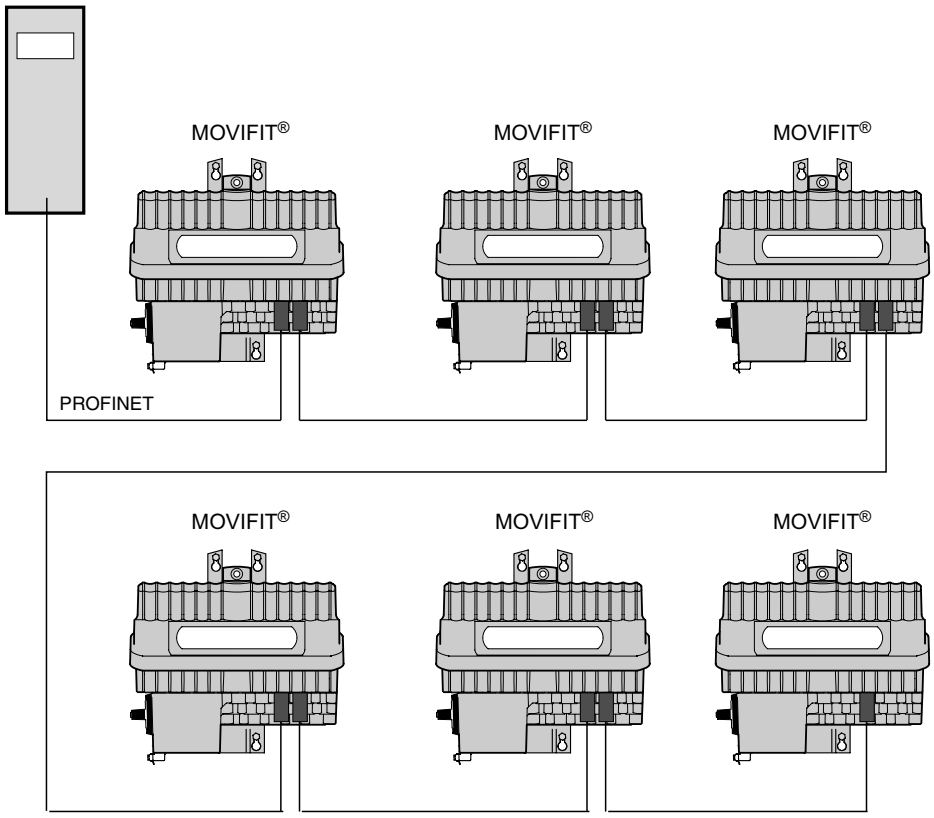
[1] Bus terminating resistor

5.9.2 PROFINET, EtherNet/IP

	TIP
	The example applies for the following connection boxes: • Standard ABOX "MTA...-S02.-...-00" • Hybrid ABOX "MTA...-S42.-...-00" • Hybrid ABOX "MTA...-S52.-...-00" • Hybrid ABOX "MTA...-S62.-...-00" • Han-Modular®-ABOX "MTA...-H22.-...-00"

The following figure shows the basic connection topology for PROFINET using RJ-45 or AIDA plug connectors (the example depicts a hybrid ABOX):



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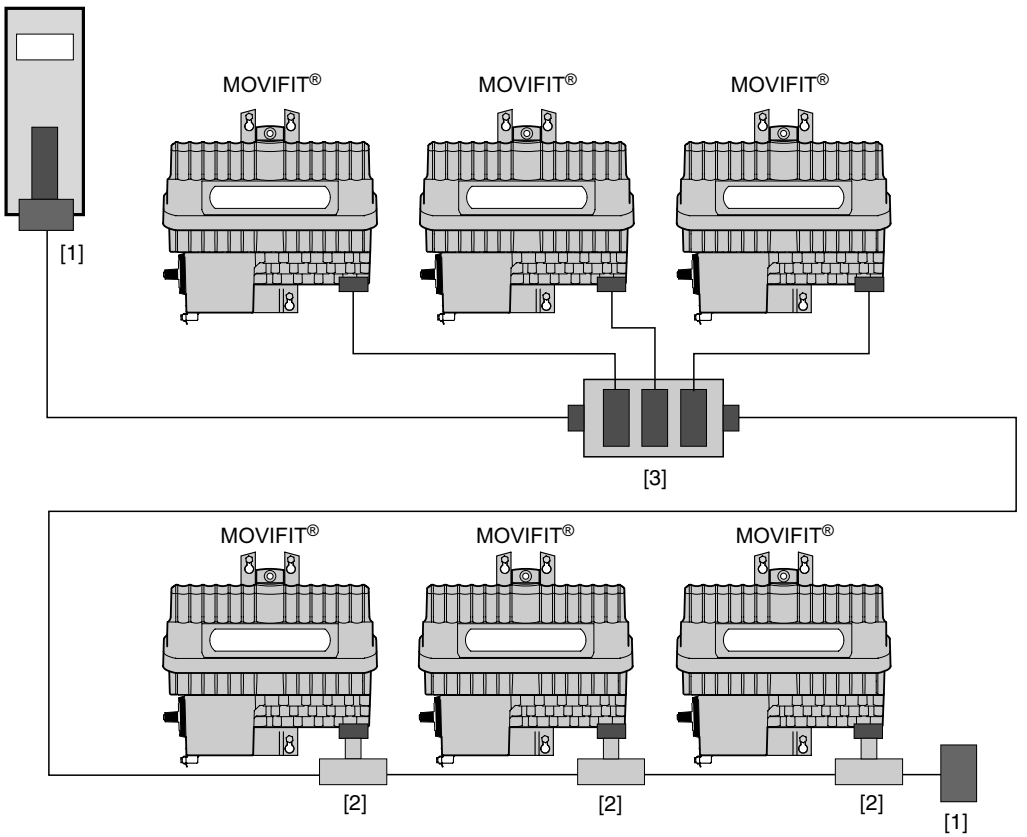
5.9.3 DeviceNet

	TIP
	The example applies for the following connection boxes: • Standard ABOX "MTA...-S02.-...-00" • Hybrid ABOX "MTA...-S52.-...-00" • Han-Modular®-ABOX "MTA...-H12.-...-00"

The following figure shows the basic connection topology for DeviceNet using a micro-style connector (the example depicts an ABOX with terminals and cable bushings):

- The connection can be made via a multiport or T connector. Observe wiring instructions in accordance with DeviceNet specification 2.0.
- The DeviceNet segment must be terminated using bus terminating resistors at the first and last physical station to prevent malfunctions in the bus system due to reflections, etc.
- Use external bus terminating resistors.



[1] Bus terminating resistor 120 Ω
[2] T connector
[3] Multiport

5.10 Encoder connection

5.10.1 Connecting the NV26 proximity sensor

Properties

The NV26 proximity sensor offers the following features:

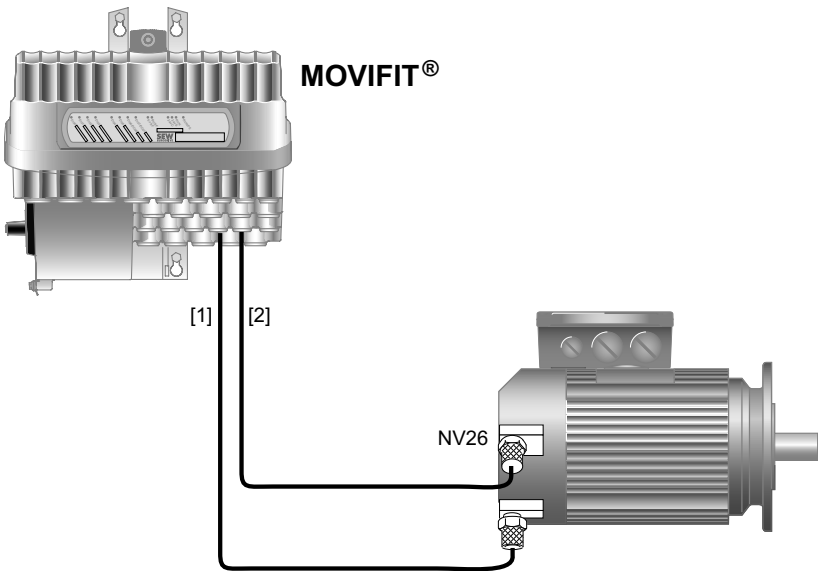
- 2 sensors with 6 pulses/revolution
- 24 increments/revolution with 4-fold evaluation
- Encoder monitoring and evaluation is possible with MOVIFIT® function level "Technology".

There must be a 45° angle between the sensors.

Installation

- Use shielded cables to connect the NV26 proximity sensor to the matching encoder inputs of MOVIFIT®.
  - For standard ABOX, see section "Fieldbus/option-independent terminal assignment", X25 terminal (see page 45)
  - For hybrid ABOX or Han-Modular®-ABOX, see section "I/O pin assignment".

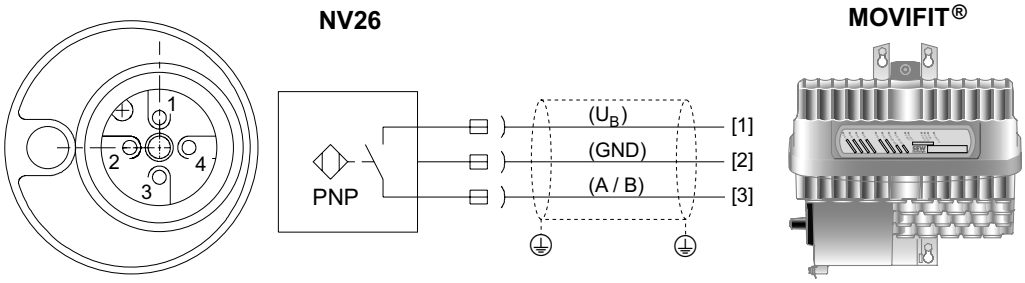
    (see page 59), (see page 64), (see page 68), (see page 74)



940059275

[1] Encoder input MOVIFIT® track B
[2] Encoder input MOVIFIT® track A

Wiring diagram



940197899

[1] [1] +24 V supply voltage
[2] [2] 0V24 reference potential
[3] [3] Encoder input MOVIFIT® track A or track B

5.10.2 Connecting the incremental encoder ES16

Properties

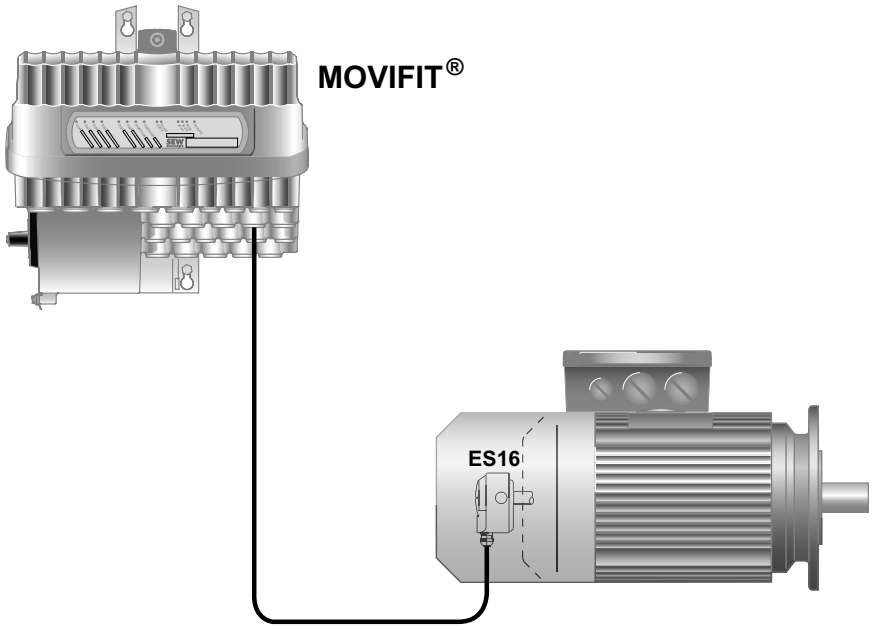
The ES 16 incremental encoder offers the following features:

- 6 pulses/revolution for each track
- 24 increments/revolution with 4-fold evaluation
- Encoder monitoring and evaluation is possible with MOVIFIT® function level "Technology".

Installation

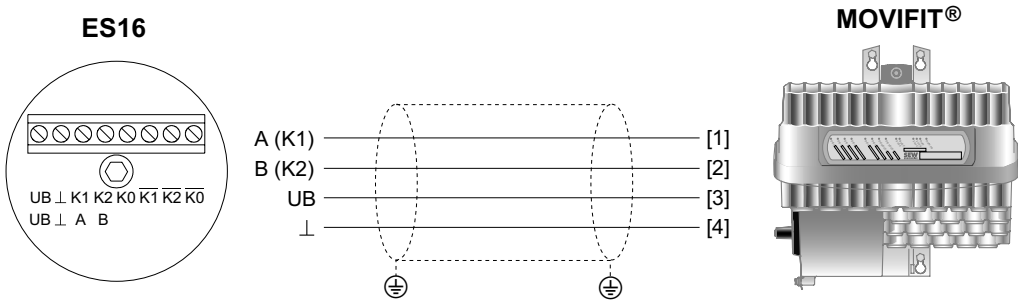
- Use a shielded cable to connect the ES16 incremental encoder to the matching encoder inputs of MOVIFIT®.
  - For standard ABOX, see section "Fieldbus/option-independent terminal assignment", X25 terminal (see page 45)
  - For hybrid ABOX or Han-Modular®-ABOX, see section "I/O pin assignment".

    (see page 59), (see page 64), (see page 68), (see page 74)



940193803

Wiring diagram



940061195

[1] Encoder input MOVIFIT® track A
[2] Encoder input MOVIFIT® track B
[3] +24 V supply voltage
[4] 0V24 reference potential

5.10.3 Connection of incremental encoder EI7.

Properties

The EI7. incremental encoder offers the following features:

- HTL or sin/cos interface (MOVIFIT® does **not** evaluate sin/cos signals)

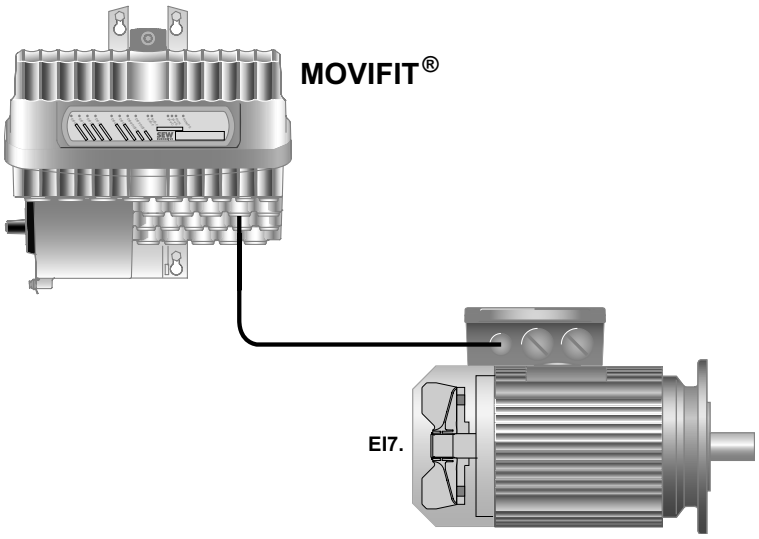
EI71:	1 pulse/revolution	=> 4 increments/revolution[1)]
EI72:	2 pulses/revolution	=> 8 increments/revolution[1)]
EI76:	6 pulses/revolution	=> 24 increments/revolution[1)]
EI7C:	24 pulses/revolution	=> 96 increments/revolution[1)]

1) With 4-fold evaluation

- Encoder monitoring and evaluation is possible with MOVIFIT® function level "Technology".

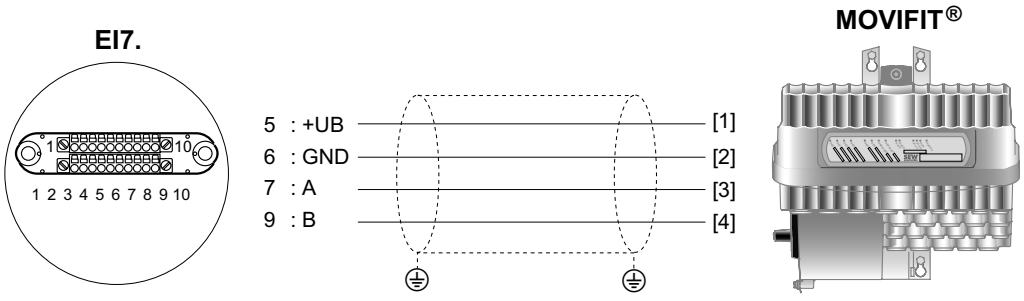
Installation

- Use a shielded cable to connect the EI7. incremental encoder to the matching encoder inputs of MOVIFIT®.
  - For standard ABOX, see section "Fieldbus/option-independent terminal assignment", X25 terminal (see page 45)
  - For hybrid ABOX or Han-Modular®-ABOX, see section "I/O pin assignment". (see page 59), (see page 64), (see page 68), (see page 74)



995367179

Wiring diagram



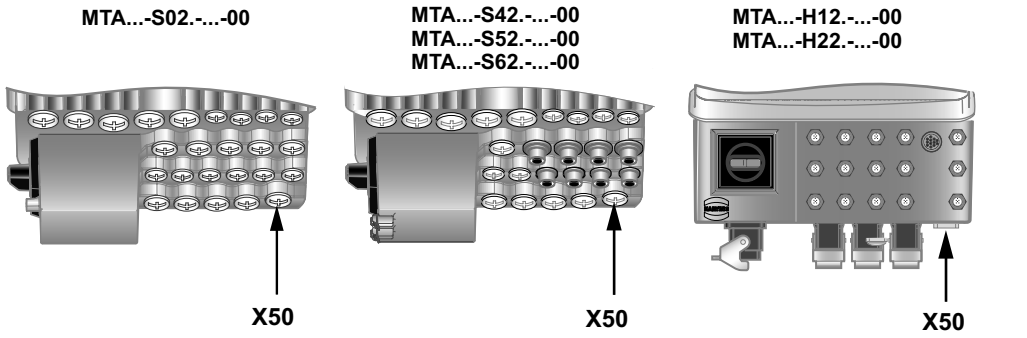
991622027

[1] +24 V supply voltage
[2] 0V24 reference potential
[3] Encoder input MOVIFIT® track A
[4] Encoder input MOVIFIT® track B

5.11 PC connection

5.11.1 Diagnostic interface

MOVIFIT® units have an X50 diagnostic interface (RJ10 plug connector) for startup, parameter setting, and servicing.

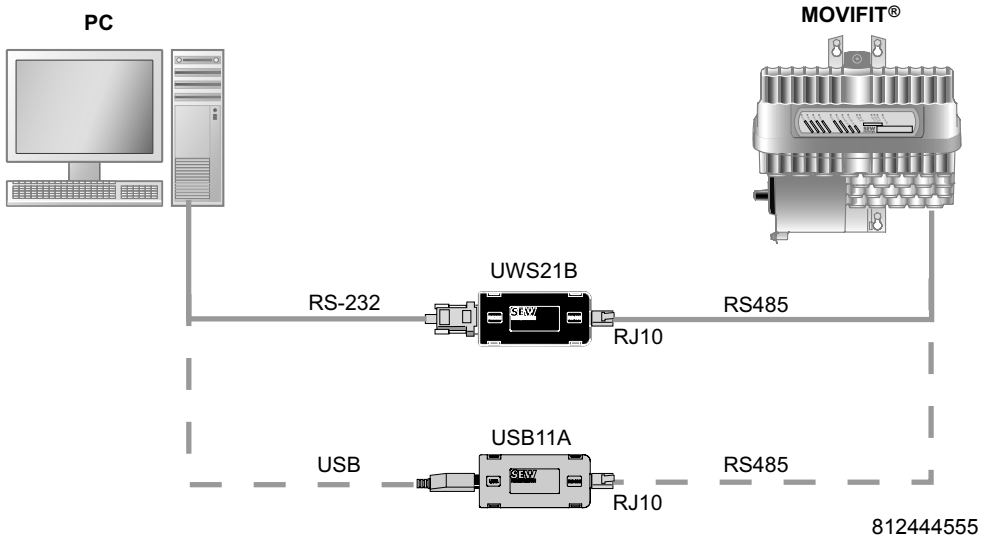


	TIP
	Depending on the function level used, different functions are available. These are described in the corresponding manuals. • Manual for MOVIFIT® function level "Classic..." • Manual for MOVIFIT® function level "Technology..." • Manual for MOVIFIT® function level "System"

5.11.2 Interface adapter

The diagnostic interface can be connected to a PC using one of the following options:

- UWS21B with serial interface RS-232, part number 1 820 456 2
- USB11A with USB interface, part number 0 824 831 1



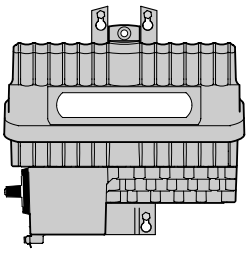
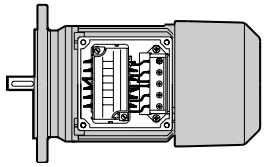
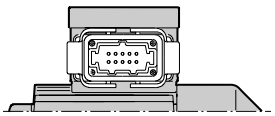
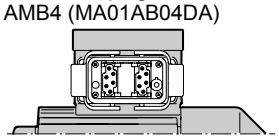
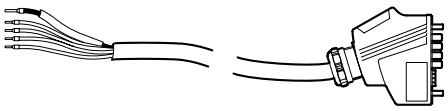
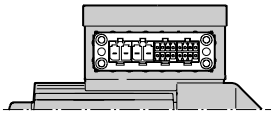
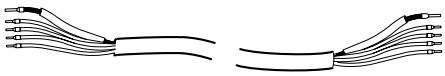
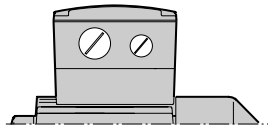
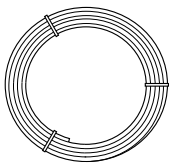
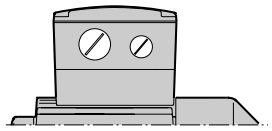
Scope of delivery:

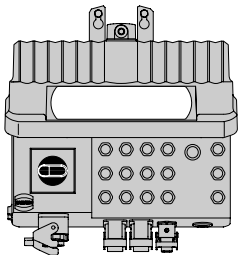
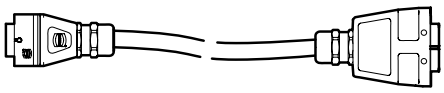
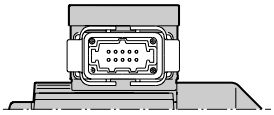
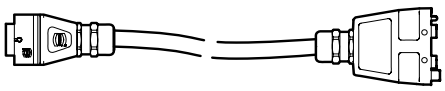
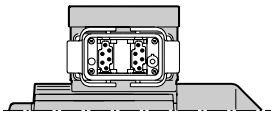
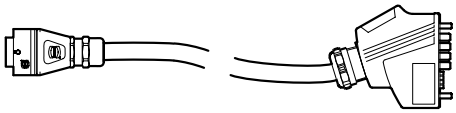
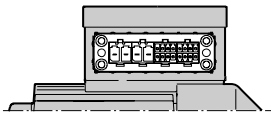
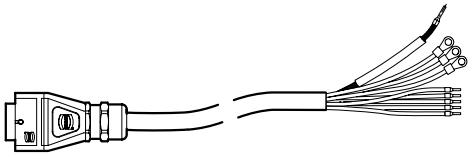
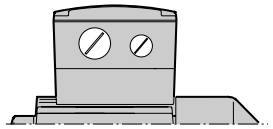
- Interface adapter
- Cable with RJ10 plug connector
- Interface cable RS-232 (UWS21B) or USB (USB11A)

5.12 Hybrid cables

5.12.1 Overview

Hybrid cables are available for connecting MOVIFIT®-SC and motors. The following table provides an overview of the available hybrid cables:

MOVIFIT®-SC	Hybrid cables	Length	Cable type	Drive
Standard ABOX: **MTA...-S02.-...-00** **Hybrid ABOX:** **MTA...-S42.-...-00** **MTA...-S52.-...-00** **MTA...-S62.-...-00** 	Part no. DR63 / DT71-90 (⅄): 0819 967 1 Part no. DR63 / DT71-90 (△): 0819 969 8 Part no. DV100, DV112 DR.71-132 (⅄): 0819 970 1 Part no. DV100, DV112, DR.71-132 (△): 0819 874 8 	Variable	A	Motor with ISU4 (02CI) plug connector 
	Part number: 0819 972 8 	Variable	A	Motor with ASB4 (BA01AB04DA) plug connector 
	Part number: 0819 875 6 	Variable	A	Motor with plug connector AMB4 (MA01AB04DA) 
	Part number: 0819 973 6 	Variable	A	Motor with APG4 plug connector 
	Part number: 0819 975 2 	Variable	A	Motor with cable glands 
	Part number: 0818 736 3 (hybrid cable drum) Part number: 0818 739 8 (hybrid cable drum) 	30 m 100 m	A	Motor with cable glands ASEPTIC DAS motor 

MOVIFIT®-SC	Hybrid cables	Length	Cable type	Drive
Han-Modular®-ABOX: **MTA...-H12.-...-00** **MTA...-H22.-...-00** 	Part number: 1810 096 1 	Variable	A	Motor with ASB4 (BA01AB04DA) plug connector 
	Part number: 1810 098 8 	Variable	A	Motor with plug connector AMB4 (MA01AB04DA) 
	Part number: 1810 099 6 	Variable	A	Motor with APG4 plug connector 
	Part number: DT/DV71-100 1811 121 1 Part number: DV112 1811 128 9 	Variable	A	Motor with cable glands 

5.12.2 Connection of hybrid cables

With open cable end (MOVIFIT® side) and plug connector (motor side)

The table shows the assignment of the following hybrid cables:

- Part number 0819 967 1
  0819 969 8
  0819 970 1
  0819 874 8
- Part number 0819 972 8
- Part number 0819 875 6
- Part number 0819 973 6

MOVIFIT®-SC connection terminal		Hybrid cables
Motor 1	**Motor 2 (for dual-motor operation)**	**Color coding/marking**
X8/1	X9/1	Green/yellow
X8/2	X9/2	Black/U1
X8/3	X9/3	Black/V1
X8/4	X9/4	Black/W1
X8/5	X9/5	Blue/15
X8/6	X9/6	White/14
X8/7	X9/7	Red/13
X81/1	X91/1	Black/1
X81/2	X91/2	Black/2
The inner shield is applied across a shield plate and the overall shield is applied with an EMC cable gland on the housing of the MOVIFIT®-ABOX, see section "Connecting the hybrid cables" (see page 44).		Shield end

With open cable end (MOVIFIT® and motor side)

The table shows the assignment of the following hybrid cables:

- Part number 0819 975 2
- Part number 0 818 736 3
- Part number 0 818 739 8

MOVIFIT®-SC connection terminal		Hybrid cables	Connection terminal
Motor 1	Motor 2 (for dual-motor operation)	Color coding/marking	Motor
X8/1	X9/1	Green/yellow	PE terminal
X8/2	X9/2	Black/U1	U1
X8/3	X9/3	Black/V1	V1
X8/4	X9/4	Black/W1	W1
X8/5	X9/5	Blue/15	5a
X8/6	X9/6	White/14	3a
X8/7	X9/7	Red/13	4a
X81/1	X91/1	Black/1	1a
X81/2	X91/2	Black/2	2a
The inner shield is applied across a shield plate and the overall shield is applied with an EMC cable gland on the housing of the MOVIFIT®-ABOX, see section "Connecting the hybrid cables" (see page 44).		Shield end	The inner shield is applied using the PE terminal and the overall shield with an EMC cable gland on the motor housing.

With plug connector (MOVIFIT® side) and open cable end (motor side)

The table shows the assignment of the following hybrid cables:

- Part number 1811 121 1
  1811 128 9

Hybrid cables Color coding/marking	Connection terminal Motor
Green/yellow	PE terminal
Black/U1	U1
Black/V1	V1
Black/W1	W1
Blue/15	5a
White/14	3a
Red/13	4a
Black/1	1a
Black/2	2a
Shield end	The inner shield is applied using the PE terminal, and the overall shield is applied with an EMC cable gland on the motor housing.

6 Startup

6.1 Startup instructions

⚠ DANGER

You must disconnect the units from the mains before removing or installing the MOVIFIT®-EBOX.

Severe or fatal injuries from electric shock

- Disconnect MOVIFIT® from the mains using an appropriate external disconnecting device and secure it against unintentional reconnection to the voltage supply.
- Then wait at least for 1 minute.

⚠ WARNING

The surface temperature of the MOVIFIT® can be very high during operation.

Danger of burns

- Touch the MOVIFIT® only when it has cooled down sufficiently.

NOTICE

Never remove the MOVIFIT®-SC EBOX during operation.

Doing so can lead to dangerous electric arcs forming between the EBOX and the ABOX, which can cause irreparable damage to the unit (risk of fire, irreparable contacts).

- Never remove the MOVIFIT®-SC EBOX during operation.

6.1.1 Wiring notes for single-motor operation

- The motor phases U, V, W must be correctly connected in accordance with the motor connection terminals in the MOVIFIT® unit. This ensures that the motor rotates in the required direction in single-motor operation.

⚠ DANGER

Important: For operation with only one motor, use the X8 and X81 terminals or X8 plug connectors.

- Do not connect any cables to the X9 and X91 terminals, and do not insert any plugs in the X9 plug connector.

⚠ DANGER

Incorrect connection will cause incorrect motor rotation and/or uncontrolled motor startup.

Severe or fatal injury

- Check the wiring before starting the motor.

6.1.2 Wiring notes for dual-motor operation

- In "dual-motor operation" mode, the mains phases L1, L2, and L3 must be connected correctly in accordance with the mains phase sequence at the terminals in the unit. If you do not follow this sequence, the unit generates the error message "Startup, no. 9, internal error 3" when the power is connected. In this case, the power section will not be enabled.

TIPS

You can deactivate the monitoring of the mains phase sequence in the MOVIFIT®-SC control word:

- Control word, bit 10, value 0: Mains phase sequence monitoring is activated
- Control word, bit 10, value 1: Mains phase sequence monitoring is deactivated

You must enable the function in parameter 8927:

- OFF: Mains phase sequence monitoring is activated
- **ON (factory setting):** Mains phase sequence monitoring via bit 10 can be deactivated

- The motor phases U, V, W of the motors must also be connected correctly in accordance with the motor connection terminals in MOVIFIT® at the terminals X8/X81 (motor 1) or X9/X91 (motor 2) so that the motor turns clockwise in dual-motor operation.

⚠ DANGER

Incorrect connection will cause incorrect motor rotation and/or uncontrolled motor startup.

Severe or fatal injuries

- Check the wiring before starting the motor.

6.1.3 Wiring notes for brakes

- For operating SEW motors with a brake, the brake can be connected to the terminals in MOVIFIT®, which are provided for the SEW brake, without any further measures (do not use a brake rectifier).
- Two digital outputs are available on MOVIFIT® for operating non-SEW motors with a brake. These outputs can be used to control non-SEW brake(s) using appropriate additional measures (e.g. brake rectifier).

⚠ DANGER

If binary outputs DB00 or DB01 are used to control the brake, do not change the parameters of the functions of the binary outputs.

Severe or fatal injuries

- Before using the binary output for controlling the brake, check the parameter settings.

6.1.4 Possible MOVIFIT® motor combinations

MOVIFIT®-SC is available in the unit power ratings 1.5 kW and 4 kW. The unit is equipped with an overcurrent protection device that is designed for the corresponding unit rating and triggers at 180% of the rated unit current.

NOTICE

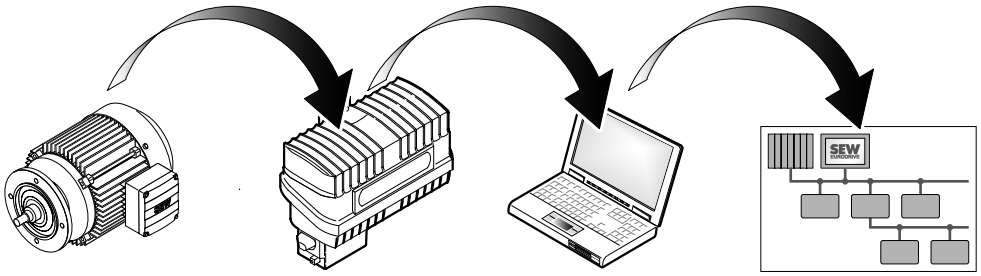
To ensure that this overcurrent protection device does not trigger, you must strictly comply with the total current in accordance with the operating mode and the motor(s) used.

- Note that the total current is 4 A (1.5 KW unit) or 8.7 A (4 KW unit), depending on the operating mode and the motor(s) used.

6.2 Startup procedure for MOVIFIT®-SC

The following sections describe how to start up MOVIFIT®-SC. Depending on the MOVIFIT® function level, note additional documentation for fieldbus configuration and advanced startup/parameter setting.

The following tables provide an overview of MOVIFIT®-SC startup and refer to additional publications:



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Function level	1. Startup Motor	2. Startup MOVIFIT®-SC	3. Parameter setting[1] Programming	4. Fieldbus configuration
Classic	Observe: • "DR/DV/DT/DTE/DVE AC Motors, CT/CV Asynchronous Servomotors" operating instructions • or "AC Motors DRS/DRE/DRP" operating instructions	• Section "Startup instructions" (see page 92) • Section "Startup MOVIFIT®-SC" (see page 95) • Section "Startup MOVIFIT® motor starter" (see page 100)	Manual "MOVIFIT® Function Level Classic..."[2]	
Technology			Manual "MOVIFIT® Function Level Technology .."[2]	
			Manual "MOVI-PLC® Programming in the PLC Editor" Manual "Libraries MPLCMotion_MC07 and MPLCMotion_MM for MOVI-PLC®"	
System			Manual "MOVIVISION® Configuration and Diagnostic Tool" Manual "MOVIFIT® Function Level System"	

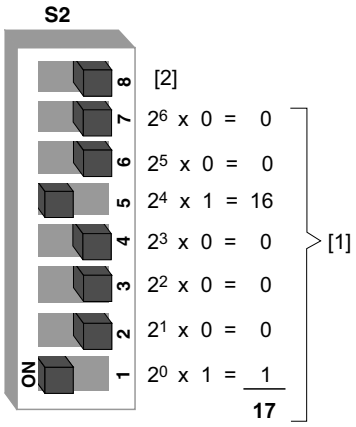
1) You only have to set parameters when the "Expert" mode is activated.

2) The "MOVIFIT® Function Level Classic" and "MOVIFIT® Function Level Technology" manuals are available in several fieldbus-specific versions.

6.3 Startup MOVIFIT®

6.3.1 Startup in conjunction with PROFIBUS

1. Check the MOVIFIT® connection.
2. Set the PROFIBUS address at DIP switch S2 of the MOVIFIT®-ABOX, see section "ABOX" (see page 14). Use DIP switches 1 to 7 to set the PROFIBUS address.



837511563

[1] Example: Address 17
[2] Switch 8 = Reserved

Addresses 1 to 125: Valid addresses
Addresses 0, 126, 127: Are not supported

The following table uses address 17 as an example to show how to set the DIP switches for any bus address:

DIP switch setting	Value
DIP 1 = ON	1
DIP 2 = OFF	2
DIP 3 = OFF	4
DIP 4 = OFF	8
DIP 5 = ON	16
DIP 6 = OFF	32
DIP 7 = OFF	64

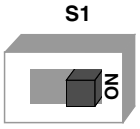
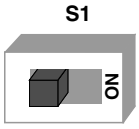
3. Connect the bus termination on MOVIFIT® at the last bus station.
   - If MOVIFIT® is located at the end of a PROFIBUS segment, the unit can only be connected to the PROFIBUS mains via the incoming PROFIBUS line.
   - To prevent malfunctions in the bus system due to reflections, etc., the PROFIBUS segment must be terminated using bus terminating resistors at the first and last physical stations.

	TIP
	The PROFIBUS is not interrupted when you remove the EBOX (electronics unit) from the ABOX (connection unit).

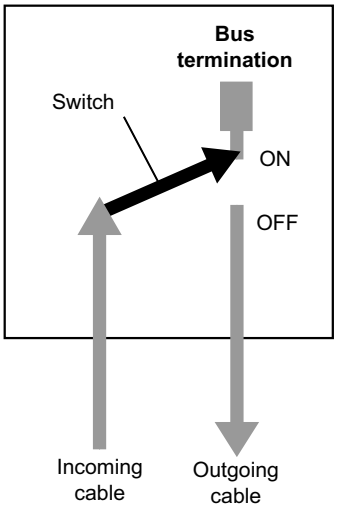
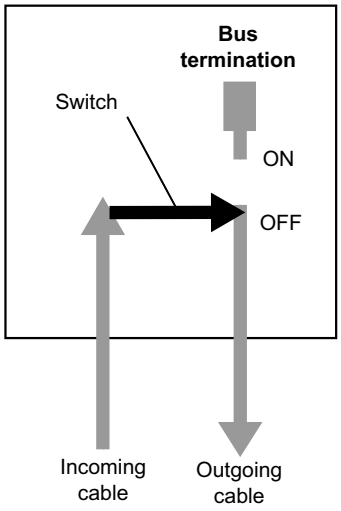
4. Start up the MOVIFIT® motor starter, see section "Startup MOVIFIT® motor starter" (see page 100).
5. Mount the MOVIFIT®-EBOX on the ABOX and close it.
6. Switch on the 24V_C and 24V_S supply voltage(s). The associated control LEDs should now light up green.

Bus termination

The bus terminating resistors are already installed in the MOVIFIT®-ABOX (only with standard ABOX "MTA...-S02.-...-00") and can be activated using switch S1, see section "ABOX" (see page 14):

Bus termination ON = On	Bus termination OFF = Off (factory setting)
 837515659	 837519755

The following table shows the operating principle of the bus termination switch:

Bus termination switch S1	
Bus termination ON = On	Bus termination OFF = Off
 837562251	 837566347

	TIP
	When using the following connection boxes, please note: • Hybrid ABOX "MTA...-S52.-...-00" • Han-Modular®-ABOX "MTA...-H12.-...-00" In contrast to the standard ABOX, these connection boxes require a plug-in bus terminator (M12) at the last station instead of the outgoing bus connection.

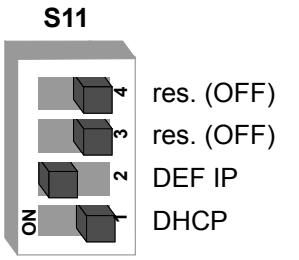
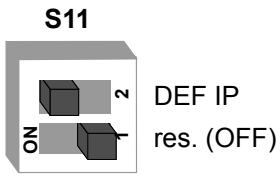
6.3.2 Startup with PROFINET IO, EtherNet/IP, or Modbus/TCP

1. Check the MOVIFIT® connection.

	TIP
	In conjunction with PROFINET IO, EtherNet/IP, or Modbus/TCP, you do not have to make any settings on the MOVIFIT® for fieldbus startup. The entire fieldbus startup is carried out via software tools and is described in the applicable manuals: • "MOVIFIT® Function Level Classic..." manual[1)] • "MOVIFIT® Function Level Technology..." manual[1)]

1) The "MOVIFIT® Function Level Classic" and "MOVIFIT® Function Level Technology" manuals are available in several fieldbus-specific versions.

2. Start up the MOVIFIT® motor starter, see section "Startup MOVIFIT® motor starter" (see page 100).
3. Set DIP switch S11/2 "DEFIP" to "ON".

DIP switch S11/2 = ON	
MOVIFIT® function level "Technology"	**MOVIFIT® function level "Classic"**
	

This sets the address parameters to the following default values:

IP address:	192.168.10.4
Subnet mask:	255.255.255.0
Gateway:	0.0.0.0

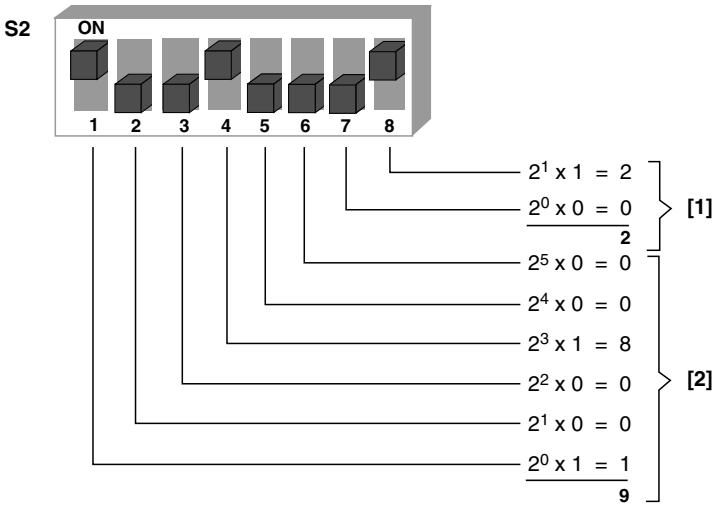
4. Mount the MOVIFIT®-EBOX on the ABOX and close it.
5. Switch on the 24V_C and 24V_S supply voltage(s). The associated control LEDs should now light up green.

6.3.3 Startup with DeviceNet

1. Check the MOVIFIT® connection.
2. Set the DeviceNet address at DIP switch S2 of the MOVIFIT®-ABOX:
3. Set the baud rate at DIP switch S2 of the MOVIFIT®-ABOX.
4. Start up the MOVIFIT® motor starter, see section "Startup MOVIFIT® motor starter" (see page 100).
5. Mount the MOVIFIT®-EBOX on the ABOX and close it.
6. Switch on the 24V_C and 24V_S supply voltage(s). The associated control LEDs should now light up green.

Setting the DeviceNet address (MAC ID) and baud rate

The DeviceNet address is set using DIP switches S2/1 to S2/4. The baud rate is set using DIP switches S2/7 and S2/8.



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[1] Baud rate setting
[2] DeviceNet address setting

The following table uses address 9 as an example to show how to set the DIP switches for any bus addresses.

DIP switch setting	Value
DIP S2/1 =ON	1
DIP S2/2 = OFF	2
DIP S2/3 = OFF	4
DIP S2/4 =ON	8
DIP S2/5 = OFF	16
DIP S2/6 = OFF	32

The following table shows how to set the baud rate using DIP switches S2/7 and S2/8:

Baud rate	Value	DIP S2/7	DIP S2/8
125 kBaud	0	OFF	OFF
250 kBaud	1	ON	OFF
500 kBaud	**2**	**OFF**	**ON**
(Reserved)	3	ON	ON

6.4 Startup MOVIFIT® motor starter

6.4.1 Startup mode

You can use one of the following startup modes to start the MOVIFIT® motor starter:

- MOVIFIT®-SC can be put into operation quickly and easily in **"Easy"** mode using DIP switch S10 (see section "EBOX", page 13).
- To operate the unit in "**Expert**" mode, set DIP switch S10/1 to ON. This mode includes additional parameters. The parameters can be adjusted to suit the application using the "MOVITOOLS® MotionStudio" software tool (function levels "Classic" and "Technology").

	TIP
	Important: When you are using the "System" function level (MOVIVISION®), you must activate the "Expert" mode (switch S10/1 = ON).

- After "Expert" mode is activated, the unit and its parameters are initialized only once according to the setting of DIP switches S10/2 to S10/6.
- When "Expert" mode is activated, DIP switches S10/2 to S10/6 are only re-effected when you set the *P802 Factory setting* parameter to "Delivery status". Otherwise, the system will ignore the changing of the DIP switch setting.

Unit behavior during transition from "Easy" mode to "Expert" mode

If "Expert" mode is activated, all parameters are set to factory settings.

For the following parameters, which can be set using DIP switch S10, the DIP switch setting becomes effective only once:

- Starter operating mode
- Rated power supply voltage
- Rated brake voltage, drive 1
- Rated brake voltage, drive 2

Unit behavior during transition from "Expert" mode to "Easy" mode

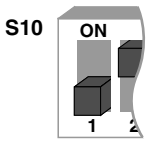
If "Expert" mode is deactivated, all parameters are set to factory settings.

For the following parameters, which can be set using DIP switch S10, the DIP switch setting is in effect:

- Starter operating mode
- Rated power supply voltage
- Rated brake voltage, drive 1
- Rated brake voltage, drive 2

6.4.2 Startup in "Easy" mode

1. Set DIP switch S10/1 to "OFF", see section "EBOX" (see page 13, Activating "Easy" mode).



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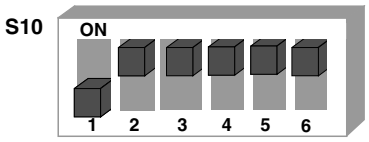
2. Set the unit parameters using DIP switches S10/2 to S10/6, see the following section "Description of DIP switches S10/2 to S10/6".

   Straightforward startup is now possible without having to make any further settings.

Description of DIP switches S10/2 to S10/6

In "Easy" mode, the unit parameters are set using the DIP switches S10/2 to S10/6. The following section describes the setting options:



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S10 Meaning	1 Startup mode	2 Operating mode	3 Rated power supply voltage	4 Rated brake voltage, drive 1/2 2^0	5 Rated brake voltage, drive 1/2 2^1	6 Soft start
ON	Expert mode	Dual-motor operation	500 V	1	1	Deactivated
OFF	Easy mode	Single-motor operation	400 V	0	0	Activated

NOTICE

Use only suitable tools, e.g. a slotted screwdriver with a blade width smaller than 3 mm, to set the DIP switches.

The force used for setting the DIP switches must not exceed 5 N.

DIP switch S10/2

Operating mode

- DIP switch S10/2 = OFF: Selection of single-motor operation
- DIP switch S10/2 = ON: Selection of dual-motor operation

⚠ DANGER

Important: For operation with only one motor, use the X8 and X81 terminals or X8 plug connectors.

- Do not connect any cables to the X9 and X91 terminals, and do not insert any plugs in the X9 plug connector.

DIP switch S10/3

Rated power supply voltage

- DIP switch S10/3 = OFF: Selection of rated power supply voltage of 400 V

  Choose this setting when the mains supply a voltage of AC 3 x 380 V, 3 x 400 V or 3 x 415 V.
- DIP switch S10/3 = ON: Selection of rated power supply voltage of 500 V

  Choose this setting when the mains supply a voltage of AC 3 x 460 V, 3 x 480 V or 3 x 500 V.

DIP switches S10/4 and S10/5

Selecting the rated brake voltage for SEW three-wire brakes

If you use motors with SEW three-wire brakes, the rated brake voltage must be selected using DIP switches S10/4 and S10/5 in accordance with the following table.

Setting options for DIP switches S10/4 and S10/5		
DIP switch S10/4	**DIP switch S10/5**	**Rated brake voltage, drive 1 and drive 2**
0	0	400 V
1	1	500 V
1	0	Reserved
0	1	Reserved

Important: For operation with only one motor, use X8 and X81 terminals or the X8 plug connector.

NOTICE

The rated brake voltage must match the rated power supply voltage.

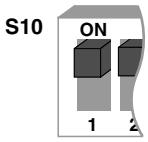
DIP switch S10/6

Soft start

- DIP switch S10/6 = OFF: Soft start is activated
- DIP switch S10/6 = ON: Soft start is deactivated

6.4.3 Advanced startup and parameter setting in "Expert" mode

1. Set DIP switch S10/1 to "ON", see section "EBOX" (see page 13, "Activating 'Expert' mode").



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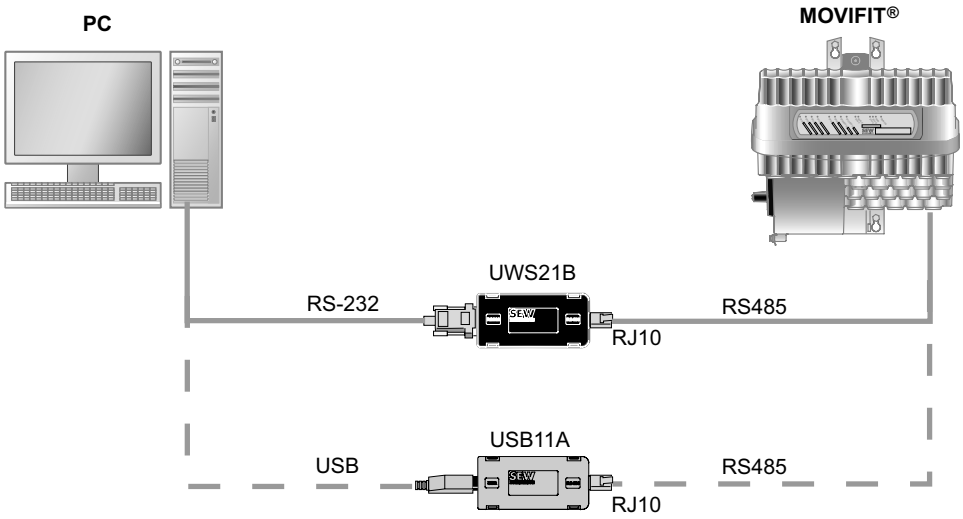
2. Connect MOVIFIT® to a PC or laptop:



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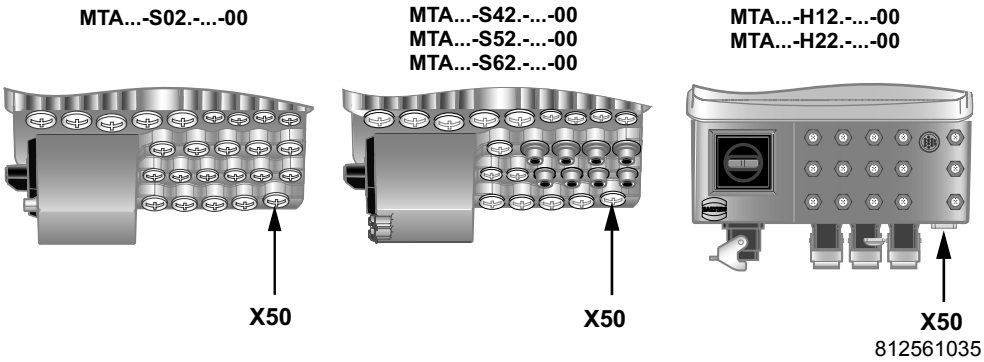
Connect USAB11A or UWS21B to MOVIFIT® via the X50 diagnostics socket. The diagnostics socket is located under the cable gland shown in the following figure:



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3. The remaining procedure for startup/parameter setting in "Expert" mode differs depending on the MOVIFIT® function level selected. See the following manuals for more information:
   - MOVIFIT® Function Level "Classic..."[1)]
   - MOVIFIT® Function Level "Technology .."[1)]
   - MOVIFIT® Function Level "System"

1) The "MOVIFIT® Function Level Classic" and "MOVIFIT® Function Level Technology" manuals are available in several fieldbus-specific versions.

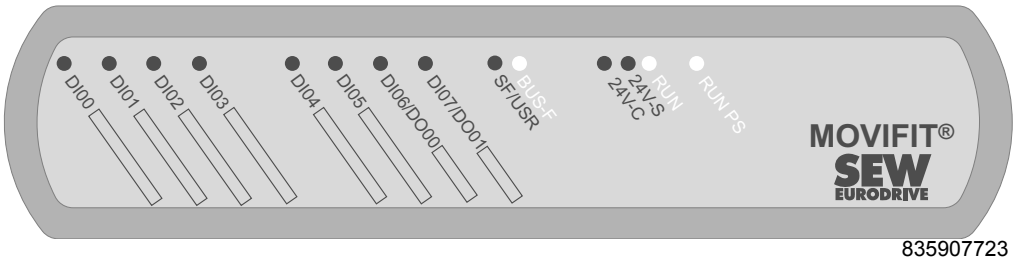
7 Operation

7.1 Status LEDs for MOVIFIT®-SC

7.1.1 General LEDs

This section describes the fieldbus-independent and option-independent LEDs. These LEDs are shown as dark in the figures. The LEDs that are shown as white differ depending on which fieldbus version is used; these LEDs are described in the following sections. The following figure depicts examples of the PROFIBUS variants:

Function level "Classic" with PROFIBUS or DeviceNet



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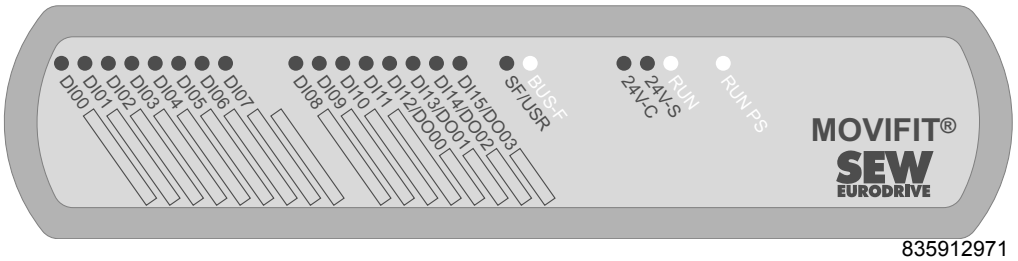
Function level "Technology" or "System" with PROFIBUS, DeviceNet, or PROFINET
Function level "Classic" with PROFINET



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LEDs "DI.." and "DO.."

The following table shows the statuses of the "DI.." and "DO.." LEDs:

LED	Status	Meaning
DI00 to DI15	**Yellow**	Input signal present at binary input DI..
	Off	Input signal at binary input DI.. open or "0".
DO00 to DO03	**Yellow**	DO.. output switched
	Off	DO.. output logical "0"

"24V-C" and "24V-S" LEDs

The following table shows the statuses of the "24V-C" and "24V-S" LEDs:

LED	Status	Meaning	Remedy
24V-C	**Green**	24V-C continuous voltage is present.	–
	Off	24V-C continuous voltage is not present.	Check 24V-C voltage supply.
24V-S	**Green**	24V-S actuator voltage is present.	–
	Off	24V-S actuator voltage is not present.	Check 24V-S voltage supply.

"SF-USR" LED

The "SF/USR" LED indicates various statuses depending on the function level.

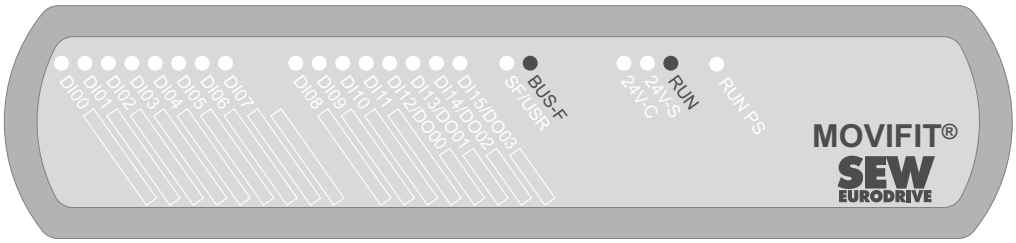
The following table shows the statuses of the "SF/USR" LED:

SF/USR	Function level			Meaning	Remedy
	C	T	S		
Off	•			Standard operating state. MOVIFIT® is exchanging data with the connected drive system (integrated motor starter).	-
Red	•			MOVIFIT® cannot exchange data with the integrated motor starter.	Check the DC 24 V supply of the integrated motor starter.
Flashing Red (2 s cycle)	•			MOVIFIT® initialization error or serious unit fault	Incorrect card ID Switch on MOVIFIT® again. If the fault is still present, replace the EBOX or contact SEW Service.
Flashing Red	•			Other unit fault	Use MOVITOOLS® MotionStudio to read out the fault status. Eliminate the cause of the fault and acknowledge this fault.
Off		•		ICE program is running.	-
Green		•		ICE program is running. The ICE program controls the green LED.	For the meaning, see the ICE program documentation.
Red		•		Due to an error, boot project was cancelled or did not start.	Use MOVITOOL®/PLC Editor/Remote Tool to log on and check the boot project.
		•		MOVIFIT® initialization fault Incorrect EBOX/ABOX combination	Incorrect card ID Check the MOVIFIT®-EBOX type. Place the correct EBOX on the ABOX and perform the complete startup process.
Flashing Red		•		No ICE application program loaded.	Load an IEC application program and, if necessary, restart the integrated PLC.
Flashing yellow		•		The IEC application program has been loaded, but it is not running (PLC = Stop).	Check the IEC application program using MOVITOOLS® MotionStudio and start the integrated PLC.
Flashing 1 x red and n x green		•		Fault status reported by the ICE program	For status/remedy, see the ICE program documentation.
Red			•	MOVIFIT® displays a fault status.	Eliminate the cause of the fault and use PROFIBUS to acknowledge the fault message. Use MOVIVISION® for detailed fault diagnostics.
Flashing red			•	MOVIFIT® indicates a fault status; cause of fault has already been eliminated.	Use PROFIBUS to acknowledge the fault message. Use MOVIVISION® for detailed fault diagnostics.

- Valid for selected function level:
  C = Function level "Classic"
  T = Function level "Technology"
  S = Function level "System"

7.1.2 Bus-specific LEDs for PROFIBUS

This section describes the bus-specific LEDs for PROFIBUS. In the following figure, the LEDs are shown as dark:



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"BUS-F" LED

The following table shows the statuses of the "BUS-F" LED:

BUS-F	RUN	Meaning	Remedy
Off	Green	MOVIFIT® is exchanging data with the DP master (data exchange).	-
Flashing red	Green	• The baud rate is being detected. However, MOVIFIT® is not being addressed by the DP master. • MOVIFIT® was configured incorrectly or not configured in DP master.	• Check the configuration of the DP master. • Check whether all the modules configured during project planning are permitted for the MOVIFIT® variant used (MC, FC, SC).
Red	Green	• Connection to the DP master has failed. • MOVIFIT® does not detect baud rate. • Bus interruption. • DP master is not in operation.	• Check the PROFIBUS DP connection of MOVIFIT®. • Check the DP master. • Check all cables in your PROFIBUS DP network.

"RUN" LED

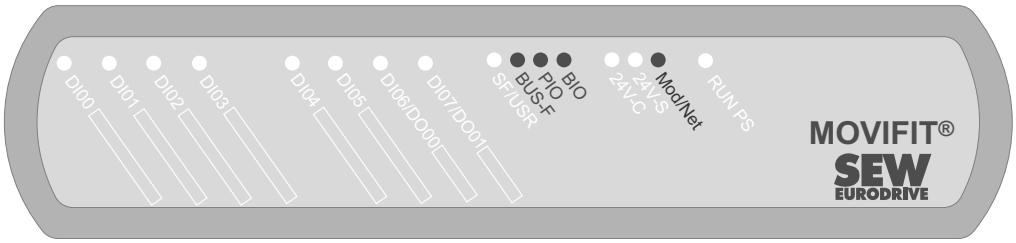
The following table shows the statuses of the "RUN" LED:

BUS-F	RUN	Meaning	Remedy
x	**Off**	• MOVIFIT® not ready for operation. • No DC 24 V supply.	• Check DC 24 V supply. • Switch on MOVIFIT® again. Exchange EBOX if problem occurs repeatedly.
x	**Green**	MOVIFIT® component hardware OK.	-
Off	**Green**	• MOVIFIT® operating correctly. • MOVIFIT® is currently exchanging data with the DP master (data exchange) and all subordinate drive systems.	-
x	**Flashing green**	PROFIBUS address is set equal to 0 or higher than 125.	Check the PROFIBUS address that is set in the MOVIFIT®-ABOX.
x	**Yellow**	MOVIFIT® is currently being initialized.	-
x	**Red**	Internal unit fault.	Switch on MOVIFIT® again. Exchange EBOX if problem occurs repeatedly.

X Any status

7.1.3 Bus-specific LEDs for DeviceNet

This section describes the bus-specific LEDs for DeviceNet. In the following figure, the LEDs are shown as dark:



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"Mod/Net" LED

The function of the "Mod/Net" LED described in the following table is defined in the DeviceNet specification.

Mod/Net	Status	Meaning	Remedy
Off	Not switched on/offline.	• Unit is offline. • Unit is performing DUP MAC check. • Unit is switched off.	• Apply supply voltage via DeviceNet connector.
Flashing green (1 s cycle)	Online and in operational mode.	• The unit is online and no connection has been established. • DUP-MAC check performed successfully. • A connection to a master has not yet been established. • Missing (incorrect) or incomplete configuration.	• Include the station in the master's scan list and start communication in the master.
Green	Online, operational mode and connected.	• Unit is online. • Connection is active (established state).	-
Flashing red (1 s cycle)	Minor fault or connection timeout.	• A correctable fault has occurred. • Polled I/O and/or bit-strobe I/O connections are in timeout status. • A correctable fault has occurred in the unit.	• Check the DeviceNet cable. • Check the timeout response (P831). If a response with fault is set, reset the unit once the fault has been corrected.
Red	Critical fault or critical link failure	• A fault that cannot be corrected has occurred. • BusOff status. • DUP-MAC check has detected a fault.	• Check the DeviceNet cable. • Check the address (MAC ID). Is another unit already using the same address?

"PIO" LED

The "PIO" LED checks the polled I/O connection (process data channel).

The function is described in the following table.

PIO	Status	Meaning	Remedy
Flashing green (500 ms cycle)	DUP-MAC check.	• Unit is performing DUP-MAC check. • If the station does not leave this status after about 2 seconds, it means that no further stations were found.	• Activate at least one other DeviceNet station in the network.
Off	Not switched on/ offline, but not performing DUP-MAC check.	• Unit is switched off. • Unit is in offline status.	• Switch on the unit. • Check whether the PIO connection type was activated in the master.
Flashing green (1 s cycle)	Online and in operational mode.	• Unit is online. • DUP-MAC check performed successfully. • A PIO connection is being established with a master (configuring state). • Missing, incorrect or incomplete configuration.	• Check the unit configuration in the master.
Green	Online, operational mode and connected.	• Unit is online. • A PIO connection has been established (established state).	-
Flashing red (1 s cycle)	Minor fault or connection timeout.	• A correctable fault has occurred. • Invalid baud rate set at the DIP switches. • Polled I/O connection is in timeout status.	• Check the DeviceNet cable. • Check the positions of the DIP switches for the baud rate. • Check the timeout response (P831). If a response with fault is set, reset the unit once the fault has been corrected.
Red	Critical fault or critical link failure.	• A fault that cannot be corrected has occurred. • BusOff status. • DUP-MAC check has detected a fault.	• Check the DeviceNet cable. • Check the address (MAC ID). Is another unit already using the same address?

"BIO" LED

The "BIO" LED checks the bit-strobe I/O connection.

The function is described in the following table.

BIO	Status	Meaning	Remedy
Flashing green (500 ms cycle)	DUP-MAC check.	• Unit is performing DUP-MAC check. • If the station does not leave this status after about 2 seconds, it means that no further stations were found.	• Activate at least one other DeviceNet station in the network.
Off	Not switched on/ offline, but not performing DUP-MAC check.	• Unit is switched off. • Unit is in offline status.	• Switch on the unit. • Check whether the BIO connection type was activated in the master.
Flashing green (1 s cycle)	Online and in operational mode.	• Unit is online. • DUP-MAC check performed successfully. • A BIO connection is being established with a master (configuring state). • Missing, incorrect or incomplete configuration.	• Check the unit configuration in the master.
Green	Online, operational mode and connected.	• Unit is online. • A BIO connection has been established (established state).	-
Flashing red (1 s cycle)	Minor fault or connection timeout.	• A correctable fault has occurred. • Bit-strobe I/O connection is in timeout state.	• Check the DeviceNet cable. • Check the timeout response (P831). If a response with fault is set, reset the unit once the fault has been corrected.
Red	Critical fault or critical link failure.	• A fault that cannot be corrected has occurred. • BusOff status. • DUP-MAC check has detected a fault.	• Check the DeviceNet cable. • Check the address (MAC ID). Is another unit already using the same address?

"BUS-F" LED

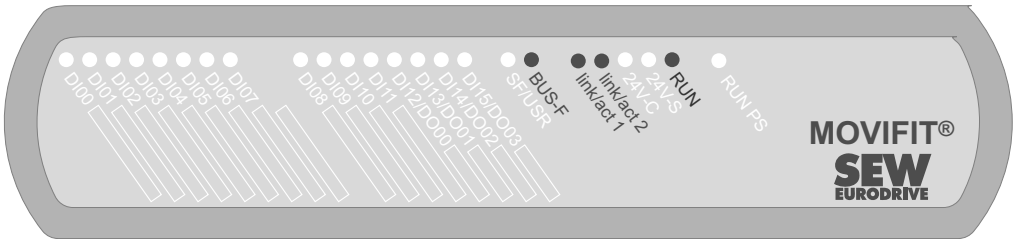
The "BUS-F" LED indicates the physical state of the bus node.

The function is described in the following table:

BUS-F	Status	Meaning	Remedy
Off	No error	• The number of bus errors is within the normal range (error active state).	-
Flashing red (1 s cycle)	Bus warning	• The unit is performing a DUP-MAC check and cannot send any messages because no other stations are connected to the bus (error passive state).	• Activate another DeviceNet station in the network. • Check the wiring and terminating resistors.
Red	Bus error	• Bus off status • The number of physical bus errors has increased despite a switch to the error-passive state. Access to the bus is deactivated.	• Check the setting for the address baud rate, wiring, and terminating resistors.
Yellow	Power off	• External voltage supply has been turned off or is not connected.	• Check the external voltage supply and wiring of the unit.

7.1.4 Bus-specific LEDs for PROFINET

This section describes the bus-specific LEDs for PROFINET. In the following figure, the LEDs are shown as dark:



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"RUN" LED

The following table shows the statuses of the "RUN" LED:

RUN	BUS-F	Meaning	Remedy
Green	x	MOVIFIT® component hardware OK.	-
Green	Off	• Correct MOVIFIT® operation. • MOVIFIT® is currently exchanging data with the PROFINET master (data exchange) and all subordinate drive systems.	-
Off	x	• MOVIFIT® not ready for operation. • No DC 24 V supply.	• Check DC 24 V supply. • Switch on MOVIFIT® again. Exchange EBOX if problem occurs repeatedly.
Red	x	Fault in MOVIFIT® component hardware.	Switch on MOVIFIT® again. Exchange EBOX if problem occurs repeatedly.
Flashing green	x	MOVIFIT® component hardware does not start.	Switch on MOVIFIT® again. Exchange EBOX if problem occurs repeatedly.
Flashing yellow	x	MOVIFIT® component hardware does not start.	Switch on MOVIFIT® again. Exchange EBOX if problem occurs repeatedly.
Yellow	x	MOVIFIT® component hardware does not start.	Switch on MOVIFIT® again. Exchange EBOX if problem occurs repeatedly.

X Any status

"BUS-F" LED

The following table shows the statuses of the "BUS-F" LED:

RUN	BUS-F	Meaning	Remedy
Green	**Off**	MOVIFIT® is currently exchanging data with the PROFINET master (data exchange).	-
Green	**Flashing green, flashing green/red**	The flashing function in the PROFINET master configuration is activated to visually locate the stations.	-
Green	**Red**	• Connection to the PROFINET master has failed. • MOVIFIT® does not detect a link. • Bus interruption. • PROFINET master not in operation.	• Check the PROFINET connection of MOVIFIT®. • Check the PROFINET master. • Check all cables in your PROFINET network.

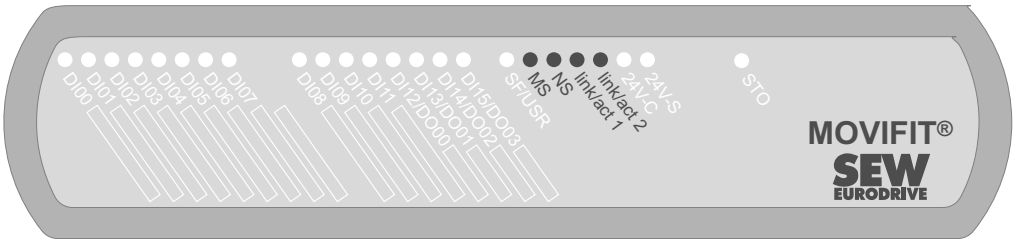
"link/act 1" and "link/act 2" LEDs

The following table shows the statuses of the "link/act 1" and "link/act 2" LEDs:

LED	Status	Meaning
link/act 1	Ethernet port 1 link = Green act = Yellow	• link = Ethernet cable connects unit with other Ethernet station • act = Active, Ethernet communication active
link/act 2	Ethernet port 2 link = Green act = Yellow	

7.1.5 Bus-specific LEDs for Modbus/TCP and EtherNet/IP

This section describes the bus-specific LEDs for Modbus/TCP and EtherNet/IP. In the following figure, the LEDs are shown as dark:



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"MS" and "NS" LEDs

The following table shows the statuses of LEDs "MS" (module status) and "NS" (network status):

MS	NS	Meaning	Remedy
Off		• MOVIFIT® not ready for operation. • No DC 24 V supply.	• Check DC 24 V supply. • Switch on MOVIFIT® again. • Exchange EBOX if problem occurs repeatedly.
Flashing Red/green		• MOVIFIT® is performing an LED test. • This status may only be active for a short time at startup.	-
Flashing red	Red	• A conflict has been detected in the IP address assignment. Another station in the network uses the same IP address.	• Check whether there is a unit in the network with the same IP address. • Change the MOVIFIT® IP address. • Check the DHCP settings for IP address assignment of the DHCP server (applies only if you are using a DHCP server).
Red	x	Fault in MOVIFIT® component hardware.	• Switch on MOVIFIT® again. • Reset MOVIFIT® to the factory settings. • Exchange EBOX if problem occurs repeatedly.
Flashing green	Flashing green	Application is started.	-
Flashing green	Off	• MOVIFIT® does not yet have any IP parameters. • The TCP IP stack is starting. • If the status continues and the DHCP DIP switch is activated, MOVIFIT® is waiting for data from the DCHP server.	• Set DIP switch S11/1 of the DHCP server to "OFF". • Check the DHCP server connection (only if DHCP is activated and the status continues).
Green	x	MOVIFIT® component hardware OK.	-
x	**Flashing red**	• The timeout interval of the controlling connection has elapsed. • The status can be reset by restarting the communication.	• Check the bus connection of MOVIFIT®. • Check the master/scanner. • Check all Ethernet cables.
x	**Flashing green**	• There is no controlling connection.	-
x	**Green**	• There is a controlling connection with a master/scanner.	-

X Any status

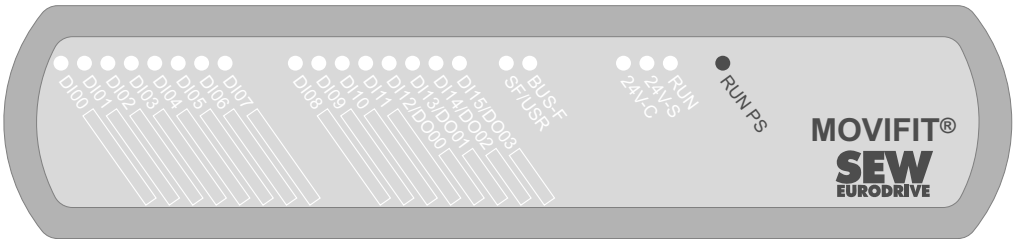
"link/act 1" and "link/act 2" LEDs

The following table shows the statuses of the "link/act 1" and "link/act 2" LEDs:

LED	Status	Meaning
link/act 1	Ethernet port 1 link = Green act = Yellow	• link = Ethernet cable connects unit with other Ethernet station • act = Active, Ethernet communication active
link/act 2	Ethernet port 2 link = Green act = Yellow	

7.1.6 "RUN PS" LED (motor starter status LED)

The following figure shows the "RUN PS" LED (shown as dark). As an example, the figure shows the PROFIBUS variant in the "Technology" or "System" function level:



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LED color	LED status	Operating status	Description
-	**Off**	Not ready	No 24 V power supply.
Red	**Constantly lit**	Not ready	24V_C and 24V_P power supply OK Defect on motor starter's power section circuit board
Yellow	**Constantly lit**	Ready, but unit inhibited.	Standard operation "No enable": • Motor starter ready for operation (24 V electronics power supply and mains voltage present). • Motor starter power section not enabled.
Green	**Constantly lit**	Unit enabled	Standard operation "enable" for single-motor operation: • Motor starter ready for operation (24 V electronics power supply and mains voltage present). • Motor enabled Standard operation "enable" for dual-motor operation: • Motor starter ready for operation (24 V electronics power supply and mains voltage present). • Both drives enabled
Green	**Flashing steadily**	Ready for operation	Standstill current function active
Green	**1 x flashing, break**	Unit enabled	Standard operation "enable" for dual-motor operation: • Motor starter ready for operation (24 V electronics power supply and mains voltage present). • Drive 1 enabled
Green	**2 x flashing, break**	Unit enabled	Standard operation "enable" for dual-motor operation: • Motor starter ready for operation (24 V electronics power supply and mains voltage present). • Drive 2 enabled
Yellow	**Flashing steadily**	Not ready	Self-test phase or 24 V supply is present, but supply voltage not OK
Yellow	**Flashing steadily, fast**	Ready for operation	Operating status "Release brake of drive 1 and/or drive 2 without drive enable"
Green/ yellow	**Flashing with alternating colors**	Ready, but timeout	Faulty communication with cyclical data exchange
Green	**Flashing steadily, fast**	Current limit active	Drive operating at current limit.

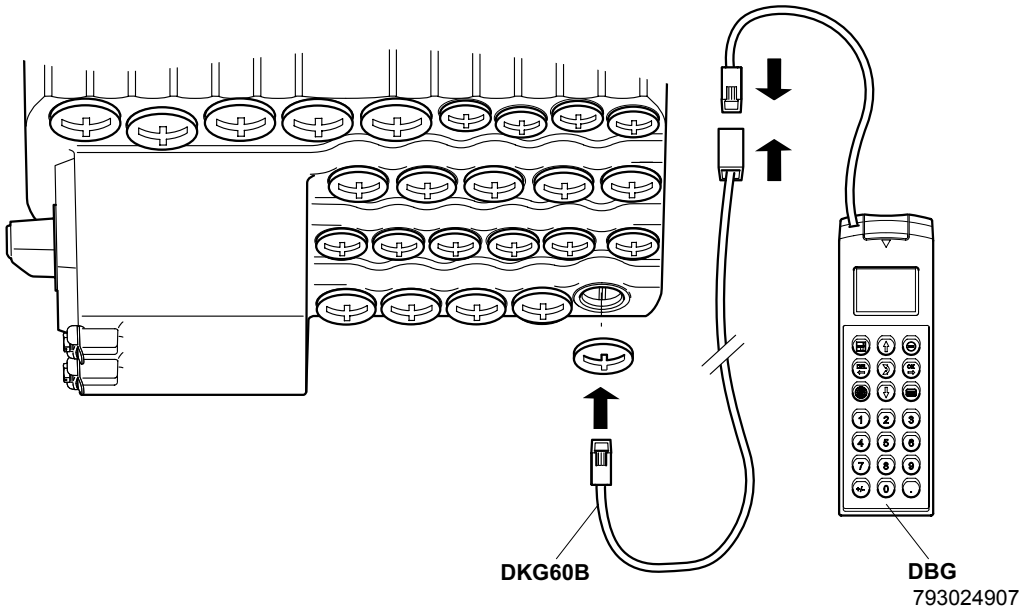
LED color	LED status	Operating status	Description
Red	**Flashing steadily, slowly**	Not ready	Internal CPU error, EEPROM error, output open, watchdog.
Red	**3 x flashing, break**	Fault 44	Ixt utilization
		Fault 01	Overcurrent in motor/output stage
		Fault 11	Overtemperature in output stage
Red	**4x flashing, break**	Fault 84	Overload in motor
		Fault 31	TF was triggered.
Red	**5x flashing, break**	Fault 89	Overtemperature in brake
Red	**6x flashing, break**	Fault 06	Mains phase failure

7.2 Manual operation using the DBG keypad

7.2.1 Connection

MOVIFIT® units have an X50 (diagnostic interface RJ10 plug connector) for parameter setting and manual operation.

The X50 diagnostic interface is located under the cable gland shown in the following figure:



⚠ WARNING

The surfaces of MOVIFIT® and of the external options, e.g. the braking resistor, can reach high temperatures during operation.

Danger of burns

- Do not touch MOVIFIT® or the external options until they have cooled down sufficiently.

You can also connect the DBG keypad to the MOVIFIT® unit using option DKG60B (5 m extension cable).

NOTICE

The degree of protection specified in the technical data applies only if the screw plug of the diagnostic interface is mounted correctly.

A missing or incorrectly installed screw plug can cause damage to MOVIFIT®.

- Screw the screw plug back on with the seal after manual operation.

7.2.2 Operation

TIP

For notes on operating the MOVIFIT® drive in manual operation, refer to the "MOVIFIT® Function Level 'Technology..'" or "MOVIFIT® Function Level 'Classic..'" manual.

8 Service

8.1 Unit diagnostics

	TIP
	Depending on the function level in use, further diagnostic tools are available via MOVITOOLS® MotionStudio or MOVIVISION®. These are described in the respective manuals: • "MOVIFIT® Function Level Classic..." manual[1)] • Manual for MOVIFIT® Function Level "Technology..."[1)] • Manual for MOVIFIT® function level "System"

1) The "MOVIFIT® Function Level Classic" and "MOVIFIT® Function Level Technology" manuals are available in several fieldbus-specific versions.

8.1.1 Fault table

Fault	Fault no.	Sub-error no.	Internal fault no.	Cause	Remedy
Unit-related faults/warnings					
Mains phase failure	**6**	**1**	**1**	Mains phase failure during mains detection. **Important: The failure of 2 mains phases does not lead to the error "Mains phase failure". Instead, the state "Not ready, 24V" is displayed without an error display.**	Check the supply system cable for phase failure.
Mains phase failure	**6**	**2**	**2**	Mains phase failure occurs after mains detection. **Important: The failure of 2 mains phases does not lead to the error "Mains phase failure". Instead, the state "Not ready, 24V" is displayed without an error display.**	Check the supply system cable for phase failure.
Startup fault "Mains phase sequence"	**9**	**99**	**3**	In the "dual-motor operation" operating mode, the mains input phases L1, L2, and L3 must be connected to the connection terminals in the correct order. When the motor phases are connected correctly for both motors, the direction of rotation is set to "CW". An incorrect mains phase sequence is detected and rejected as a fault.	Check the connection sequence of the mains input phases and switch two mains phases to obtain a clockwise rotating field.
Startup error in the "single-motor operation" operating mode	**9**	**100**	**2**	In the "single-motor operation" operating mode, the measured output current of drive 2 is greater than 10% $I_{Rated,unit}$. This output current is caused by the fact that: • the drive is connected to the X9 terminal or to the X9 plug connector, or • two drives are connected to the MOVIFIT® unit in "single-motor operation" operating mode.	Check the drive connection. In the "single-motor operation" operating mode, only one drive can be connected at the terminals provided for drive 1. **Important: Because this monitoring function is only activated when the output current of drive 2 exceeds 10% $I_{Rated,unit}$, the incorrect wiring can cause the drive to rotate in the wrong direction or the second drive to turn in an uncontrolled manner.**
Thermal overload	**11**	**1**	**2**	The measured heat sink temperature has exceeded the permitted limit value.	• Lower the ambient temperature. • Prevent heat build-up. • Reduce the load on the drive(s).
Total utilization too high	**11**	**4**	**5**	The total drive utilization in dual-motor operation is too high.	Reduce the load on the drives.

Fault	Fault no.	Sub-error no.	Internal fault no.	Cause	Remedy
CPU fault	**20, 21, 37**	**0**	**0**		Reset the fault. If the fault occurs repeatedly, send the unit to SEW-EURODRIVE for inspection.
EEPROM fault	**25**	**0**	**4, 7**	Fault when accessing EEPROM	Use parameter *P802* to set the delivery status, perform a reset, and re-parameterize the unit. Consult SEW Service if the fault recurs.
External terminal	**26**	**0**	**0**	Low signal on the terminal that was programmed with the "/External fault" function (only with SBUS slave).	
Ixt utilization	**44**	**100**	**1**	The total current from the measured output currents of drives 1 and 2 exceeds 180% $I_{Rated,\ unit}$.	• Reduce the load on the drives. • Do not enable both drives at the same time.
Initialization fault mains recognition	**45**	**9**	**1**	Unable to recognize mains phase sequence.	Check unit's power supply connection. Is a 3-phase power supply connected correctly? Note: The mains phase sequence is detected automatically.
CAN communication timeout	**47**	**0**	**0**	Timeout with cyclical communication	
Checksum	**94**	**0**	**0**	Defective EEPROM	Contact SEW Service.
Copy error	**97**	**0**	**2, 4**	Error during data transmission	Repeat copying process, or set the delivery status and re-parameterize the unit.
Motor-related fault					
Motor overcurrent in drive 1	**1**	**3**	**3**	The measured output current of drive 1 exceeds the configured switch-off current for the duration of the delay time specified in the parameters.	• Check configuration. • Reduce the load on the drive.
Motor overcurrent in drive 2	**1**	**4**	**4**	The measured output current of drive 2 exceeds the configured switch-off current for the duration of the delay time specified in the parameters.	• Check configuration. • Reduce the load on the drive.
TF message for motor 1	**31**	**100**	**2**	Temperature sensor of drive 1 triggers.	• Make sure that the temperature sensor is connected correctly. • Reduce the load on the drive. • Lower ambient temperature. • Prevent heat build-up. • Note: You must let the drive cool down before resetting the fault.
TF message motor 2	**31**	**101**	**3**	Temperature sensor of drive 2 triggers.	• Make sure that the temperature sensor is connected correctly. • Reduce the load on the drive. • Lower ambient temperature. • Prevent heat build-up. • Note: You must let the drive cool down before resetting the fault.
"Output open" detected for drive 1.	**82**	**2**	**1**	The measured output current of drive 1 is less than 1% $I_{Rated,unit}$ when the drive is enabled.	Check the motor cable of drive 1.
"Output open" detected for drive 2	**82**	**3**	**2**	The measured output current of drive 2 is less than 1% $I_{Rated,unit}$ when the drive is enabled for "dual-motor operation".	Check the motor cable of drive 2.
Cyclical monitoring drive 1	**84**	**5**	**1**	Cyclical monitoring has triggered for drive 1.	Reduce load on drive 1, reduce starting frequency.
Cyclical monitoring drive 2.	**84**	**6**	**2**	Cyclical monitoring has triggered for drive 2.	Reduce load on drive 2, reduce starting frequency.

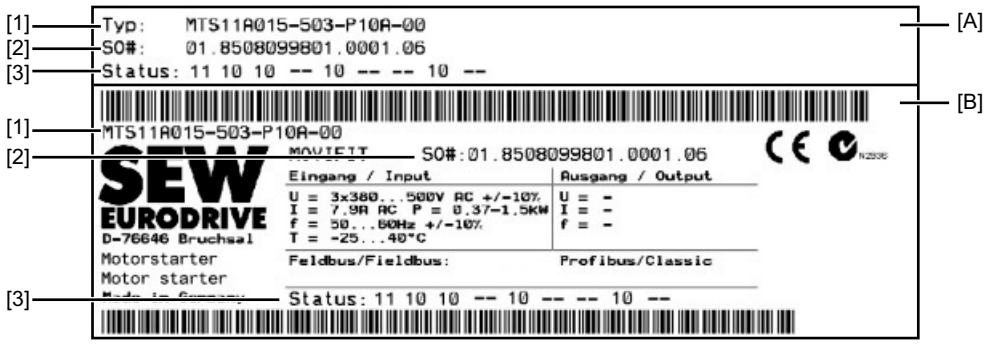
Fault	Fault no.	Sub-error no.	Internal fault no.	Cause	Remedy
UL protective functions for motor 1.	**84**	**7**	**3**	Motor 1 switches off when there is an excess of 600% $I_{Rated,unit}$ for more than 30 ms.	
			7	Motor 1 switches off when there is an excess of 400% $I_{Rated,unit}$ for more than 400 ms.	
			8	Motor 1 switches off when there is an excess of 300% $I_{Rated,unit}$ for more than 600 ms.	
UL protective functions for motor 2	**84**	**8**	**4**	Motor 2 switches off when there is an excess of 600% $I_{Rated,unit}$ for more than 30 ms.	
			8	Motor 2 switches off when there is an excess of 400% $I_{Rated,unit}$ for more than 400 ms.	
			10	Motor 2 switches off when there is an excess of 300% $I_{Rated,unit}$ for more than 600 ms.	
Motor temperature simulation motor 1	**84**	**9**	**5**	When motor 1 reaches a thermal utilization of 110%, the unit shuts down.	• Reduce the load on the drive. • Lower ambient temperature. • Prevent heat build-up. • Note: You must let the drive cool down before resetting the fault.
Motor temperature simulation motor 2	**84**	**10**	**6**	When motor 2 reaches a thermal utilization of 110%, the unit shuts down.	• Reduce the load on the drive. • Lower ambient temperature. • Prevent heat build-up. • Note: You must let the drive cool down before resetting the fault.
Cyclical monitoring for brake release without drive enable for brake 1	**89**	**2**	**1**	Cyclical monitoring has triggered for brake 1.	Reduce the starting frequency for releasing the brake without drive enable.
Cyclical monitoring for brake release without drive enable for brake 2	**89**	**3**	**2**	Cyclical monitoring has triggered for brake 2.	Reduce the starting frequency for releasing the brake without drive enable.

8.2 SEW electronics service

If a fault cannot be corrected, please consult SEW Service (see section "Address list").

When contacting SEW Service, always provide the following information:

- Unit designation [1]
- Serial number [2]
- Digits in the status field [3]
- Brief description of the application
- Nature of the fault
- Accompanying circumstances (e.g. initial startup)
- Your own presumptions as to what has happened
- Any unusual events preceding the problem, etc.



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[A] External nameplate
[B] Internal nameplate
[1] Unit designation
[2] Serial number
[3] Status field

8.3 Disposal

This product consists of:

- Iron
- Aluminum
- Copper
- Plastic
- Electronic components

Dispose of all components in accordance with applicable regulations.

9 Technical Data

9.1 CE marking, UL approval, and C-Tick

9.1.1 CE marking

- Low voltage directive:

  The MOVIFIT® drive system complies with the regulations of the low voltage directive 2006/95/EC.

- Electromagnetic compatibility (EMC):

  MOVIFIT®-SC motor starters are designed for use as components for installation in machinery and systems. They meet the following EMC product standards:

  Interference emission: EN 60947-4-2 limit class A

  Interference immunity: EN 60947-4-2

  Provided the installation instructions are complied with, the CE marking requirements for the entire machine/system in which they are installed are satisfied on the basis of the EMC directive 2004/108/EEC. For detailed information on EMC-compliant installation, refer to the publication "Electromagnetic Compatibility in Drive Engineering" from SEW-EURODRIVE.

CE

The CE mark on the nameplate indicates conformity with the low-voltage directive 2006/95/EC and the EMC directive 2004/108/EC. We can provide a declaration of conformity on request.

9.1.2 UL approval

c UL us

UL and cUL approval has been granted for the MOVIFIT® unit series.

9.1.3 C-Tick

C-Tick approval has been granted for the MOVIFIT® unit series. C-Tick certifies conformity with ACA (Australian Communications Authority) standards.

9.2 Version with operating point 400 V/50 Hz

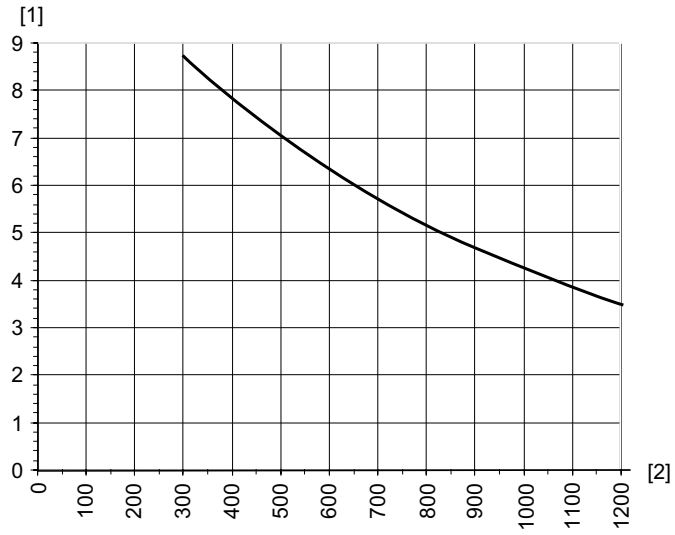
Motor starter		MTS11A015	MTS11A040
Supply voltages Permitted range	V_{Mains}	AC 3 x 380 V / **400 V** / 415 V / 460 V / 500 V V_{Mains} = AC 380 V -10% – AC 500 V +10%	
Mains frequency	f_{Mains}	50-60 Hz ± 10%	
Rated operating current (at 400 V)		I_{max} AC 4.0 A (2 x 2.5 A) I_{min} 0.5 A (2 x 0.5 A)	I_{max} AC 8.7 A (2 x 4.8 A) I_{min} 0.5 A (2 x 0.5 A)
Maximum starting frequency		See section "Maximum starting frequency" (see page 125)	
Cycle times		Typically 10 ms	
Power connection		Number of motor outputs: 2 (2 x 3 phases), not short-circuit proof Number of brake outputs: 2, not short-circuit proof **Caution: Dangerous contact voltage. The motor and brake outputs are switched using semiconductors.**	
Motor startup time		Max. 0.5 s (fast disconnection I > 180% within 1 s)	
Soft startup time		0 – **0.2** – 1 s (can be parameterized)	
Reversing time (for single-motor operation)		0.05 – **0.2** – 10 s (can be parameterized)	
Parameter setting range for motor current monitoring		0 – **150%** I_{Rated}, trigger time 0 < t < 15 s, default value: t = 2 s) Motor current is measured in phase W	
Motor protection		Thermistor	
Brake control		Integrated brake function (BGE)	
Fusing in MOVIFIT®		16 AT fuses, circuit-breaking capacity: 1.5 kA **Important: When the fuse triggers, e.g. due to a short circuit in the motor output, you must replace the EBOX. Only SEW-EURODRIVE is authorized to carry out the repair.**	
Cable length between MOVIFIT® and motor		Max. 15 m (with SEW hybrid cable, type A)	
Hybrid cable shielding		Apply outer shield with EMC cable gland; apply inner shield with EMC shield clamp, see section "Installation instructions".	
Interference immunity		Meets EN 60947-4-2	
Interference emission on mains side with EMC-compliant installation		According to class A limit as per EN 60947-4-2	
Operating mode		S1 (EN 600034-1), S3 50% For max. cycle duration, see section "Maximum starting frequency" (see page 125)	
Cooling type (DIN 41751)		Self-cooling	
Degree of protection		Standard: IP65 in accordance with EN 60529 (MOVIFIT® housing closed and all cable bushings and plug connections sealed)	
		Hygienic^{plus} version: IP66 in accordance with EN 60529 and IP69K in accordance with DIN 40050-9 (MOVIFIT® housing closed and all cable bushings sealed according to the relevant degree of protection)	
Ambient temperature		–25°C to +40°C (P_{Rated} reduction: 3% I_{Rated} per K to max. 60°C	
Climate class		EN 60721-3-3, class 3K3	
Storage temperature		–25 to +85°C (EN 60721-3-3, class 3K3)	
Permissible oscillation and impact load		According to EN 50178	
Overvoltage category		III according to IEC 60664-1 (VDE 0110-1)	
Pollution class		2 according to IEC 60664-1 (VDE 0110-1) within the housing	
Installation altitude	h	Up to 1,000 m without restrictions (installation altitude at 1000 m and higher: see section "Electrical Installation – Installation instructions")	
Mass		EBOX "MTS...-....-00" (MOVIFIT®-SC): Approx. 3.5 kg ABOX "MTA...-S02.-...-00": Approx. 4.5 kg ABOX "MTA...-S42.-...-00", "MTA...-S52.-...-00", "MTA...-S62.-...-00": Approx. 4.8 kg ABOX "MTA...-H12.-...-00", "MTA...-H22.-...-00": Approx. 6.0 kg	

9.3 Version with operating point 460 V/60 Hz

Motor starter		MTS11A015	MTS11A040
Supply voltages Permitted range	V_{Mains}	AC 3 x 380 V / 400 V / 415 V / **460 V** / 500 V V_{Mains} = AC 380 V -10% – AC 500 V +10%	
Mains frequency	f_{Mains}	50-60 Hz ± 10%	
Rated operating current (at 460 V)		I_{max} AC 4.0 A (2 x 2.5 A) I_{min} 0.5 A (2 x 0.5 A)	I_{max} AC 7.5 A (2 x 4.1 A) I_{min} 0.5 A (2 x 0.5 A)
Maximum starting frequency		See section "Maximum starting frequency" (see page 125)	
Cycle times		Typically 10 ms	
Power connection		Number of motor outputs: 2 (2 x 3 phases), not short-circuit proof Number of brake outputs: 2, not short-circuit proof **Caution: Dangerous contact voltage. The motor and brake outputs are switched using semiconductors.**	
Motor startup time		Max. 0.5 s (fast disconnection I > 180% within 1 s)	
Soft startup time		0 – **0.2** – 1 s (can be parameterized)	
Reversing time (for single-motor operation)		0.05 – **0.2** – 10 s (can be parameterized)	
Parameter setting range for motor current monitoring		0 – **150%** I_{Rated}, trigger time 0 < t < 15 s, default value: t = 2 s) Motor current is measured in phase W	
Motor protection		Thermistor	
Brake control		Integrated brake function (BGE)	
Fusing in MOVIFIT®		16 AT fuses, circuit-breaking capacity: 1.5 kA **Important: When the fuse triggers, e.g. due to a short circuit in the motor output, you must replace the EBOX. Only SEW-EURODRIVE is authorized to carry out the repair.**	
Cable length between MOVIFIT® and motor		Max. 15 m (with SEW hybrid cable, type A)	
Hybrid cable shielding		Apply outer shield with EMC cable gland; apply inner shield with EMC shield clamp, see section "Installation instructions".	
Interference immunity		Meets EN 60947-4-2	
Interference emission on mains side with EMC-compliant installation		According to class A limit as per EN 60947-4-2	
Operating mode		S1 (EN 600034-1), S3 50% For max. cycle duration, see section "Maximum starting frequency" (see page 125)	
Cooling type (DIN 41751)		Self-cooling	
Degree of protection		Standard: IP65 in accordance with EN 60529 (MOVIFIT® housing closed and all cable bushings and plug connections sealed)	
		Hygienic^{plus} version: IP66 in accordance with EN 60529 and IP69K in accordance with DIN 40050-9 (MOVIFIT® housing closed and all cable bushings sealed according to the relevant degree of protection)	
Ambient temperature		–25°C to +40°C (P_{Rated} reduction: 3% I_{Rated} per K to max. 60°C	
Climate class		EN 60721-3-3, class 3K3	
Storage temperature		–25 to +85°C (EN 60721-3-3, class 3K3)	
Permissible oscillation and impact load		According to EN 50178	
Overvoltage category		III according to IEC 60664-1 (VDE 0110-1)	
Pollution class		2 according to IEC 60664-1 (VDE 0110-1) within the housing	
Installation altitude	h	Up to 1,000 m without restrictions (installation altitude at 1000 m and higher: see section "Electrical Installation – Installation instructions")	
Mass		EBOX "MTS...-....-00" (MOVIFIT®-SC): Approx. 3.5 kg ABOX "MTA...-S02.-...-00": Approx. 4.5 kg ABOX "MTA...-S42.-...-00", "MTA...-S52.-...-00", "MTA...-S62.-...-00": Approx. 4.8 kg ABOX "MTA...-H12.-...-00", "MTA...-H22.-...-00": Approx. 6.0 kg	

9.4 Maximum starting frequency

The following figure depicts the maximum starting frequency of the MOVIFIT®-SC unit. Note also the specifications for starting frequencies for the connected motor. The maximum starting frequency only applies to the motor starter.



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[1] Current in A
[2] Switching cycles/h

9.5 General electronics data

General electronics data	
Electronics and sensor supply 24V-C (continuous)	V_{IN} = DC 24 V -15% / +20% according to EN 61131-2 I_{In} ≤ 500 mA, typically 200 mA (for MOVIFIT® electronics) plus up to 1,500 mA (3 x 500 mA) for sensor supply (depending on number and type of connected sensors) **Important: If 24V-S and 24V-P are supplied by 24V-C, the currents specified below must be added together.**
Actuator supply 24V-S (switched)	V_{IN} = DC 24 V -15% / +20% according to EN 61131-2 I_{In} ≤ 2,000 mA (4 outputs with 500 mA each or 1 x sensor supply - group 4 with 500 mA)
Electrical isolation	Separate potentials for: • Fieldbus connection (X30, X31) potential-free • SBus connection (X35/1-3) potential-free • 24V-C for MOVIFIT® electronics, diagnostic interface (X50), and digital inputs (DI..) - groups I to III • 24V-S for digital outputs (DO..) and digital inputs (DI..) – group IV
Shielding of bus cables	Apply using EMC metal cable glands or EMC shield clamps (see section "Installation instructions").

9.6 Digital inputs

Digital inputs	**Function level "Classic" with PROFIBUS or DeviceNet**	**Function level "Technology" or "System" with PROFIBUS or DeviceNet** **Function level "Classic", "Technology", or "System" with PROFINET, EtherNet/IP, or Modbus/TCP**
Number of inputs	6 – 8	12 – 16
Input type	PLC-compatible according to EN 61131-2 (digital inputs, type 1) R_i approx. 4 kΩ, sampling time ≤ 5 ms Signal level +15 V – +30 V "1" = Contact closed -3 V – +5 V "0" = Contact open	
Number of simultaneously controllable inputs	8	16 with 24 V 8 with 28.8 V
Sensor supply (4 groups) **Rated current** **Permitted total current** **Internal voltage drop**	DC 24 V according to EN 61131-2, interference voltage proof and short-circuit proof 500 mA per group 2 A / 1 A at ambient temperatures above 30 C Max. 2 V	
Potential reference	Groups I to III → 24V-C Group IV → 24V-S	

9.7 Digital outputs DO00-DO03

Digital outputs	Function level "Classic" with PROFIBUS or DeviceNet	Function level "Technology" or "System" with PROFIBUS or DeviceNet Function level "Classic", "Technology", or "System" with PROFINET, EtherNet/IP, or Modbus/TCP
Number of outputs	0 – 2	0 – 4
Output type **Rated current** **Permitted total current** **Leakage current** **Internal voltage drop**	PLC-compatible in accordance with EN 61131-2, interference voltage proof and short-circuit proof 500 mA 2 A / 1 A at ambient temperatures above 30 C Max. 0.2 mA Max. 2 V	
Potential reference	24V_S	

9.8 Digital outputs DB00-DB01

Digital outputs	
Output type **Rated current** **Leakage current** **Internal voltage drop**	PLC-compatible in accordance with EN 61131-2, interference voltage proof and short-circuit proof 150 mA Max. 0.2 mA Max. 2 V
Potential reference	24V-C

9.9 Interfaces

Interface	
SBus interface **(not with function level "Classic")** **Transmission technology** **Bus termination**	Interface to other SBus-capable SEW units CAN bus in accordance with CAN specification 2.0, parts A and B ISO 11898-compliant 120 Ω terminating resistor in conjunction with ABOX "MTA...-S02.-...-00" is already installed and can be actived via the switch. With all other ABOX versions, you must use an external terminating resistor.
RS-485 diagnostic interface	Diagnostic interface, not electrically isolated from MOVIFIT® electronics

9.9.1 PROFIBUS interface

PROFIBUS			
Function level	**Classic**	**Technology**	**System**
PROFIBUS protocol option	PROFIBUS DP/DPV1		
Supported baud rates	9.6 kBaud - 1.5 MBaud / 3-12 MBaud (with automatic detection)		
Bus termination	In conjunction with the standard ABOX "MTA...-S02.-...-00", this is already installed and can be activated via the switch. With all other ABOX versions, you must use an external terminating resistor.		
Maximum line length 9.6 kBaud: 19.2 kBaud: 93.75 kBaud: 187.5 kBaud: 500 kBaud: 1.5 MBaud: 12 MBaud:	 1,200 m 1,200 m 1,200 m 1,000 m 400 m 200 m 100 m To extend the length, several segments can be coupled using repeaters. The maximum expansion/cascading depth can be found in the manuals for the DP master or the repeater modules.		
Address setting	Addresses 1 to 125 can be set using DIP switches in the connection box.		
DP ID number	Classic $600A_{hex}$ (24586_{dec})	Technology $600B_{hex}$ (24587_{dec})	System $077A_{hex}$ (1914_{dec})
GSD file name	Classic SEW_600A.GSD	Technology SEW_600B.GSD	System SEW_077A.GSD
Bitmap file name	Classic SEW600AN.BMP SEW600AS.BMP	Technology SEW600BN.BMP SEW600BS.BMP	-

9.9.2 PROFINET interface

PROFINET		
Function level	**Classic**	**Technology**
PROFINET protocol option	PROFINET IO RT	
Supported baud rates	100 MBit/s (full duplex)	
SEW ID number	$010A_{hex}$	
Unit ID number	2	
Connection technology	M12, RJ45 (push-pull) and RJ45 plug connectors (in the ABOX)	
Integrated switch	Supports autocrossing, autonegotiation	
Permitted cable types	Category 5 and higher, class D in accordance with IEC 11801	
Maximum line length (from switch to switch)	100 m in accordance with IEEE 802.3	
GSD file name	GSDML-V2.1-SEW-MTX-yyyymmdd.xml	GSDML-V2.1-SEW-MTX-yyyymmdd.xml
Bitmap file name	SEW-MTX-Classic.bmp	SEW-MTX-Technology.bmp

9.9.3 EtherNet/IP interface

EtherNet/IP	
Function level	**Technology**
Automatic baud rate detection	10 MBaud/100 MBaud
Connection technology	M12, RJ45 (push-pull) and RJ45 plug connectors (in the ABOX)
Integrated switch	Supports autocrossing, autonegotiation
Maximum line length	100 m in accordance with IEEE 802.3
Addressing	4-byte IP address or MAC ID (00-0F-69-xx-xx-xx) Can be configured using DHCP server or MOVITOOLS® MotionStudio with version 5.5 and higher, default address 192.168.10.4 (dependent on the setting of DIP switch S11)
Manufacturer ID (vendor ID)	$013B_{hex}$
Name of EDS files	SEW_MOVIFIT_TECH_ENIP.eds
Name of icon files	SEW_MOVIFIT_TECH_ENIP.ico

9.9.4 Modbus/TCP interface

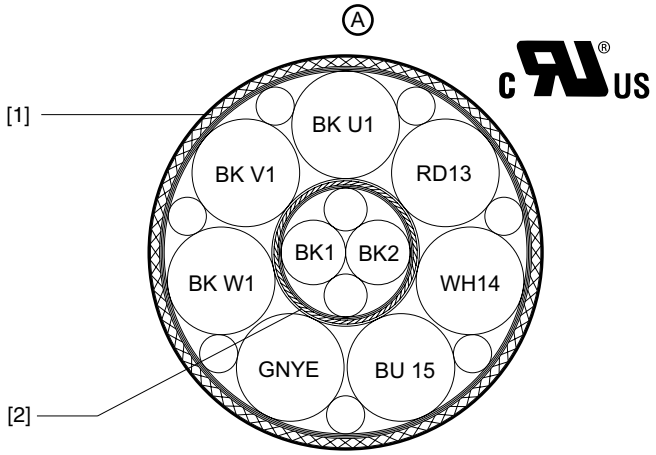
Modbus/TCP	
Function level	**Technology**
Automatic baud rate detection	10 MBaud/100 MBaud
Connection technology	M12, RJ45 (push-pull) and RJ45 plug connectors (in the ABOX)
Integrated switch	Supports autocrossing, autonegotiation
Maximum line length	100 m in accordance with IEEE 802.3
Addressing	4-byte IP address or MAC ID (00-0F-69-xx-xx-xx) Can be configured using DHCP server or MOVITOOLS® MotionStudio with version 5.5 and higher, default address 192.168.10.4 (dependent on the setting of DIP switch S11)
Manufacturer ID (vendor ID)	$013B_{hex}$
Supported services	FC3, FC16, FC23, FC43

9.9.5 DeviceNet interface

DeviceNet interface		
Function level	**Classic**	**Technology**
Protocol option	Master-slave connection set with polled I/O and bit-strobe I/O	
Supported baud rates	500 kBaud 250 kBaud 125 kBaud	
DeviceNet cable length 500 kBaud 250 kBaud 125 kBaud	See DeviceNet specification V 2.0. 100 m 250 m 500 m	
Bus termination	120 Ω (external connection)	
Process data configuration	See "MOVIFIT® Function Level Classic .." manual	See "MOVIFIT® Function Level Technology.." manual
Bit-strobe response	Checkback signal of the unit status via bit-strobe I/O data	
Address setting	DIP switch	
Name of EDS files	SEW_MOVIFIT_Classic.eds	SEW_MOVIFIT_TECH_DNET.eds
Name of icon files	SEW_MOVIFIT_Classic.ico	SEW_MOVIFIT_TECH_DNET.ico

9.10 Cable type "A" hybrid cable

9.10.1 Mechanical design



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[1] Overall shield
[2] Shield

- SEW work standard W3251 (817 953 0)
- Supply cores: 7 x 1.5 mm^2
- Control core pair: 2 x 0.75 mm^2
- Insulation: TPE-E (polyolefin)
- Conductor: Bare E-Cu strand, extra fine wires with individual wire 0.1 mm
- Shield: Tinned E-Cu wire
- Overall diameter: Max. 15.9 mm
- Color of outer cable sheath: Black

9.10.2 Electrical properties

- Conductor resistance for 1.5 mm^2 (at 20°C): Max. 13 Ω/km
- Conductor resistance for 0.75 mm^2 (at 20°C): Max. 26 Ω/km
- Operating voltage for 1.5 mm^2 core: Max. 600 V according to c UL us
- Operating voltage for 0.75 mm^2 core: Max. 600 V according to c UL us
- Insulation resistance at 20°C: Min. 20 MΩ x km

9.10.3 Mechanical properties

- Suitable for cable carriers
  - Bending cycles > 2.5 million
  - Traveling velocity ≤ 3 m/s

- Bending radius in the cable carrier: 10 x diameter
  for fixed routing: 5 x diameter

- Torsional strength (e.g. rotary table applications)
  - Torsion ±180° at a cable length of > 1 m
  - Torsional cycles > 100,000

	TIP
	If reversed bending and high torsional load occur for a length of < 3 m, check the mechanical margin conditions more closely. Please contact SEW-EURODRIVE in such cases.

9.10.4 Thermal properties

- Processing and operation: -30°C – +90°C (load capacity according to DIN VDE 0298-4)
  -30°C – +80°C according to cULus
- Transport and storage: -40°C – +90°C (load capacity according to DIN VDE 0298-4)
  -30°C – +80°C according to cULus
- Flame-retardant according to UL1581 Vertical Wiring Flame Test (VW-1)
- Flame-retardant according to CSA C22.2 Vertical Flame Test (FT-1)

9.10.5 Chemical properties

- Oil-resistant according to VDE 0472 part 803 method B
- General resistance to fuels (such as diesel and gasoline) in accordance with DIN ISO 6722 parts 1 and 2
- General resistance to acids, alkalis, cleaning agents
- General resistance to dusts (e.g. bauxite and magnesite)
- Insulation and cable jacket material is halogen free in accordance with VDE 0472 part 815
- Within the specified temperature range, free from substances interfering with wetting agents (silicon-free)

9.11 Hygienic^{plus} version

9.11.1 Properties of sealing materials and surfaces

Sealing material property

EPDM is the standard sealing material for the Hygienic^{plus} version. The following table shows a selection of various EPDM properties. Take this information into account when planning your system.

Property	EPDM stability
Alkali resistance	Very good
Resistance to ageing	Very good
Ammonia (water-free)	Very good
Ethanol	Very good
Gasoline resistance	Low
Vapor	Up to 130°C
Hot water	Very good
Lye	Very good
Carbonic acid	Very good
Methanol	Very good
Sodium chloride	Very good
Oil (vegetable, ethereal)	Good to medium
Oil and grease resistance	Low
Ozone resistance	Very good
Phosphoric acid (50%)	Very good
Nitric acid (40%)	Good
Hydrochloric acid (38%)	Very good
Acid resistance	Very good
Sulfuric acid (30%)	Very good
Silicone oils and greases	Very good
Drinking water	Very good
Suds (laundry detergent)	Very good
Sugar (watery)	Very good
Permitted temperature range	–25 to +150°C

TIP

The low rated stability of EPDM in case of contact with mineral oils, gasoline, grease, etc. results from the fact that EPDM swells when it comes into contact with these materials. However, these chemicals do not destroy EPDM.

Surface properties

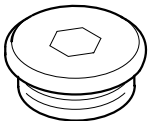
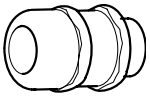
- Advanced anti-adhesive surface properties
- Surface roughness
  - R_a < 1.6 to 2
- Resistance to acidic and alkaline cleaning agents
  - Sulfuric acid (10%)
  - Caustic soda (10%)

  Never mix cleaning and disinfecting agents.

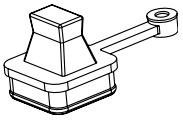
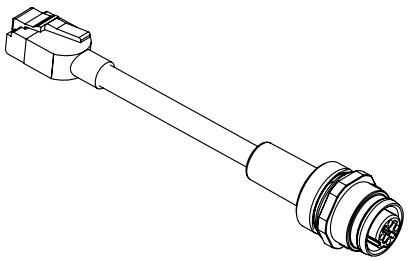
  Never mix acids and chlorine alkalis, as poisonous chlorine gas will result.

  Strictly observe the safety instructions of the cleaning agent manufacturer.
- Resistance to materials at installation location
  - Grease
  - Mineral oils
  - Edible oils
  - Gasoline
  - Alcohol
  - Solvents
- Resilient against shock and impact load
- Impact-resistant
- Resistant to temperature change
  - –25 to +60°C
  - Increased temperature for cleaning processes: 80°C
- Water-jet-resistant
  - Approx. 100 l/min
- Steam cleaning (according to DIN 40050 part 9)
  - Max. 80-100 bar (approx. 15 l/min)
  - Max. 80°C (30 seconds)
- Light-resistant
  - Direct sunlight

9.11.2 Optional metal cable glands and protective caps

Type	Figure	Contents	Size	Part number
Stainless steel screw plugs		10 pieces	M16 x 1.5	1820 223 3
		10 pieces	M20 x 1.5	1820 224 1
		10 pieces	M25 x 1.5	1820 226 8
EMC cable gland (brass, nickel plated)		10 pieces	M16 x 1.5	1820 478 3
		10 pieces	M20 x 1.5	1820 479 1
		10 pieces	M25 x 1.5	1820 480 5

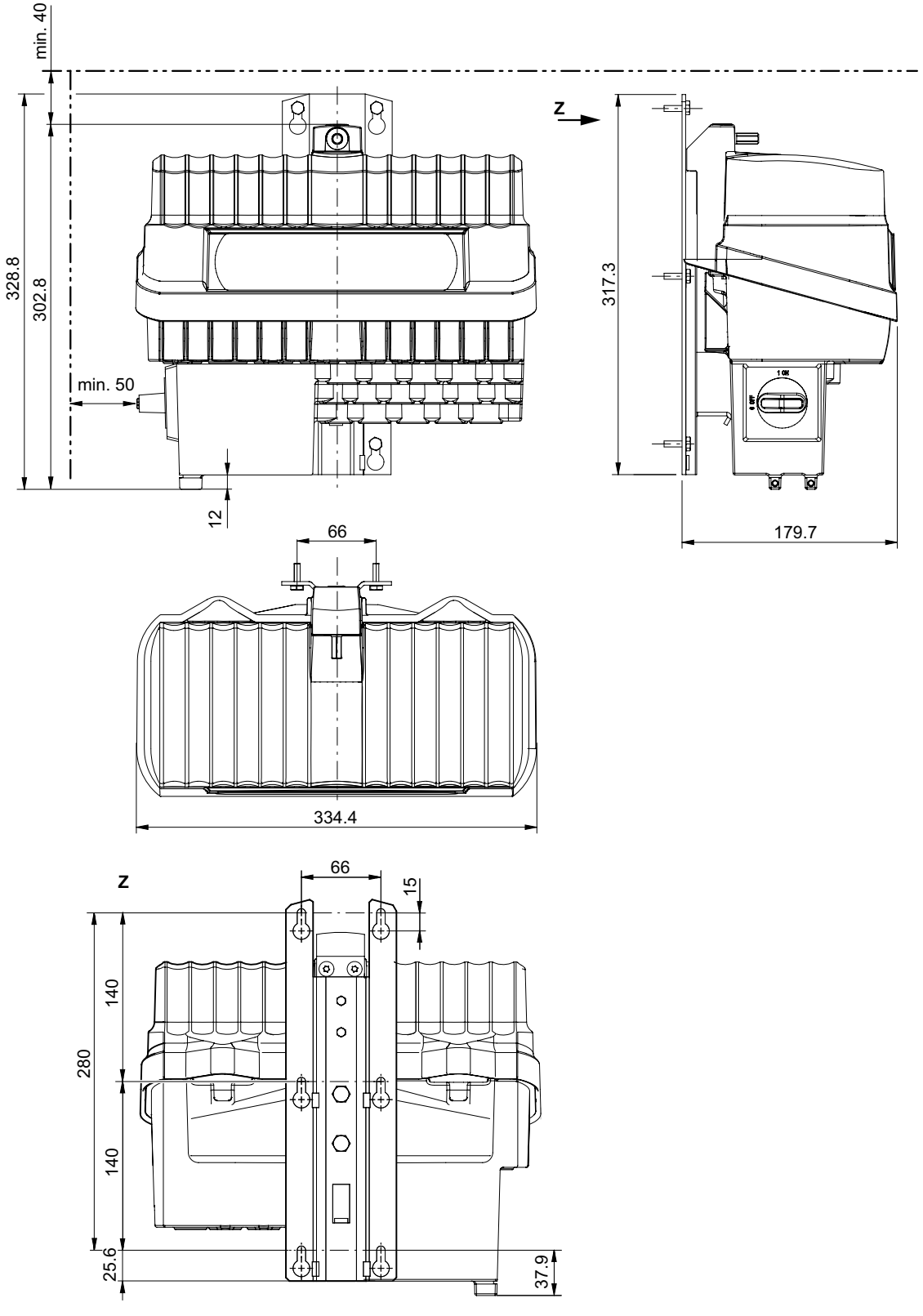
9.12 Options

Type	Figure	Contents	Part number
Ethernet closing plug for push-pull RJ45 socket		10 pieces	1822 370 2
		30 pieces	1822 371 0
Ethernet adapter RJ45-M12 RJ45 (internal) M12 (external) For each unit, two pieces are required.		1 piece	1328 168 2

9.13 Dimension drawings

9.13.1 Dimension drawing in conjunction with standard or hybrid ABOX (S02, S42, S52, S62)

MOVIFIT®-SC with standard mounting rail



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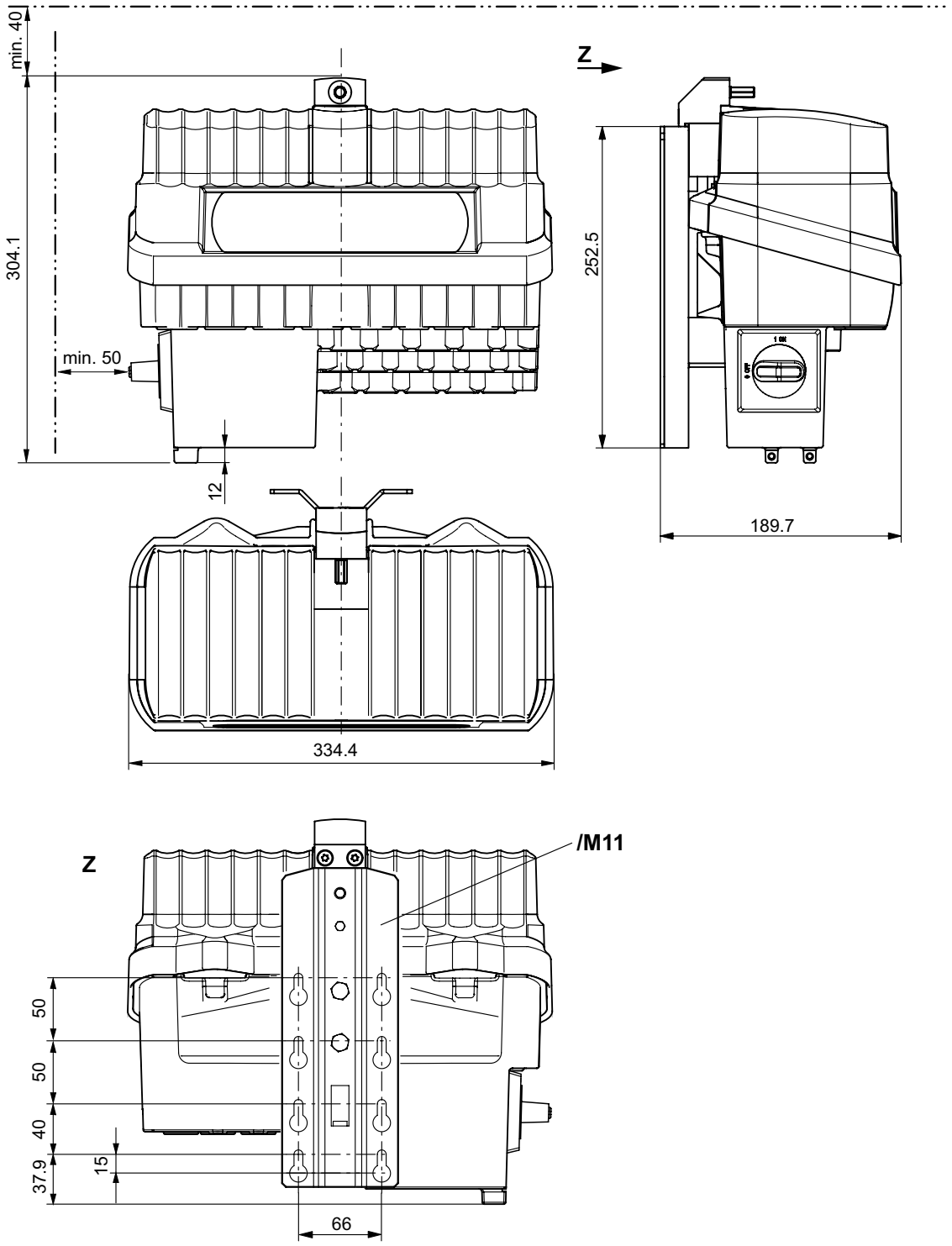
MOVIFIT®-SC with optional M11 stainless steel mounting rail



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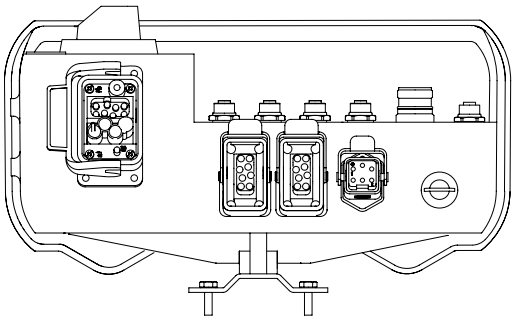
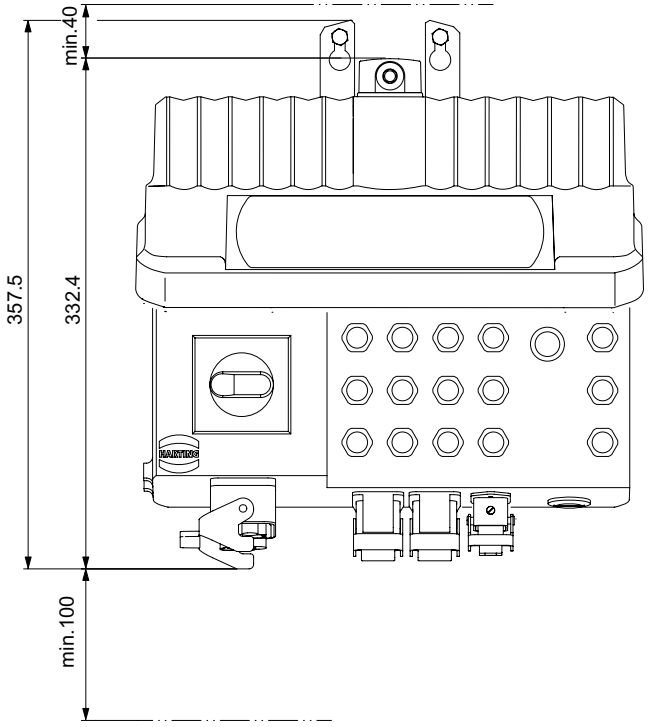
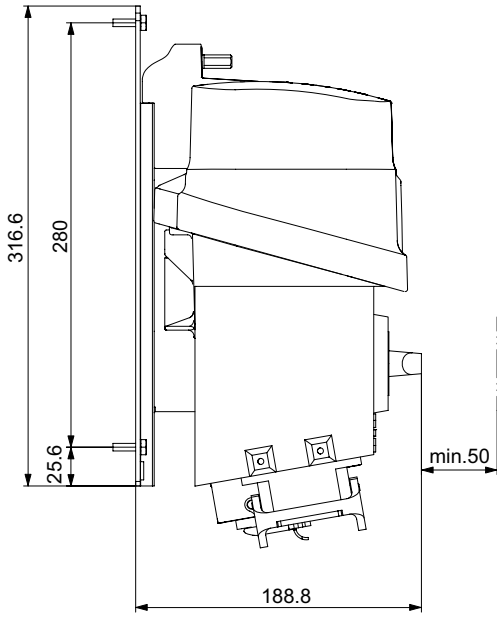
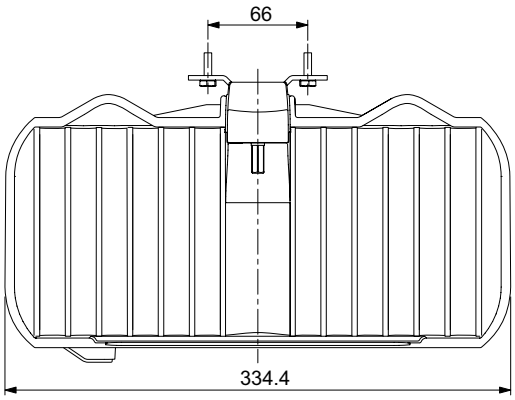
9.13.2 Dimension drawing in conjunction with Han-Modular®-ABOX (H12 and H22)









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10 Address List

Germany			
Headquarters **Production** **Sales**	**Bruchsal**	SEW-EURODRIVE GmbH & Co KG Ernst-Blickle-Straße 42 D-76646 Bruchsal P.O. Box Postfach 3023 • D-76642 Bruchsal	Tel. +49 7251 75-0 Fax +49 7251 75-1970 http://www.sew-eurodrive.de sew@sew-eurodrive.de
Service **Competence** **Center**	**Central**	SEW-EURODRIVE GmbH & Co KG Ernst-Blickle-Straße 1 D-76676 Graben-Neudorf	Tel. +49 7251 75-1710 Fax +49 7251 75-1711 sc-mitte@sew-eurodrive.de
	North	SEW-EURODRIVE GmbH & Co KG Alte Ricklinger Straße 40-42 D-30823 Garbsen (near Hannover)	Tel. +49 5137 8798-30 Fax +49 5137 8798-55 sc-nord@sew-eurodrive.de
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	South	SEW-EURODRIVE GmbH & Co KG Domagkstraße 5 D-85551 Kirchheim (near München)	Tel. +49 89 909552-10 Fax +49 89 909552-50 sc-sued@sew-eurodrive.de
	West	SEW-EURODRIVE GmbH & Co KG Siemensstraße 1 D-40764 Langenfeld (near Düsseldorf)	Tel. +49 2173 8507-30 Fax +49 2173 8507-55 sc-west@sew-eurodrive.de
	Electronics	SEW-EURODRIVE GmbH & Co KG Ernst-Blickle-Straße 42 D-76646 Bruchsal	Tel. +49 7251 75-1780 Fax +49 7251 75-1769 sc-elektronik@sew-eurodrive.de
	Drive Service Hotline / 24 Hour Service		+49 180 5 SEWHELP +49 180 5 7394357
	Additional addresses for service in Germany provided on request!		

France			
Production **Sales** **Service**	**Haguenau**	SEW-USOCOME 48-54, route de Soufflenheim B. P. 20185 F-67506 Haguenau Cedex	Tel. +33 3 88 73 67 00 Fax +33 3 88 73 66 00 http://www.usocome.com sew@usocome.com
Production	**Forbach**	SEW-EUROCOME Zone Industrielle Technopôle Forbach Sud B. P. 30269 F-57604 Forbach Cedex	Tel. +33 3 87 29 38 00
Assembly **Sales** **Service**	**Bordeaux**	SEW-USOCOME Parc d'activités de Magellan 62, avenue de Magellan - B. P. 182 F-33607 Pessac Cedex	Tel. +33 5 57 26 39 00 Fax +33 5 57 26 39 09
	Lyon	SEW-USOCOME Parc d'Affaires Roosevelt Rue Jacques Tati F-69120 Vaulx en Velin	Tel. +33 4 72 15 37 00 Fax +33 4 72 15 37 15
	Paris	SEW-USOCOME Zone industrielle 2, rue Denis Papin F-77390 Verneuil l'Etang	Tel. +33 1 64 42 40 80 Fax +33 1 64 42 40 88
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Argentina			
Assembly **Sales** **Service**	**Buenos Aires**	SEW EURODRIVE ARGENTINA S.A. Centro Industrial Garin, Lote 35 Ruta Panamericana Km 37,5 1619 Garin	Tel. +54 3327 4572-84 Fax +54 3327 4572-21 sewar@sew-eurodrive.com.ar http://www.sew-eurodrive.com.ar

Australia			
Assembly **Sales** **Service**	**Melbourne**	SEW-EURODRIVE PTY. LTD. 27 Beverage Drive Tullamarine, Victoria 3043	Tel. +61 3 9933-1000 Fax +61 3 9933-1003 http://www.sew-eurodrive.com.au enquires@sew-eurodrive.com.au
	Sydney	SEW-EURODRIVE PTY. LTD. 9, Sleigh Place, Wetherill Park New South Wales, 2164	Tel. +61 2 9725-9900 Fax +61 2 9725-9905 enquires@sew-eurodrive.com.au

Austria			
Assembly **Sales** **Service**	**Wien**	SEW-EURODRIVE Ges.m.b.H. Richard-Strauss-Strasse 24 A-1230 Wien	Tel. +43 1 617 55 00-0 Fax +43 1 617 55 00-30 http://sew-eurodrive.at sew@sew-eurodrive.at

Belarus			
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Belgium			
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Service Competence Center	**Industrial Gears**	SEW Caron-Vector S.A. Rue de Parc Industriel, 31 BE-6900 Marche-en-Famenne	Tel. +32 84 219-878 Fax +32 84 219-879 http://www.sew-eurodrive.be service-wallonie@sew-eurodrive.be

Brazil			
Production **Sales** **Service**	**Sao Paulo**	SEW-EURODRIVE Brasil Ltda. Avenida Amâncio Gaiolli, 152 - Rodovia Presidente Dutra Km 208 Guarulhos - 07251-250 - SP SAT - SEW ATENDE - 0800 7700496	Tel. +55 11 6489-9133 Fax +55 11 6480-3328 http://www.sew-eurodrive.com.br sew@sew.com.br
	Additional addresses for service in Brazil provided on request!		

Bulgaria			
Sales	**Sofia**	BEVER-DRIVE GmbH Bogdanovetz Str.1 BG-1606 Sofia	Tel. +359 2 9151160 Fax +359 2 9151166 bever@fastbg.net

Cameroon			
Sales	**Douala**	Electro-Services Rue Drouot Akwa B.P. 2024 Douala	Tel. +237 33 431137 Fax +237 33 431137

Canada			
Assembly **Sales** **Service**	**Toronto**	SEW-EURODRIVE CO. OF CANADA LTD. 210 Walker Drive Bramalea, Ontario L6T3W1	Tel. +1 905 791-1553 Fax +1 905 791-2999 http://www.sew-eurodrive.ca marketing@sew-eurodrive.ca
	Vancouver	SEW-EURODRIVE CO. OF CANADA LTD. 7188 Honeyman Street Delta. B.C. V4G 1 E2	Tel. +1 604 946-5535 Fax +1 604 946-2513 marketing@sew-eurodrive.ca
	Montreal	SEW-EURODRIVE CO. OF CANADA LTD. 2555 Rue Leger LaSalle, Quebec H8N 2V9	Tel. +1 514 367-1124 Fax +1 514 367-3677 marketing@sew-eurodrive.ca
	Additional addresses for service in Canada provided on request!		

Chile			
Assembly **Sales** **Service**	**Santiago de Chile**	SEW-EURODRIVE CHILE LTDA. Las Encinas 1295 Parque Industrial Valle Grande LAMPA RCH-Santiago de Chile P.O. Box Casilla 23 Correo Quilicura - Santiago - Chile	Tel. +56 2 75770-00 Fax +56 2 75770-01 http://www.sew-eurodrive.cl ventas@sew-eurodrive.cl

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	Guangzhou	SEW-EURODRIVE (Guangzhou) Co., Ltd. No. 9, JunDa Road East Section of GETDD Guangzhou 510530	Tel. +86 20 82267890 Fax +86 20 82267891 guangzhou@sew-eurodrive.cn
	Shenyang	SEW-EURODRIVE (Shenyang) Co., Ltd. 10A-2, 6th Road Shenyang Economic Technological Development Area Shenyang, 110141	Tel. +86 24 25382538 Fax +86 24 25382580 shenyang@sew-eurodrive.cn
	Wuhan	SEW-EURODRIVE (Wuhan) Co., Ltd. 10A-2, 6th Road No. 59, the 4th Quanli Road, WEDA 430056 Wuhan	Tel. +86 27 84478398 Fax +86 27 84478388
	Additional addresses for service in China provided on request!		

Colombia			
Assembly **Sales** **Service**	**Bogotá**	SEW-EURODRIVE COLOMBIA LTDA. Calle 22 No. 132-60 Bodega 6, Manzana B Santafé de Bogotá	Tel. +57 1 54750-50 Fax +57 1 54750-44 http://www.sew-eurodrive.com.co sewcol@sew-eurodrive.com.co

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Assembly **Sales** **Service**	**Kopenhagen**	SEW-EURODRIVEA/S Geminivej 28-30 DK-2670 Greve	Tel. +45 43 9585-00 Fax +45 43 9585-09 http://www.sew-eurodrive.dk sew@sew-eurodrive.dk

Egypt			
Sales **Service**	**Cairo**	Copam Egypt for Engineering & Agencies 33 El Hegaz ST, Heliopolis, Cairo	Tel. +20 2 22566-299 + 1 23143088 Fax +20 2 22594-757 http://www.copam-egypt.com/ copam@datum.com.eg

Estonia			
Sales	**Tallin**	ALAS-KUUL AS Reti tee 4 EE-75301 Peetri küla, Rae vald, Harjumaa	Tel. +372 6593230 Fax +372 6593231 veiko.soots@alas-kuul.ee

Finland			
Assembly **Sales** **Service**	**Lahti**	SEW-EURODRIVE OY Vesimäentie 4 FIN-15860 Hollola 2	Tel. +358 201 589-300 Fax +358 3 780-6211 sew@sew.fi http://www.sew-eurodrive.fi
Production **Assembly** **Service**	**Karkkila**	SEW Industrial Gears OY Valurinkatu 6 FIN-03600 Karkkila	Tel. +358 201 589-300 Fax +358 201 589-310 sew@sew.fi http://www.sew-eurodrive.fi

Gabon			
Sales	**Libreville**	Electro-Services B.P. 1889 Libreville	Tel. +241 7340-11 Fax +241 7340-12

Great Britain			
Assembly **Sales** **Service**	**Normanton**	SEW-EURODRIVE Ltd. Beckbridge Industrial Estate P.O. Box No.1 GB-Normanton, West- Yorkshire WF6 1QR	Tel. +44 1924 893-855 Fax +44 1924 893-702 http://www.sew-eurodrive.co.uk info@sew-eurodrive.co.uk

Greece			
Sales **Service**	**Athen**	Christ. Boznos & Son S.A. 12, Mavromichali Street P.O. Box 80136, GR-18545 Piraeus	Tel. +30 2 1042 251-34 Fax +30 2 1042 251-59 http://www.boznos.gr info@boznos.gr

Hong Kong			
Assembly **Sales** **Service**	**Hong Kong**	SEW-EURODRIVE LTD. Unit No. 801-806, 8th Floor Hong Leong Industrial Complex No. 4, Wang Kwong Road Kowloon, Hong Kong	Tel. +852 2 7960477 + 79604654 Fax +852 2 7959129 contact@sew-eurodrive.hk

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Sales **Service**	**Budapest**	SEW-EURODRIVE Kft. H-1037 Budapest Kunigunda u. 18	Tel. +36 1 437 06-58 Fax +36 1 437 06-50 office@sew-eurodrive.hu

India			
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Ireland			
Sales **Service**	**Dublin**	Alperton Engineering Ltd. 48 Moyle Road Dublin Industrial Estate Glasnevin, Dublin 11	Tel. +353 1 830-6277 Fax +353 1 830-6458 info@alperton.ie http://www.alperton.ie

Israel			
Sales	**Tel-Aviv**	Liraz Handasa Ltd. Ahofer Str 34B / 228 58858 Holon	Tel. +972 3 5599511 Fax +972 3 5599512 http://www.liraz-handasa.co.il office@liraz-handasa.co.il

Italy			
Assembly **Sales** **Service**	**Milano**	SEW-EURODRIVE di R. Blickle & Co.s.a.s. Via Bernini,14 I-20020 Solaro (Milano)	Tel. +39 02 96 9801 Fax +39 02 96 799781 http://www.sew-eurodrive.it sewit@sew-eurodrive.it

Ivory Coast			
Sales	**Abidjan**	SICA Ste industrielle et commerciale pour l'Afrique 165, Bld de Marseille B.P. 2323, Abidjan 08	Tel. +225 2579-44 Fax +225 2584-36

Japan			
Assembly **Sales** **Service**	**Iwata**	SEW-EURODRIVE JAPAN CO., LTD 250-1, Shimoman-no, Iwata Shizuoka 438-0818	Tel. +81 538 373811 Fax +81 538 373814 http://www.sew-eurodrive.co.jp sewjapan@sew-eurodrive.co.jp

Korea			
Assembly **Sales** **Service**	**Ansan-City**	SEW-EURODRIVE KOREA CO., LTD. B 601-4, Banweol Industrial Estate 1048-4, Shingil-Dong Ansan 425-120	Tel. +82 31 492-8051 Fax +82 31 492-8056 http://www.sew-korea.co.kr master@sew-korea.co.kr
	Busan	SEW-EURODRIVE KOREA Co., Ltd. No. 1720 - 11, Songjeong - dong Gangseo-ku Busan 618-270	Tel. +82 51 832-0204 Fax +82 51 832-0230 master@sew-korea.co.kr

Latvia			
Sales	**Riga**	SIA Alas-Kuul Katlakalna 11C LV-1073 Riga	Tel. +371 7139253 Fax +371 7139386 http://www.alas-kuul.com info@alas-kuul.com

Lebanon			
Sales	**Beirut**	Gabriel Acar & Fils sarl B. P. 80484 Bourj Hammoud, Beirut	Tel. +961 1 4947-86 +961 1 4982-72 +961 3 2745-39 Fax +961 1 4949-71 gacar@beirut.com

Lithuania			
Sales	**Alytus**	UAB Irseva Naujoji 19 LT-62175 Alytus	Tel. +370 315 79204 Fax +370 315 56175 info@irseva.lt http://www.sew-eurodrive.lt

Luxembourg			
Assembly **Sales** **Service**	**Brüssel**	CARON-VECTOR S.A. Avenue Eiffel 5 B-1300 Wavre	Tel. +32 10 231-311 Fax +32 10 231-336 http://www.sew-eurodrive.lu info@caron-vector.be

Malaysia			
Assembly **Sales** **Service**	**Johore**	SEW-EURODRIVE SDN BHD No. 95, Jalan Seroja 39, Taman Johor Jaya 81000 Johor Bahru, Johor West Malaysia	Tel. +60 7 3549409 Fax +60 7 3541404 sales@sew-eurodrive.com.my

Mexico			
Assembly **Sales** **Service**	**Queretaro**	SEW-EURODRIVE MEXIKO SA DE CV SEM-981118-M93 Tequisquiapan No. 102 Parque Industrial Queretaro C.P. 76220 Queretaro, Mexico	Tel. +52 442 1030-300 Fax +52 442 1030-301 http://www.sew-eurodrive.com.mx scmexico@seweurodrive.com.mx

Morocco			
Sales	**Casablanca**	Afit 5, rue Emir Abdelkader MA 20300 Casablanca	Tel. +212 22618372 Fax +212 22618351 ali.alami@premium.net.ma

Netherlands			
Assembly **Sales** **Service**	**Rotterdam**	VECTOR Aandrijftechniek B.V. Industrieweg 175 NL-3044 AS Rotterdam Postbus 10085 NL-3004 AB Rotterdam	Tel. +31 10 4463-700 Fax +31 10 4155-552 http://www.vector.nu info@vector.nu

New Zealand			
Assembly **Sales** **Service**	**Auckland**	SEW-EURODRIVE NEW ZEALAND LTD. P.O. Box 58-428 82 Greenmount drive East Tamaki Auckland	Tel. +64 9 2745627 Fax +64 9 2740165 http://www.sew-eurodrive.co.nz sales@sew-eurodrive.co.nz
	Christchurch	SEW-EURODRIVE NEW ZEALAND LTD. 10 Settlers Crescent, Ferrymead Christchurch	Tel. +64 3 384-6251 Fax +64 3 384-6455 sales@sew-eurodrive.co.nz

Norway			
Assembly **Sales** **Service**	**Moss**	SEW-EURODRIVE A/S Solgaard skog 71 N-1599 Moss	Tel. +47 69 24 10 20 Fax +47 69 24 10 40 http://www.sew-eurodrive.no sew@sew-eurodrive.no

Peru			
Assembly **Sales** **Service**	**Lima**	SEW DEL PERU MOTORES REDUCTORES S.A.C. Los Calderos, 120-124 Urbanizacion Industrial Vulcano, ATE, Lima	Tel. +51 1 3495280 Fax +51 1 3493002 http://www.sew-eurodrive.com.pe sewperu@sew-eurodrive.com.pe

Poland			
Assembly **Sales** **Service**	**Lodz**	SEW-EURODRIVE Polska Sp.z.o.o. ul. Techniczna 5 PL-92-518 Łódź	Tel. +48 42 67710-90 Fax +48 42 67710-99 http://www.sew-eurodrive.pl sew@sew-eurodrive.pl
	24 Hour Service		Tel. +48 602 739 739 (+48 602 SEW SEW) sewis@sew-eurodrive.pl

Portugal			
Assembly **Sales** **Service**	**Coimbra**	SEW-EURODRIVE, LDA. Apartado 15 P-3050-901 Mealhada	Tel. +351 231 20 9670 Fax +351 231 20 3685 http://www.sew-eurodrive.pt infosew@sew-eurodrive.pt

Romania			
Sales **Service**	**Bucureşti**	Sialco Trading SRL str. Madrid nr.4 011785 Bucuresti	Tel. +40 21 230-1328 Fax +40 21 230-7170 sialco@sialco.ro

Russia			
Assembly **Sales** **Service**	**St. Petersburg**	ZAO SEW-EURODRIVE P.O. Box 36 195220 St. Petersburg Russia	Tel. +7 812 3332522 +7 812 5357142 Fax +7 812 3332523 http://www.sew-eurodrive.ru sew@sew-eurodrive.ru

Senegal			
Sales	**Dakar**	SENEMECA Mécanique Générale Km 8, Route de Rufisque B.P. 3251, Dakar	Tel. +221 338 494 770 Fax +221 338 494 771 senemeca@sentoo.sn

Serbia			
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Singapore			
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Slovenia			
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Spain			
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Sweden			
Assembly **Sales** **Service**	**Jönköping**	SEW-EURODRIVE AB Gnejsvägen 6-8 S-55303 Jönköping Box 3100 S-55003 Jönköping	Tel. +46 36 3442 00 Fax +46 36 3442 80 http://www.sew-eurodrive.se info@sew-eurodrive.se

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Thailand			
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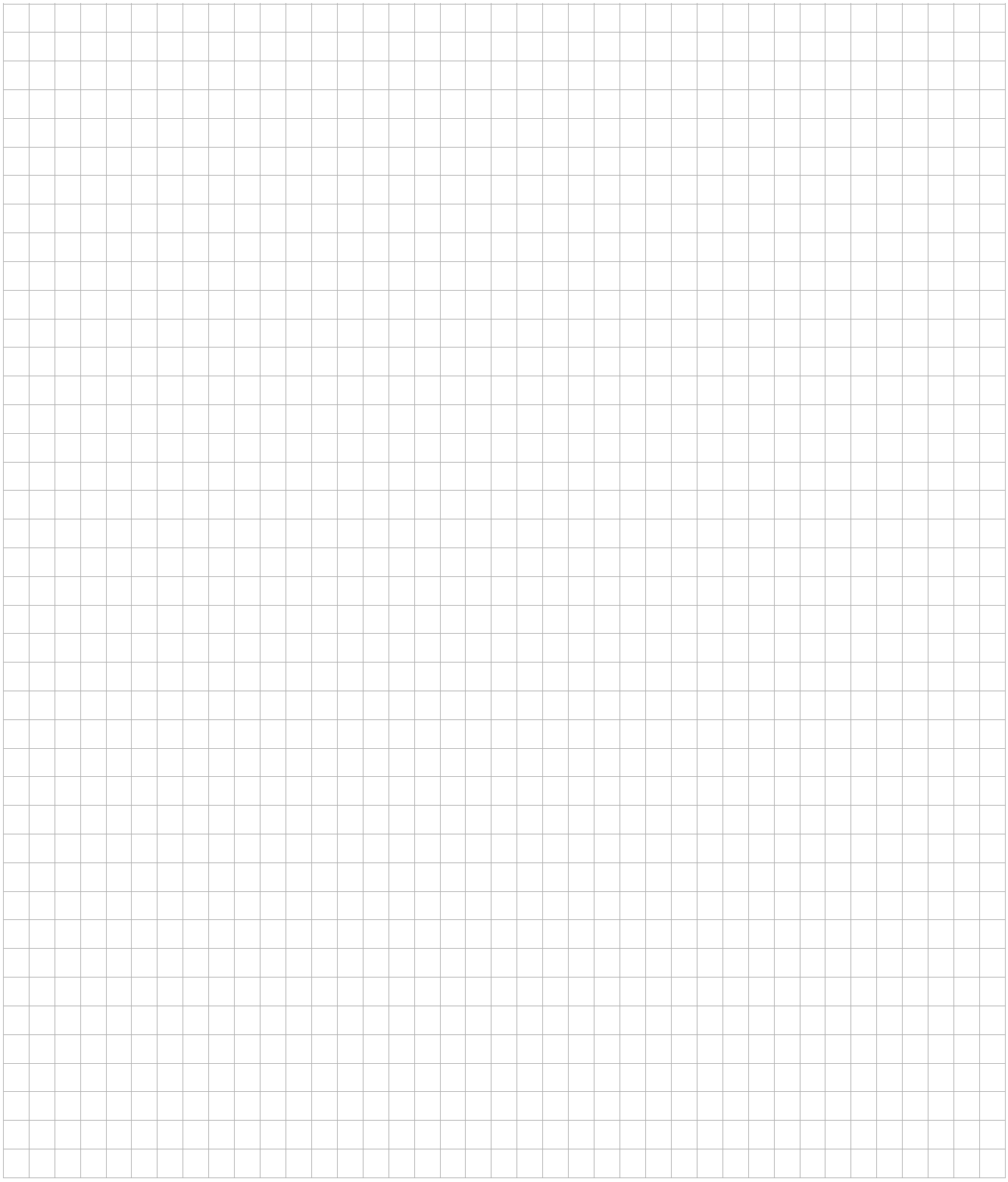

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